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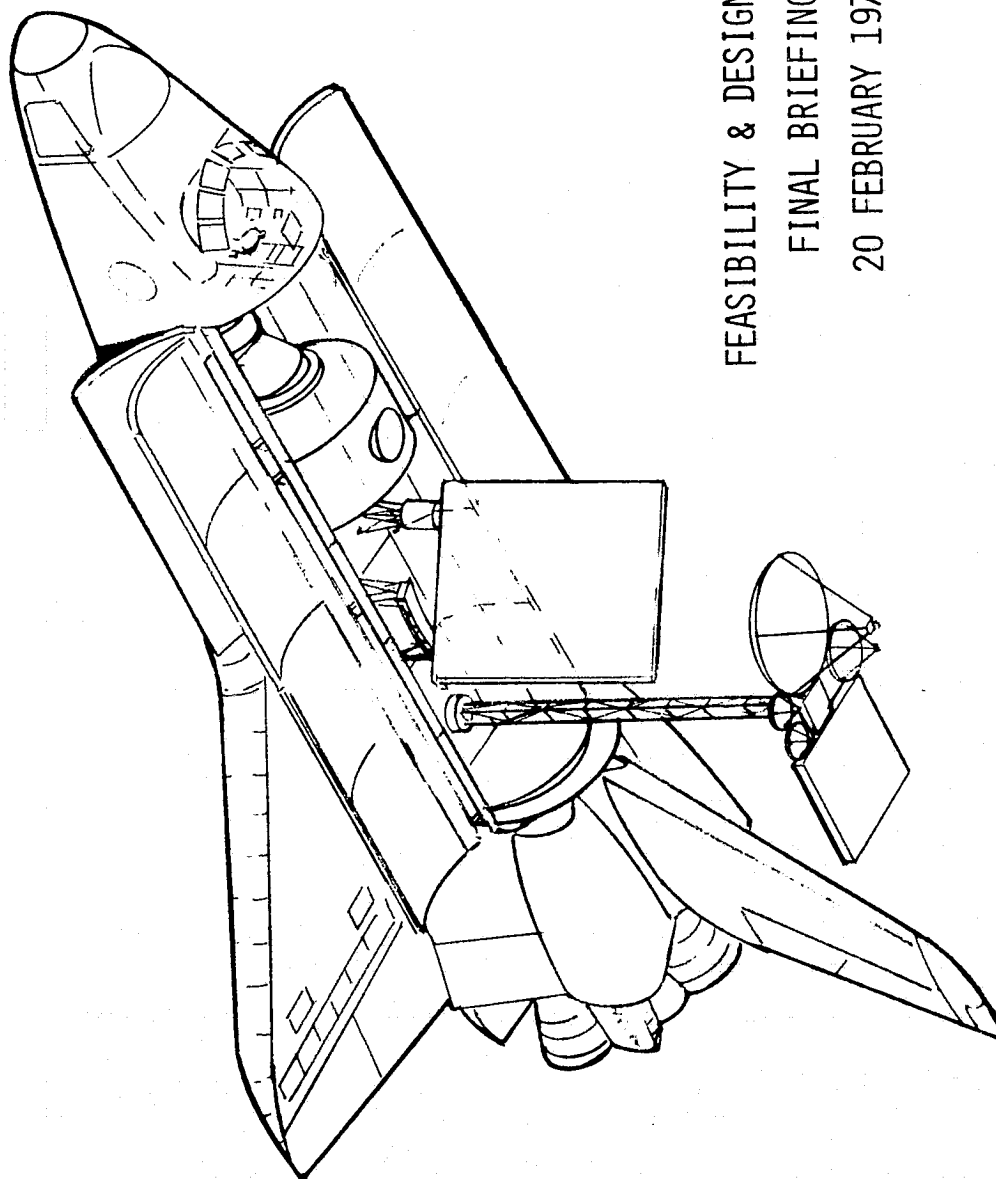
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NASA CR-152588

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METEOROLOGICAL RADAR FACILITY



FEASIBILITY & DESIGN STUDY

FINAL BRIEFING

20 FEBRUARY 1976

(NASA-CR-152588) METEOROLOGICAL RADAR
FACILITY. PART 1: SYSTEM DESIGN Final
Report (Hughes Aircraft Co.) 140 p HC
A07/MF A01

CSCL 17I

N77-32219

Unclas
G3/16 49295
INPUT BRANCH

FINAL REPORT OF MRF STUDY

PART I SYSTEM DESIGN

Contract No. NAS5-22468

February 1976

HUGHES PERSONNEL



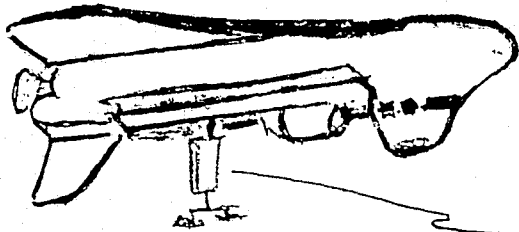
LLOYD L. BRASSAW JR.

SWEGN D. HAMREN

WILLIAM H. MULLINS

BERNARD P. SCHWEITZER

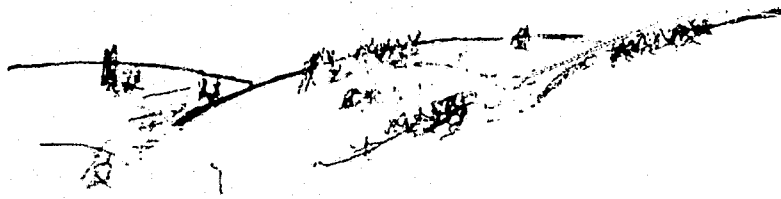
METEOROLOGICAL RADAR
CYCLE



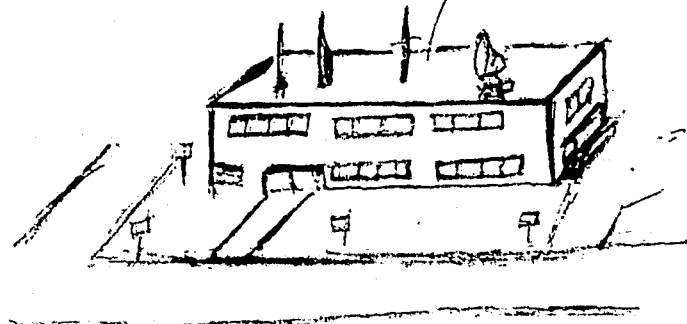
RADAR SENSOR

COMMUNICATION LINK

GROUND PROCESSING
STATION



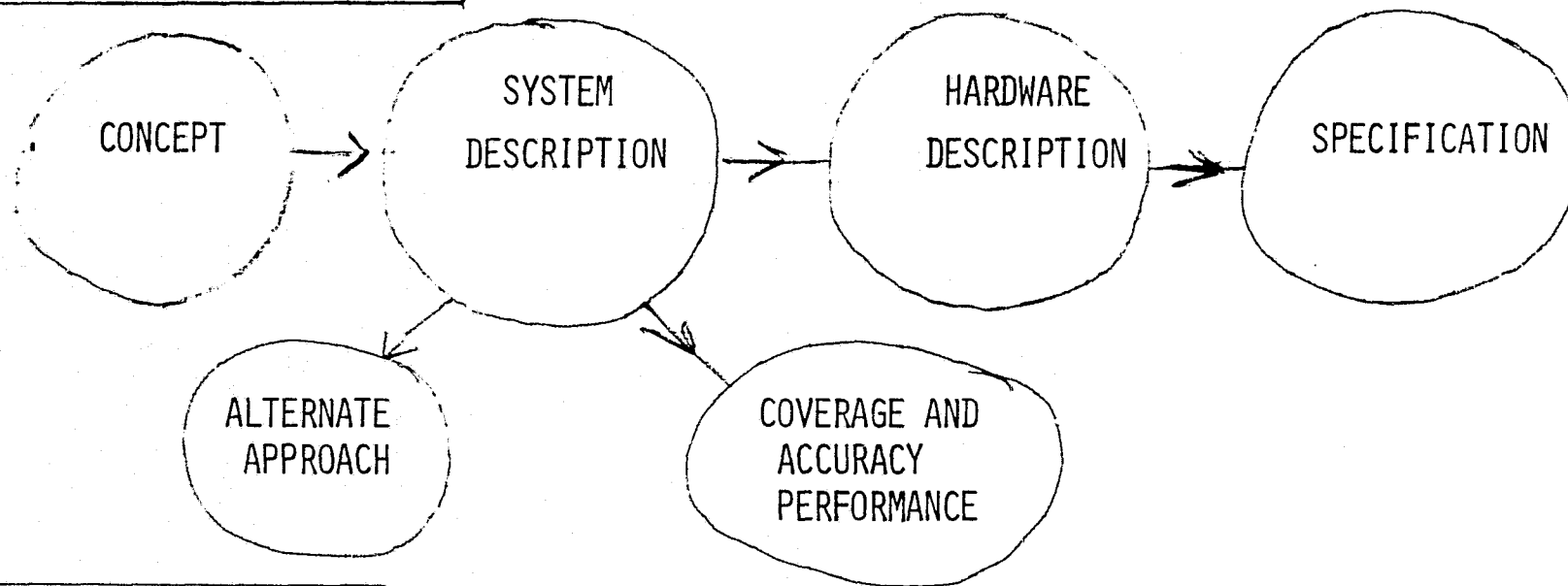
SHUTTLE LANDING FIELD



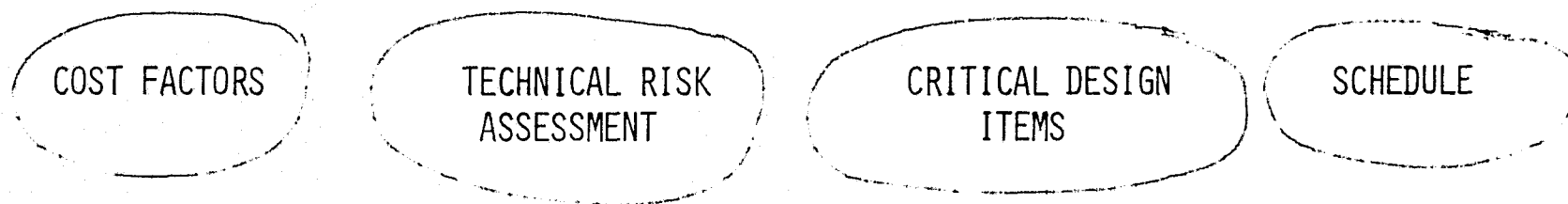
IRF TOPICS



DESIGN AND SPECIFICATIONS



PLANNING & RESOURCES



BRIEFING OUTLINE - MORNING

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- | | | | |
|----|-------------------------------|-------|--------------------|
| 1. | INTRODUCTION | 9:15 | L. BRASSAW |
| 2. | OVERVIEW | 9:30 | B. SCHWEITZER |
| 3. | WEIGHT/POWER/VOLUME ESTIMATES | 10:30 | W. MULLINS |
| | BREAK | 10:45 | |
| 4. | CRITICAL DESIGN AREAS | 11:00 | MULLINS/HAMREN |
| 5. | SYSTEM DESCRIPTION | 11:20 | SCHWEITZER/MULLINS |
| 6. | MAJOR SYSTEM DESIGN DECISIONS | 11:40 | SCHWEITZER/MULLINS |
| | LUNCH | | |

BRIEFING OUTLINE - AFTERNOON

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7. SYSTEM PERFORMANCE	1:30	W. MULLINS
8. SUBSYSTEM DESCRIPTION	2:00	B. SCHWEITZER
o ANTENNA	2:10	S. HAMREN
o TRANSMITTER/RECEIVERS	2:40	W. MULLINS
o PRE-PROCESSOR & RECORDER	2:55	W. MULLINS
9. SYSTEM SPECIFICATIONS	3:10	W. MULLINS
10. SUMMARY	3:30	L. BRASSAW
BREAK	3:45	

OVERVIEW I



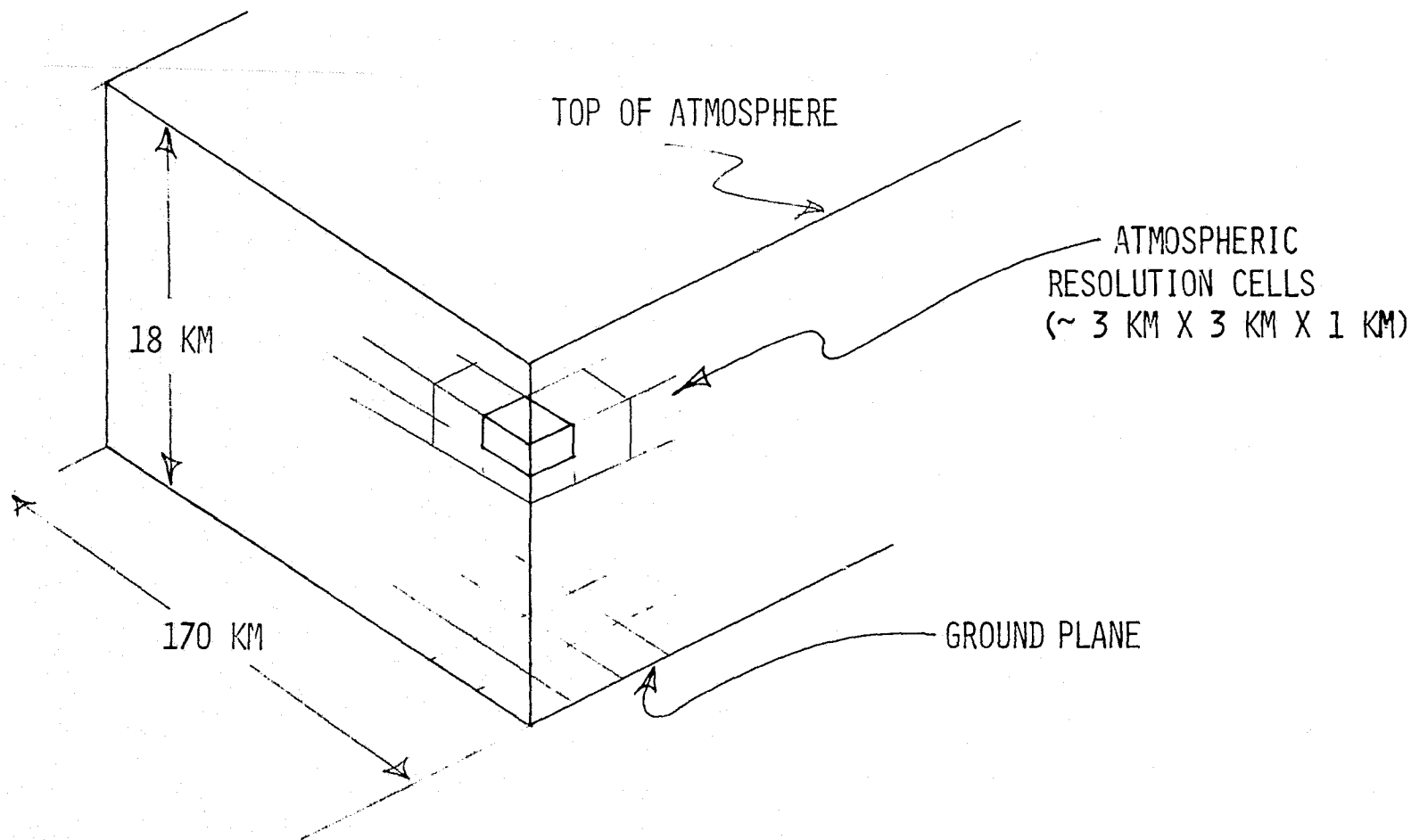
- o SUMMARY OF MRF FUNCTIONS
- o SCHEDULE
- o BISTATIC ANTENNA APPROACH
- o SPATIAL GEOMETRY
- o ACCURACY
- o INSTALLATION
- o COST
- o RISK ASSESSMENT

SUMMARY OF MRF FUNCTIONS



- o THREE-DIMENSIONAL PRECIPITATION MEASUREMENTS
- o GROUND MAP

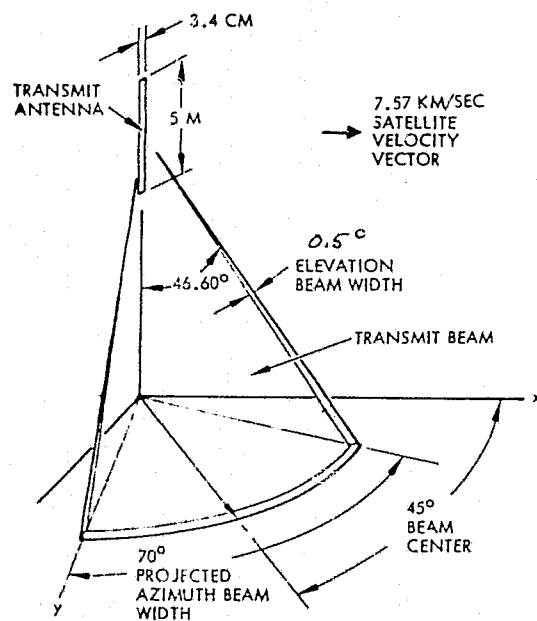
MRF THREE DIMENSIONAL PRECIPITATION DATA



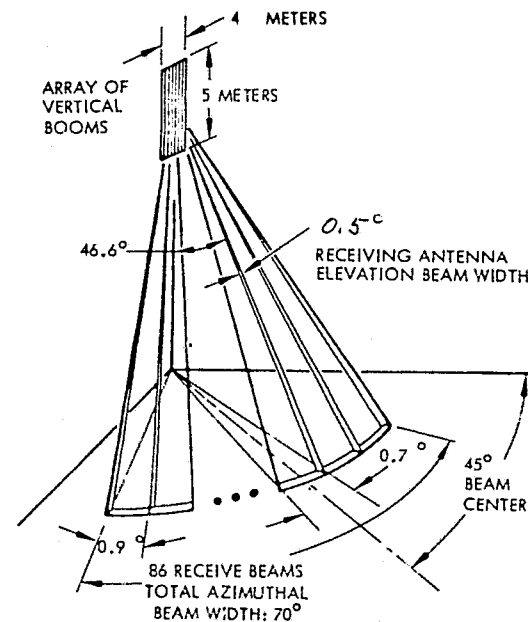
BISTATIC ANTENNA APPROACH

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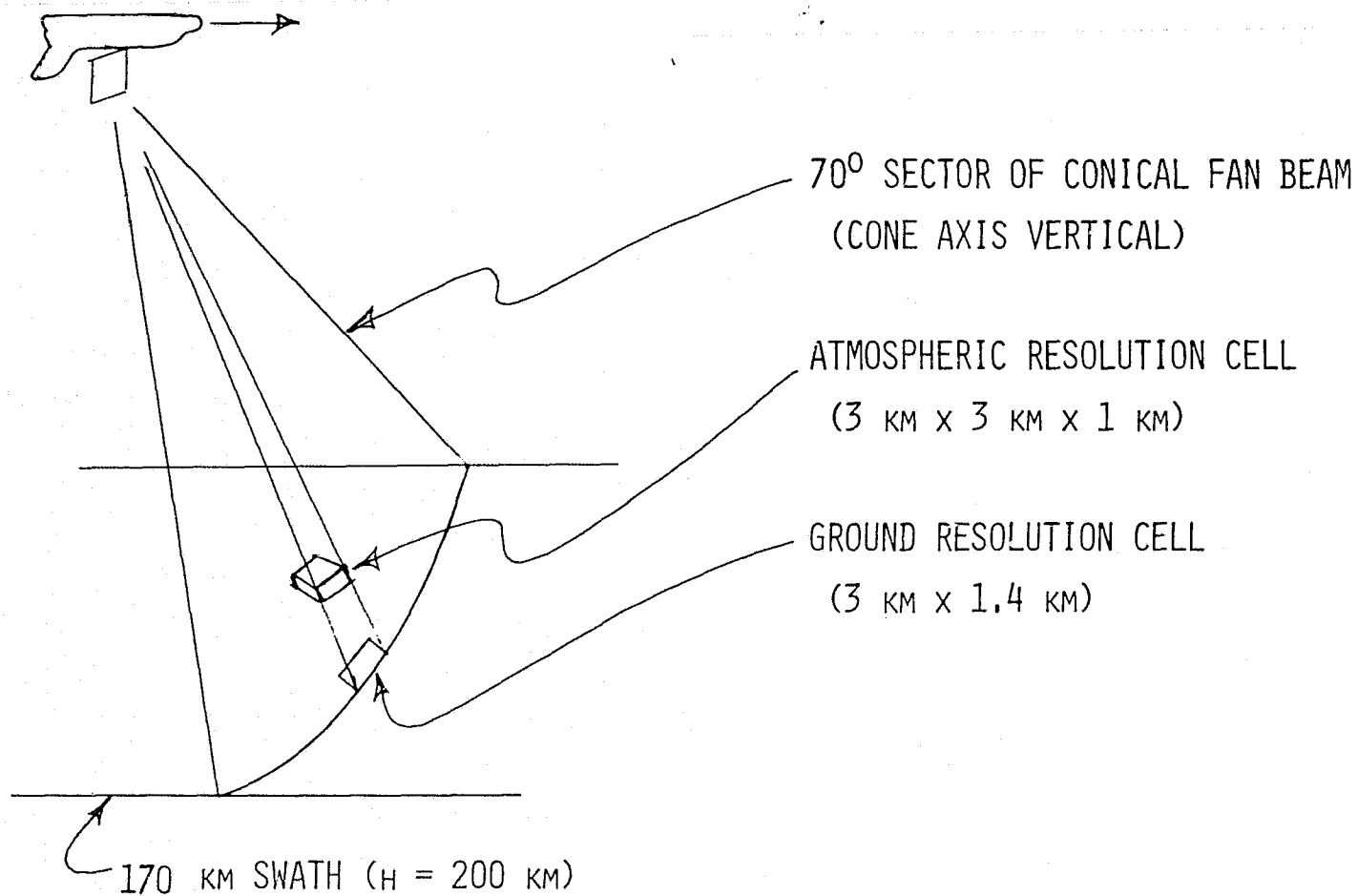


TRANSMIT ANTENNA



RECEIVE ANTENNA

SPATIAL GEOMETRY



MRF EXPERIMENTAL PHASES



PARAMETER	SUB-SCALE GOALS	FULL-SCALE GOALS
SPATIAL RESOLUTION (AZ X EL X R), KM	2.8 x 2.6 x 1	8.4 x 1.3 x 1
DOPPLER RESOLUTION	1 x 2 x 1	1 x 1 x 1
ORBIT ALTITUDE	200 KM	582 KM
SWATH WIDTH	170 KM	1000 KM
NUMBER OF AZIMUTH BEAMS	86	86
ANTENNA DIMENSIONS (H x W), M	5.8 x 4.3	35 x 4.3
NUMBER OF ANTENNAS	1	2

SCHEDULE



GO-AHEAD

SYSTEM DEFINITION

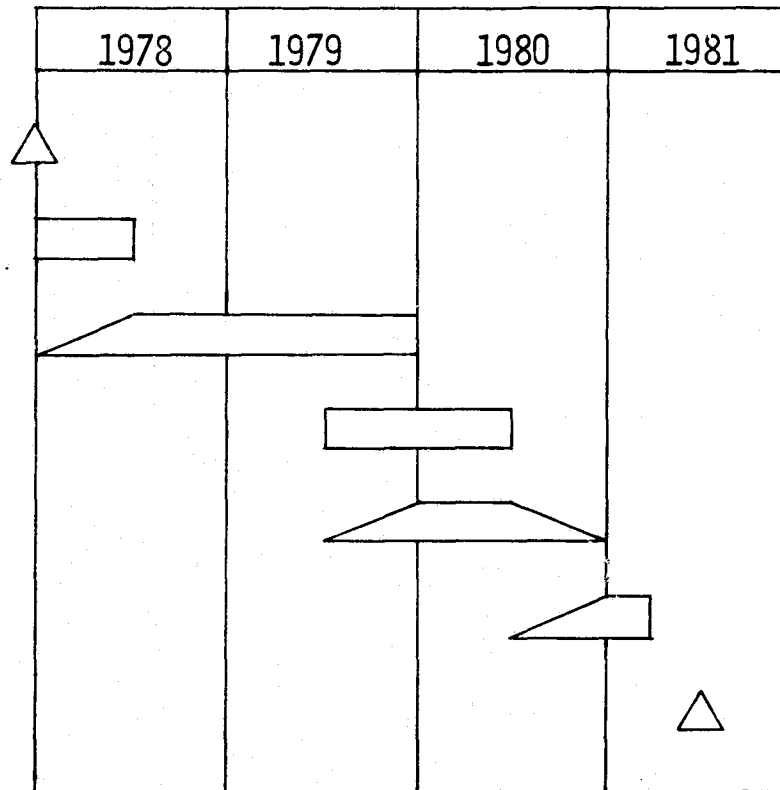
EM DESIGN & FABRICATE

FM FAB & ASSEMBLY

EM SYSTEM INTEGRATION & TEST

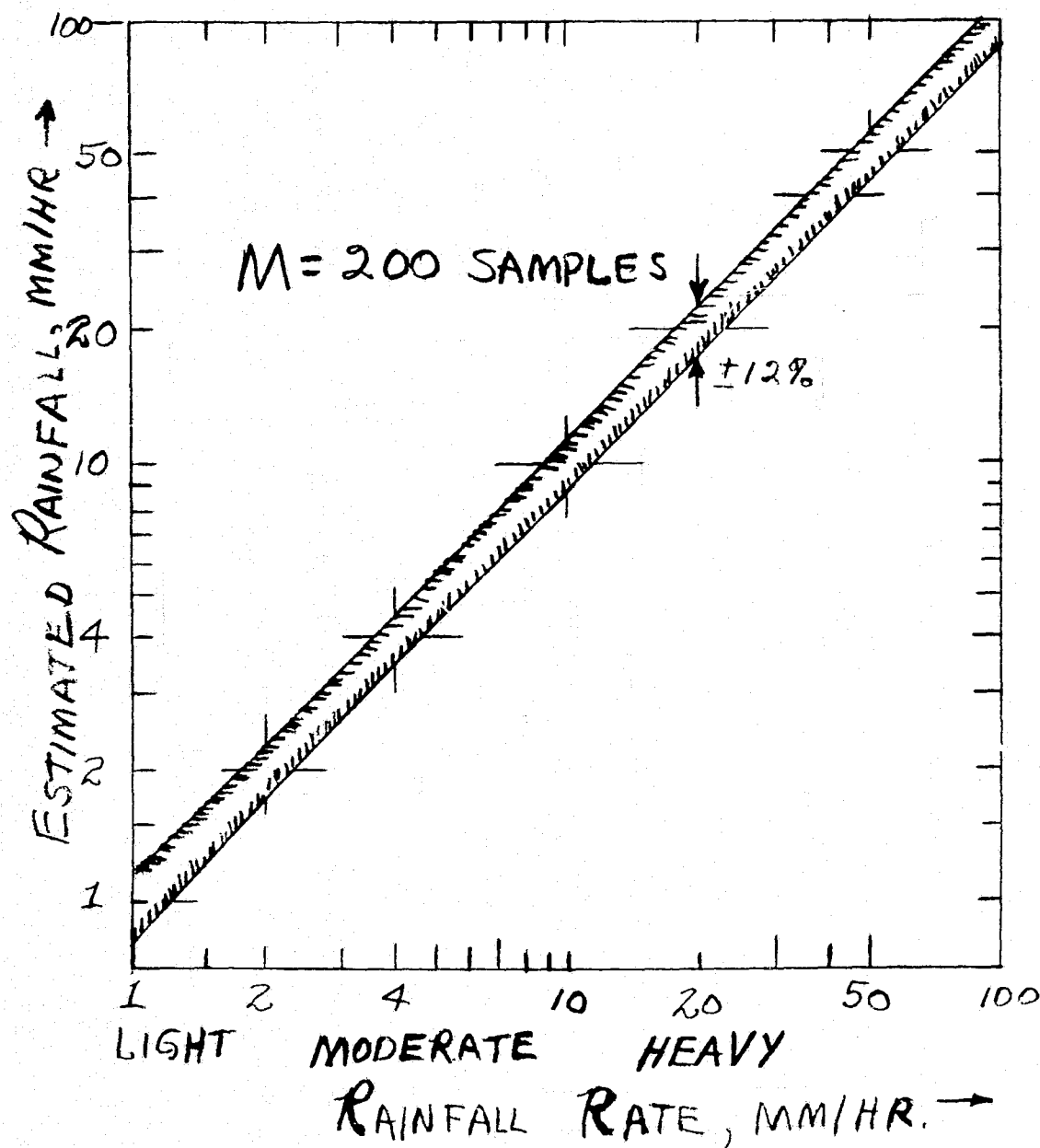
FM SYSTEM INTEGRATION & SELL-OFF

FIRST MRF FLIGHT



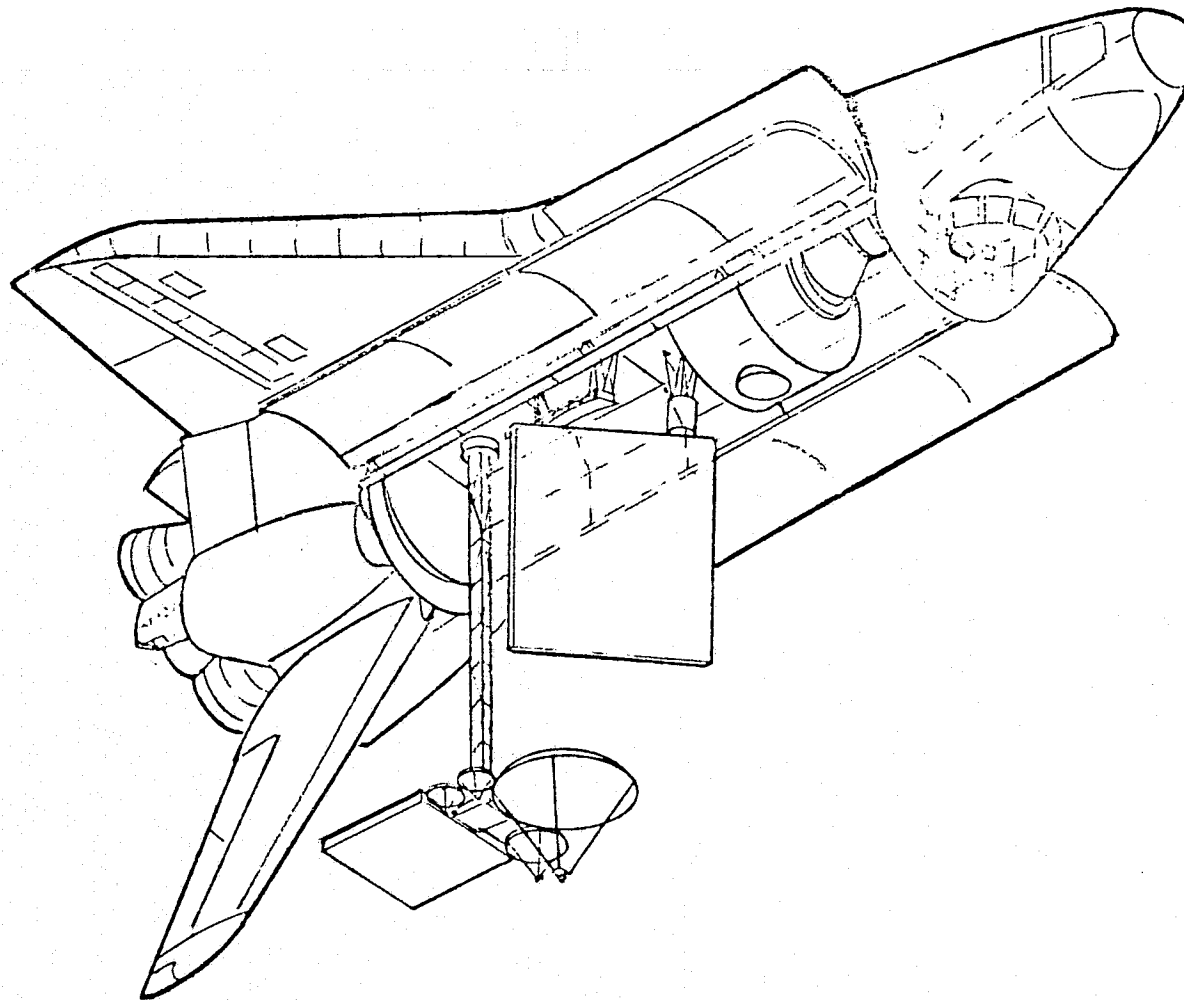
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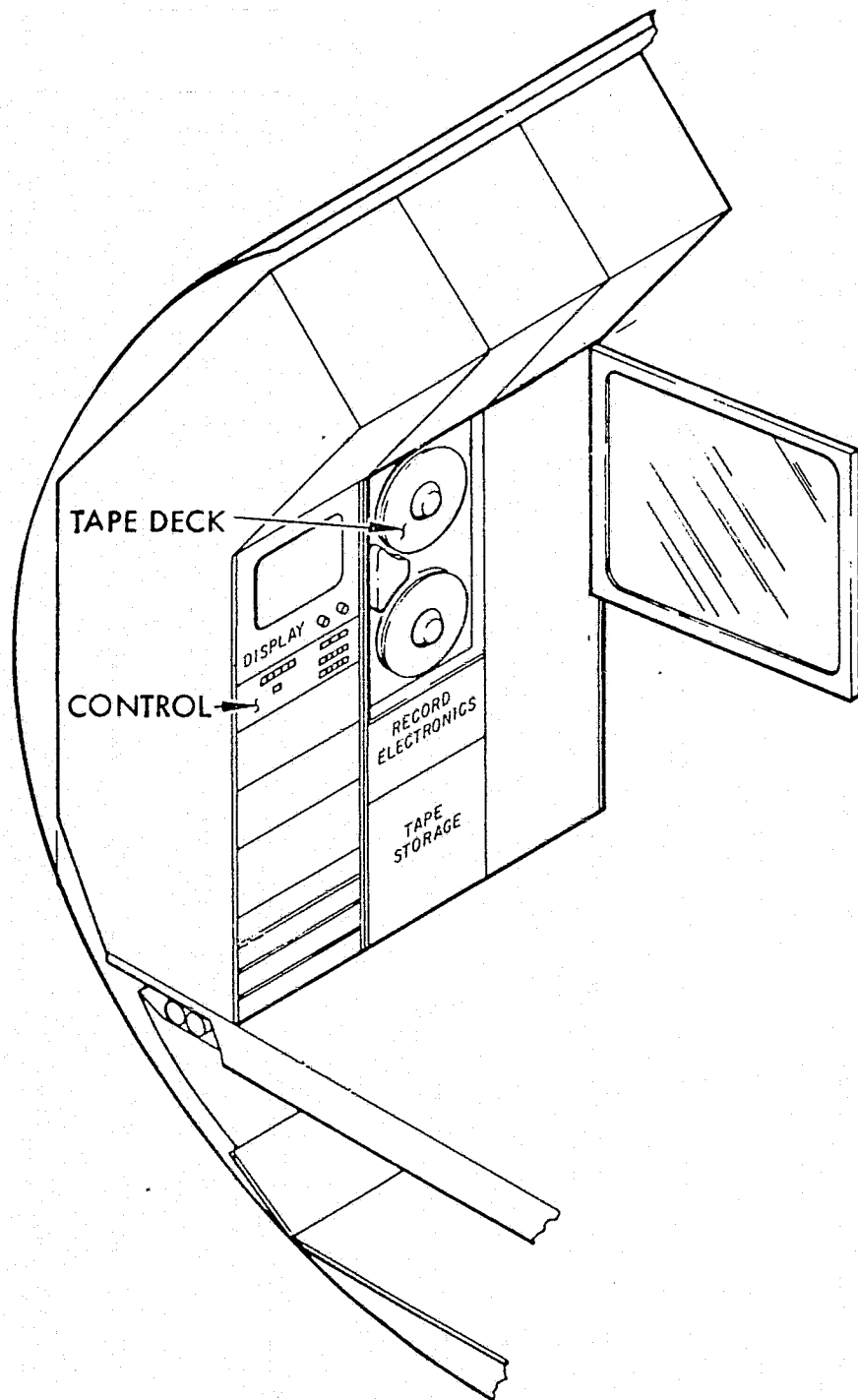
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ACCURACY

INSTALLATION





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RADAR EQUIPMENT IN MODULE

COST BREAKDOWN

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<u>UNIT</u>	<u>DETAIL DESIGN</u>	<u>FABRICATION, ASSEMBLY & TEST</u>	<u>TOTALS</u>
ANTENNA	18%	29%	47%
TRANSMITTER/RECEIVERS	5%*	13%	18%
PRE-PROCESSOR/RECORDER	9%	26%	35%
	<u>32%</u>	<u>68%</u>	<u>100%</u>

* ASSUMES TRANSMITTER DEVELOPMENT COST IS COVERED BY ANOTHER PROGRAM.

COST DRIVERS (SUB-SCALE SYSTEM)

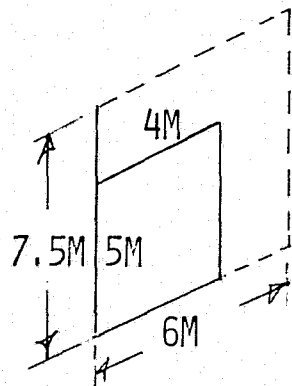


- o RESOLUTION
- o SWATH WIDTH
- o MEASUREMENT ACCURACY IN LOWER ATMOSPHERE
- o DATA TIMELINESS

SPATIAL RESOLUTION COSTS



- o ASSUMING X-BAND IS REQUIRED:



ANTENNA REQUIRED FOR 2 KM X 2 KM X 1 KM RESOLUTION
(FABRICATION COST ~ 50% GREATER THAN BASELINE, PLUS FOLDING
COST. 278 RECEIVE ELEMENTS.)

BASELINE ANTENNA (185 RECEIVE ELEMENTS)

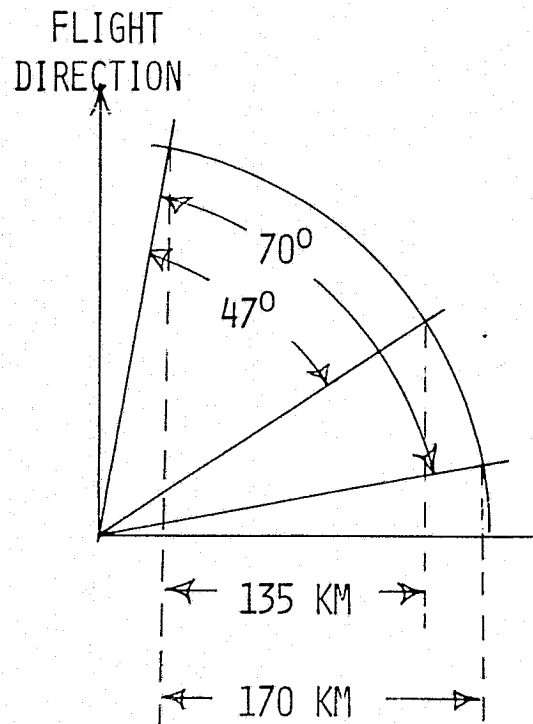
- o ASSUMING K_U-BAND (15 GHz) CAN BE USED:
 - o ANTENNA ENVELOPE SAME AS X-BAND BASELINE. (FABRICATION COST ~ 50% GREATER. 278 RECEIVE ELEMENTS.)
- o IN BOTH CASES: RECEIVER/PRE-PROCESSOR FABRICATION COSTS INCREASE BY ~ 50%.

SWATH COSTS

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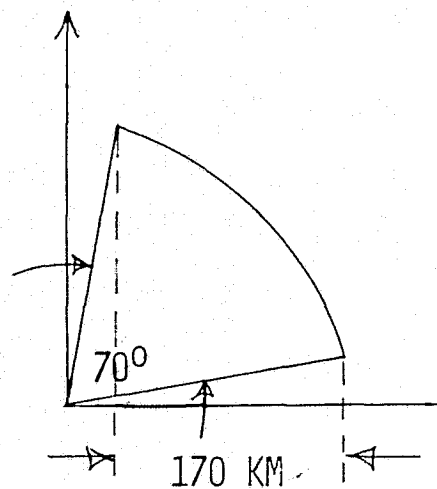
- o A 20% REDUCTION IN SWATH WIDTH REDUCES THE NUMBER OF RECEIVER CHANNELS BY 34%.



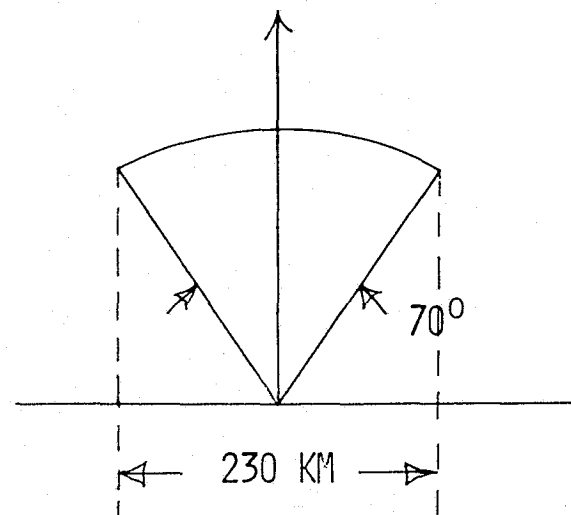
RECEIVER AND PRE-PROCESSOR FABRICATION
COSTS REDUCED.

COST SAVINGS: ~ 7%.

- o WITH REDUCED DOPPLER PROCESSING CAPABILITY:



BASELINE



BEAM CENTER MOVED TO VELOCITY VECTOR

- o POINTING ANTENNA DIRECTLY AHEAD INCREASES SWATH WIDTH BY 35%.

MEASUREMENT ACCURACY IN LOWER ATMOSPHERE



- o ANTENNA VERTICAL ALIGNMENT SHOULD BE WITHIN 0.1° TO MAINTAIN MEASUREMENT ACCURACY IN LOWER ATMOSPHERE.

SENSING APPROACHES

NONE-USE SHUTTLE ORIENTATION	NOT ACCEPTABLE: $\pm 2^{\circ}$ ERROR.
PAYLOAD SENSOR	$\pm .16^{\circ}$ (BEST ACCURACY, BASED ON 0.1° DEADBAND). SENSOR/ANTENNA ALIGNMENT ERROR. PROBABLY NOT ACCEPTABLE.
RADAR SENSOR (RECOMMENDED)	ACCURACY BETTER THAN $.01^{\circ}$ (NULLING SYSTEM). USE SHUTTLE YAW DATA. COST INCREMENT: $\sim 3\%$.

CONTROL APPROACHES

ROTATE SHUTTLE	$\pm .1^{\circ}$ DEADBAND CAUSES HUNTING.
ROTATE ANTENNA (RECOMMENDED)	FINE CONTROL POSSIBLE. VERY LOW POWER REQUIRED (~ 25 WATTS). REQUIRES EXTRA DEGREE OF FREEDOM FOR ANTENNA. COST INCREMENT: $\sim 6\%$.

DATA TIMELINESS



- o 30 MINUTES OF PRECIPITATION DATA PER DAY PROJECTED. (10 REELS OF TAPE, AT 18 LBS/REEL, FOR A 10 DAY FLIGHT).
- o TIME LAG BEFORE DATA IS PROCESSED AT GROUND STATION.
- o TELEMETERING DATA DOWN REQUIRES TAPE PLAYBACK UNIT (AND SLOWDOWN).
- o COST INCREASE FOR PLAYBACK UNIT: ~ 3%.

COST DRIVER SUMMARY

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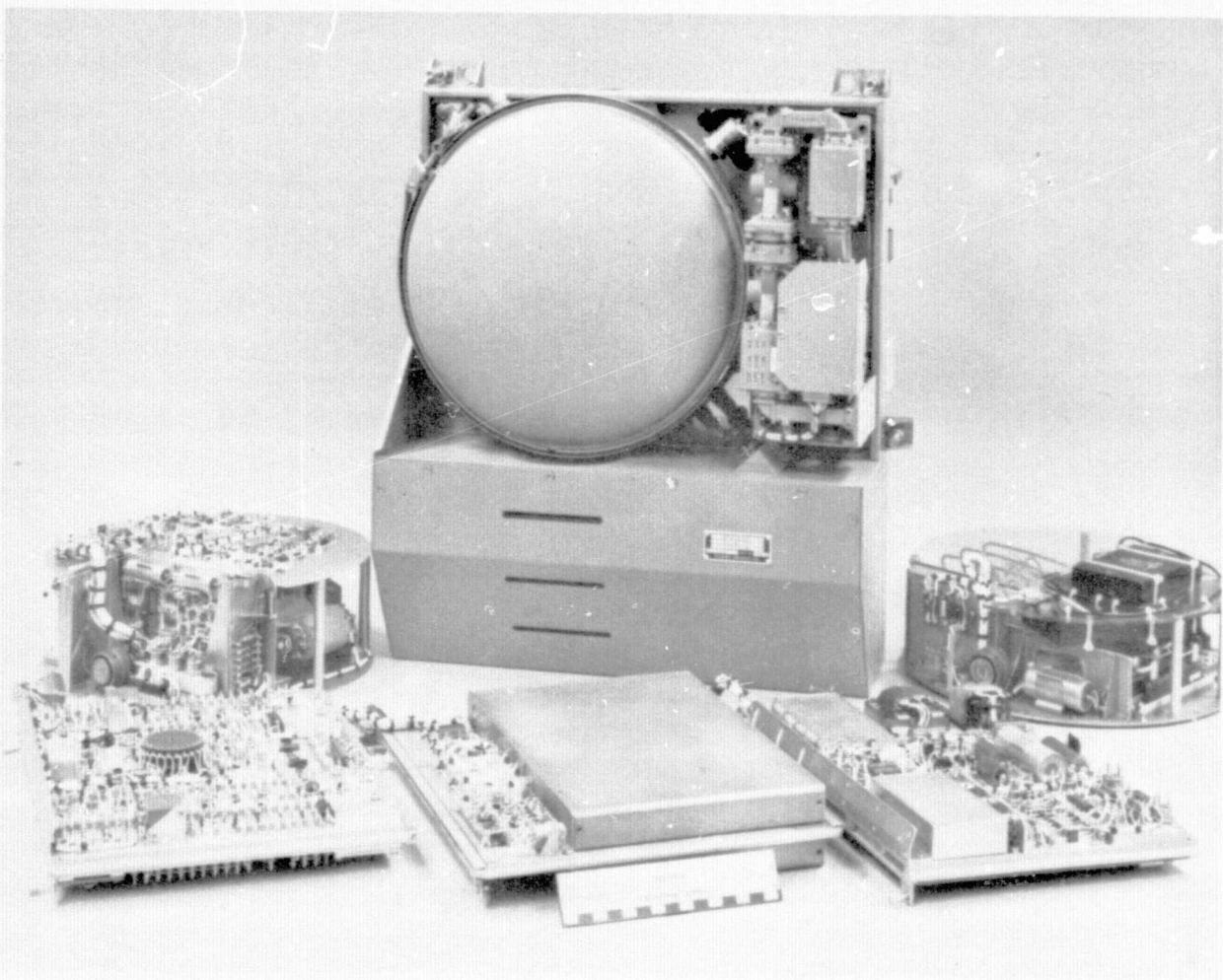
	BASELINE	ALTERNATIVE	COST INCREMENT
SPATIAL RESOLUTION (KM)	3 X 3 X 1	2 X 2 X 1	20 TO 30%
SWATH WIDTH (KM)	170	(REDUCED BEAM- WIDTH) 135	7%
SWATH WIDTH (KM)	170	(ANTENNA RE- POINTED) 230	-----
SWATH WIDTH (KM)	170	(ANTENNA RE- POINTED AND REDUCED BEAMWIDTH) 170	7.5%
MEASUREMENT BIAS IN LOWER ATMOSPHERE	0.6 dB AT 4 MM/HR.	3 dB AT 4 MM/HR.	9%

RISK ASSESSMENT

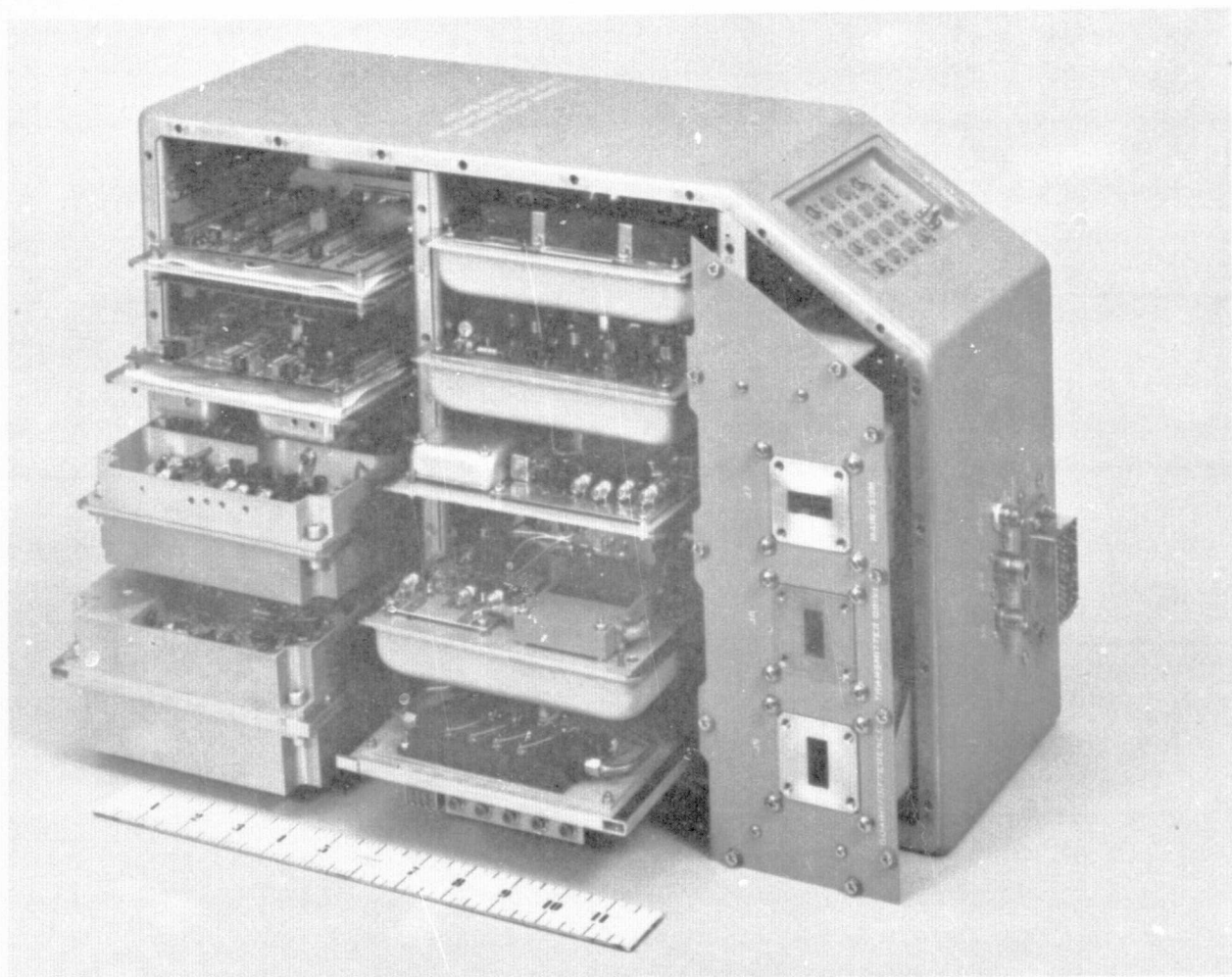
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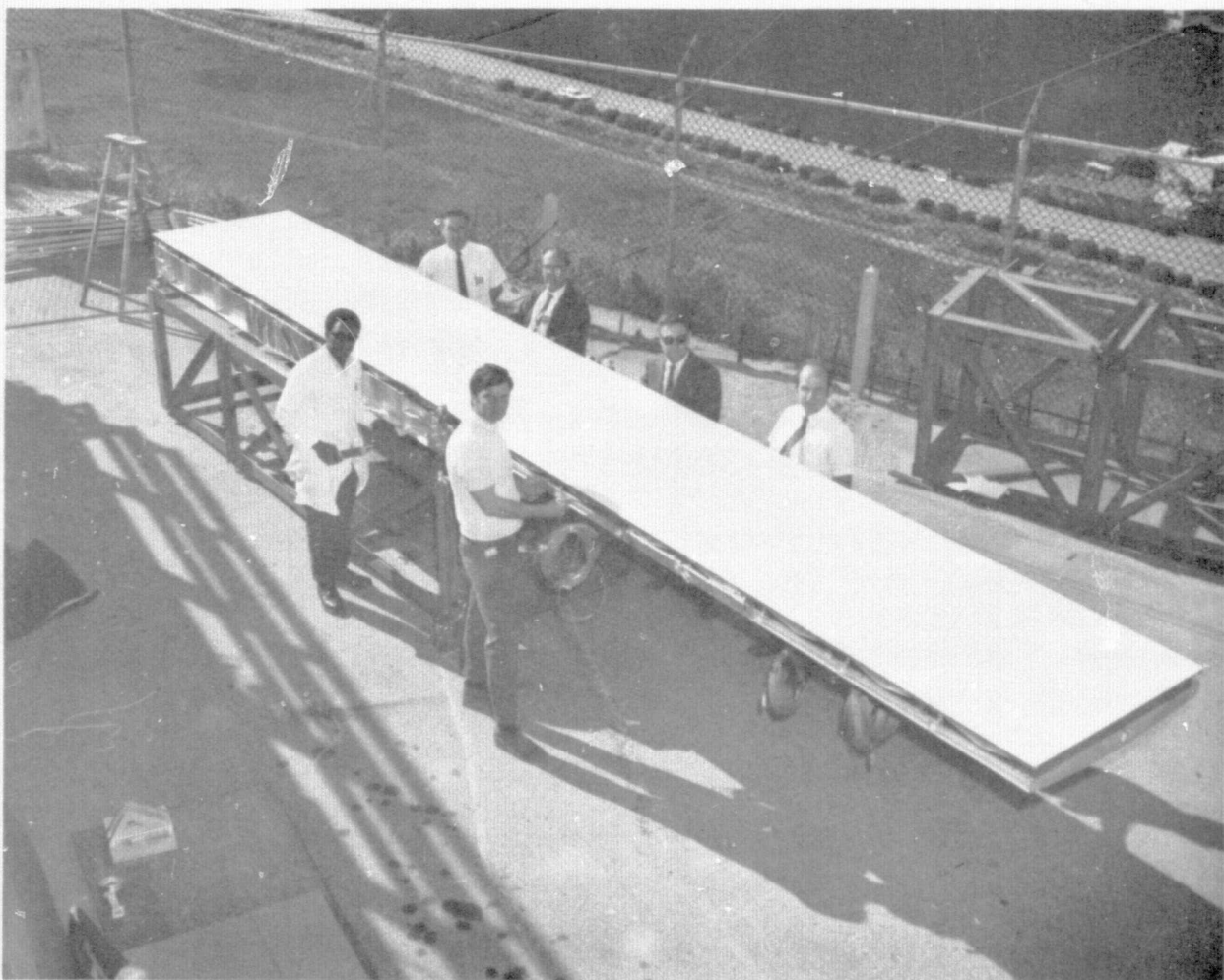
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<u>SUBSYSTEM</u>	<u>TECHNICAL RISK</u>
ANTENNA	LOW
TRANSMITTER/RECEIVERS	LOW
PRE-PROCESSOR/RECORDER	VERY LOW
THERMAL CONTROL	VERY LOW



ORIGINAL PAGE IS
OF POOR QUALITY





ORIGINAL PAGE IS
OF POOR QUALITY

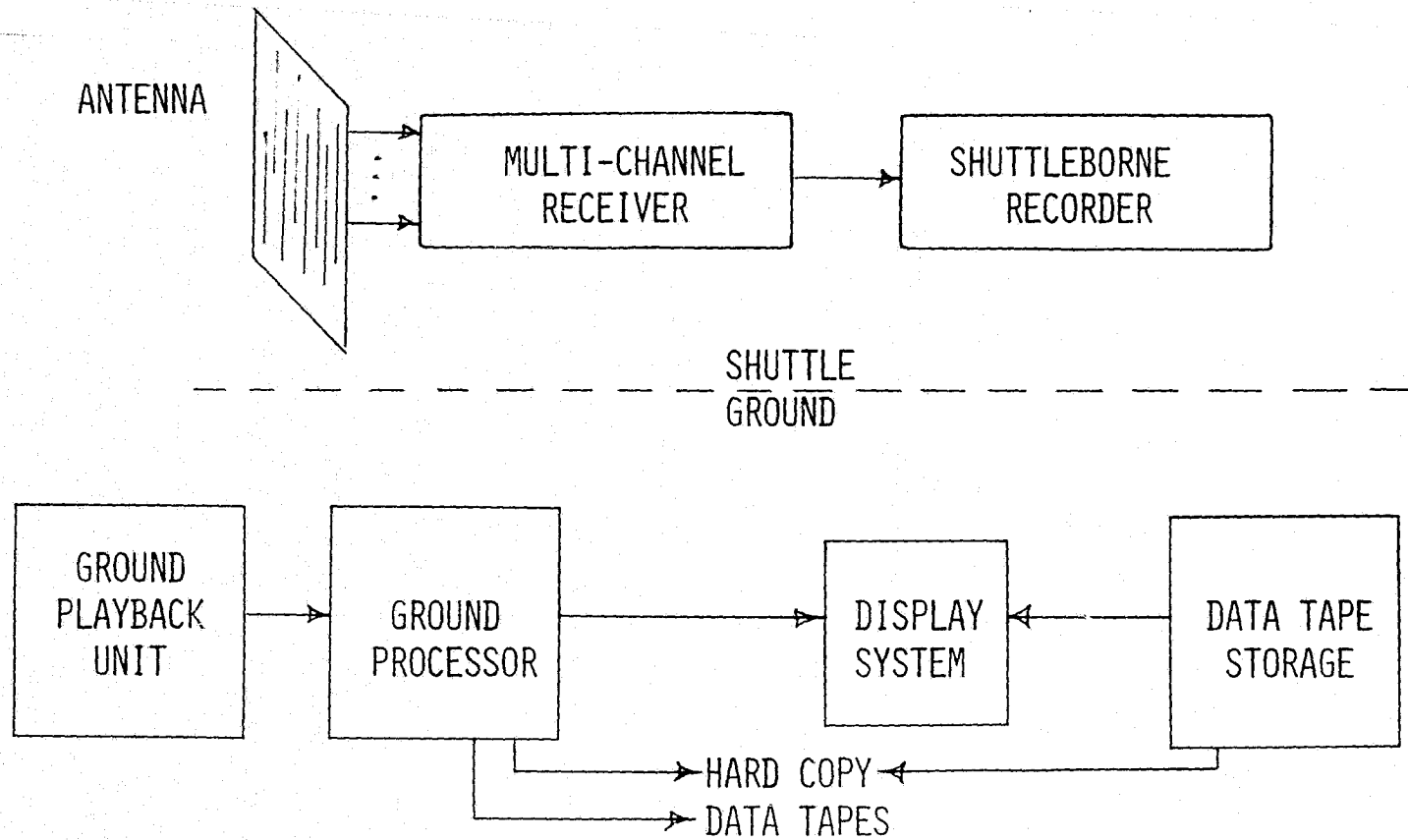
CRITICAL DESIGN ITEMS



- o MULTI-CHANNEL RECEIVER DESIGN TESTS
 - LOW COUPLING AND GOOD PHASE BALANCE NEEDED
- o ANTENNA STABILIZATION SENSOR DESIGN
 - VERTICAL SENSING WITH RADAR
- o ANTENNA SLOT TESTS
 - LOW ANTENNA SIDELOBES NEEDED
- o ANTENNA STRUCTURAL/THERMAL STUDIES
 - LONG LEAD TIME ITEM

- o DATA FLOW
- o OUTPUTS
- o SYSTEM DUTY FACTOR
- o GROUND PROCESSOR FUNCTIONS
- o SELECTED SYSTEM PARAMETERS
- o SELECTED PERFORMANCE PARAMETERS
- o SUB-SCALE/FULL-SCALE COMPARISON

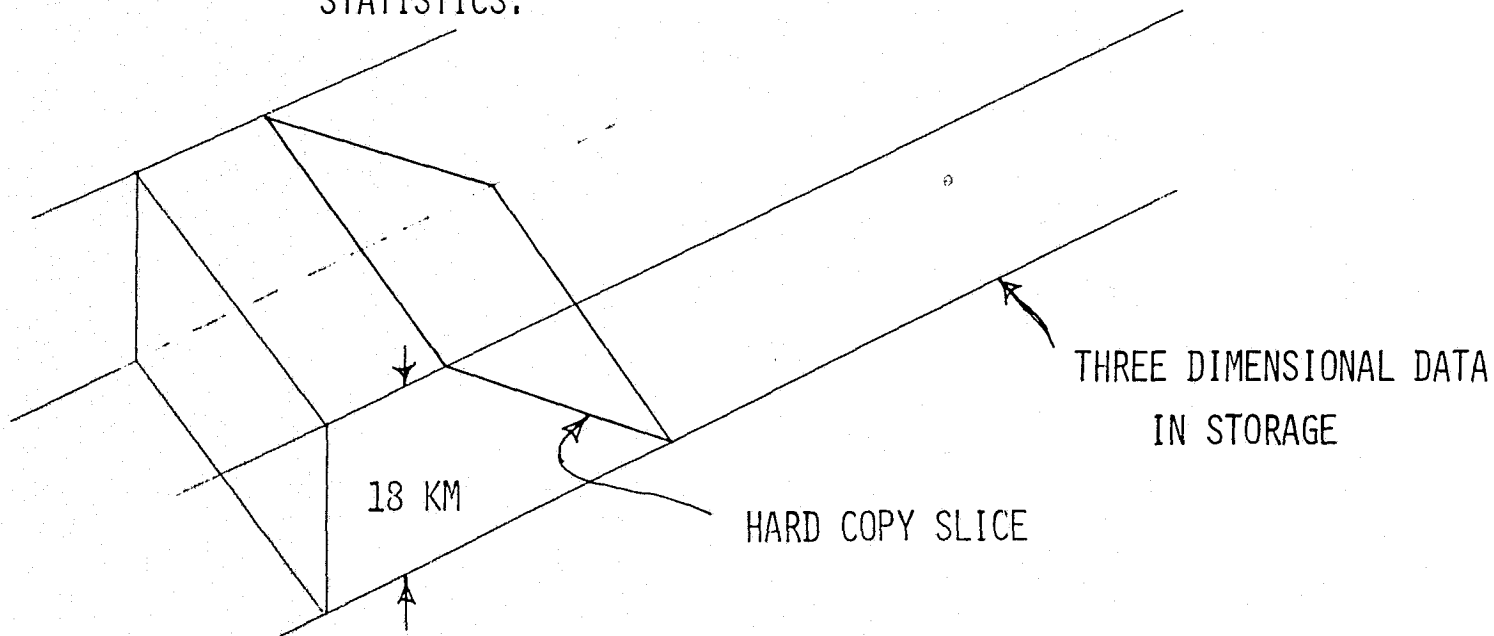
DATA FLOW



OUTPUTS



- o DATA TAPES: FORMATTED, EARTH COORDINATE REFERENCED, TIME-LABELED MEASUREMENTS OF PRECIPITATION AND SURFACE REFLECTIVITY.
- o HARD COPY: A TWO-DIMENSIONAL "SLICE" OF THE THREE DIMENSIONAL DATA. - DATA STATISTICS.



SYSTEM DUTY FACTOR

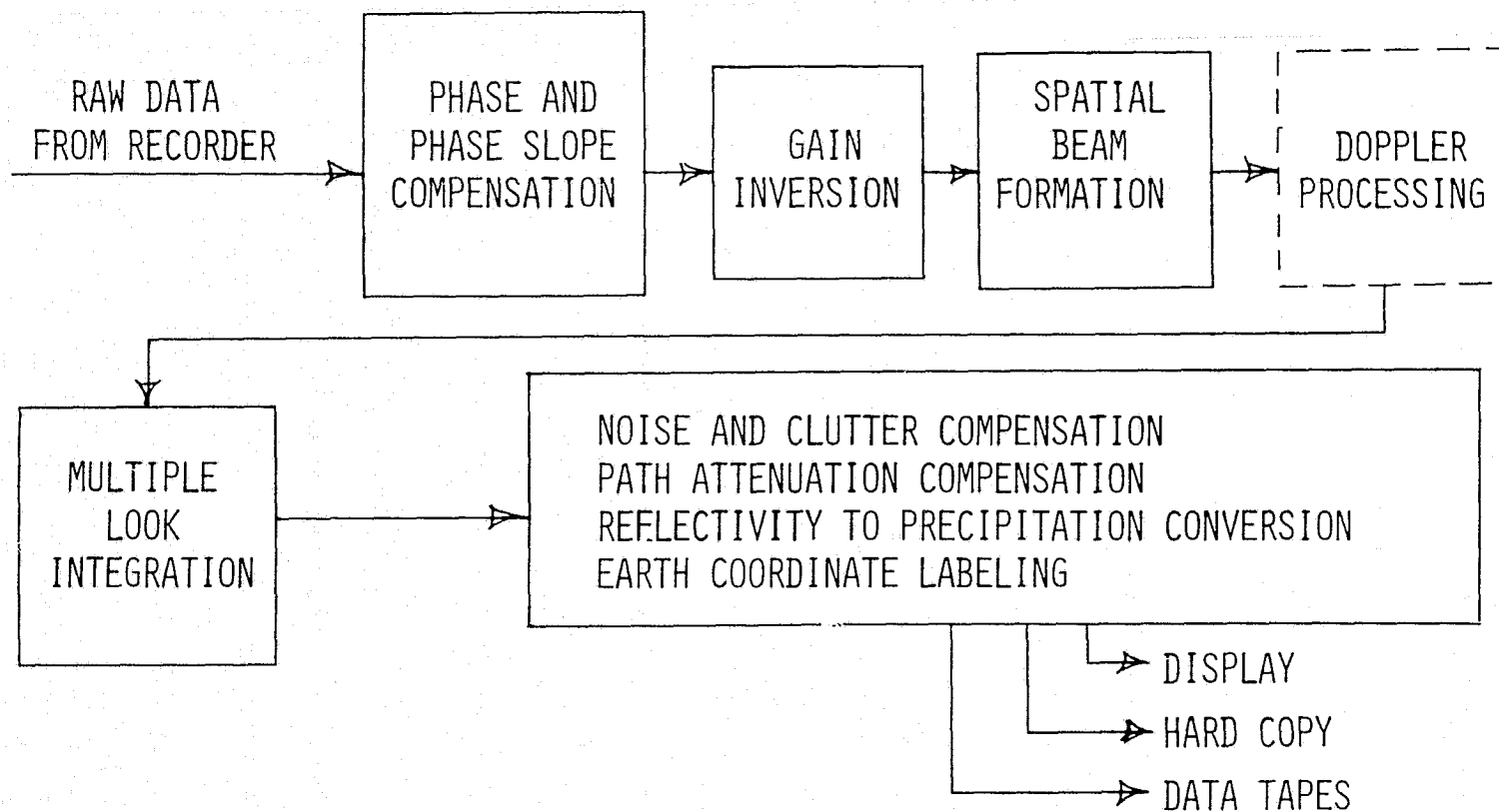


- o SELECTED STORM SYSTEMS
- o ALLOCATE 30 MINUTES/DAY AVERAGE (2%)
(1 REEL = 30 MINUTES = 18 LBS.)
- o MRF SENSOR PROGRAMMED BY SUMMARY MESSAGE ON COMMAND DATA LINK. BASED ON WEATHER NETWORK DATA.
- o ALTERNATE PROGRAMMING APPROACH: USE ON-BOARD SENSOR-AUXILIARY OR MRF DERIVED.
- o DUTY FACTOR IMPACTS ON MRF AVERAGE POWER CONSUMPTION & TAPE STORAGE REQUIREMENTS.

GROUND PROCESSOR FUNCTIONS

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GROUND PROCESSING REQUIREMENTS

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- o SPATIAL BEAM FORMATION MULTIPLICATION (FFT):
 - 10.3M REAL MULTIPLIES/KILOMETER
 - 78M REAL MULTIPLIES/SECOND (REAL TIME)
- o REAL TIME PROCESSING REQUIRES ONE MASTER-SLAVE, PROGRAMMABLE SIGNAL PROCESSOR

SELECTED SYSTEM PARAMETERS

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OPERATING FREQUENCY	X-BAND
ORBIT ALTITUDE	200 \pm 30 KM
SWATH WIDTH	170 KM
AVERAGE TRANSMITTED POWER	75 TO 150 WATTS
ANTENNA SIZE	4 M X 5 M
BEAM WIDTH:	
ELEVATION	0.5 $^{\circ}$
AZIMUTH	0.8 $^{\circ}$ TO 0.9 $^{\circ}$
PULSE REPETITION FREQUENCY	3410 Hz, 6820 Hz
NUMBER OF RECEIVER CHANNELS	185

SELECTED PERFORMANCE PARAMETERS



MODE	REAL ARRAY
RESOLUTION	3 x 3 x 1 KM
SIGNAL TO TOTAL NOISE RATIO (FOR 4MM/HR)	6 dB
NUMBER OF INDEPENDENT SAMPLES	200
CALIBRATION ACCURACY*	1.2 dB AT 80% CONFIDENCE LEVEL
MEASUREMENT ACCURACY*	1.6 dB AT 80% CONFIDENCE LEVEL

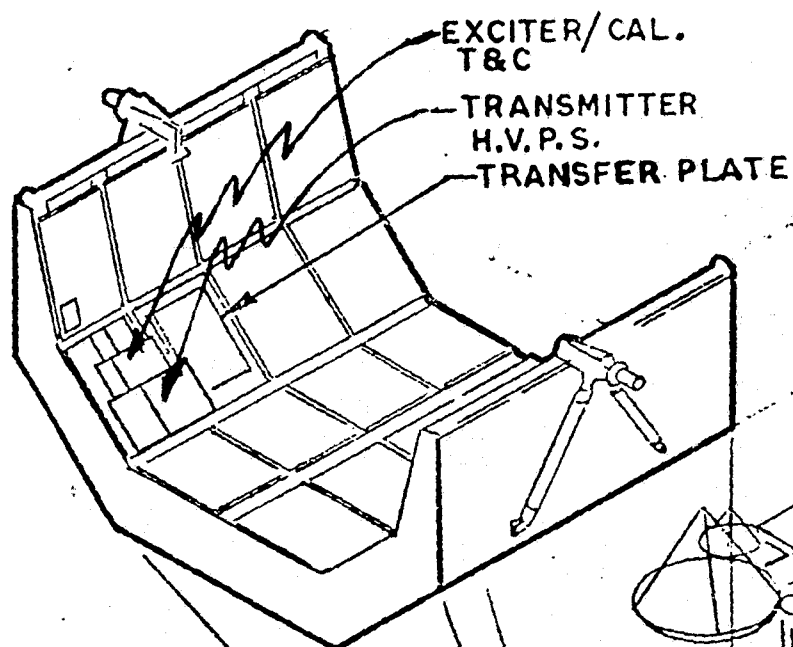
*TEMPORAL CALIBRATION FACTORS OF .44 dB RSS INCLUDED

SUB-SCALE/FULL SCALE COMPARISON



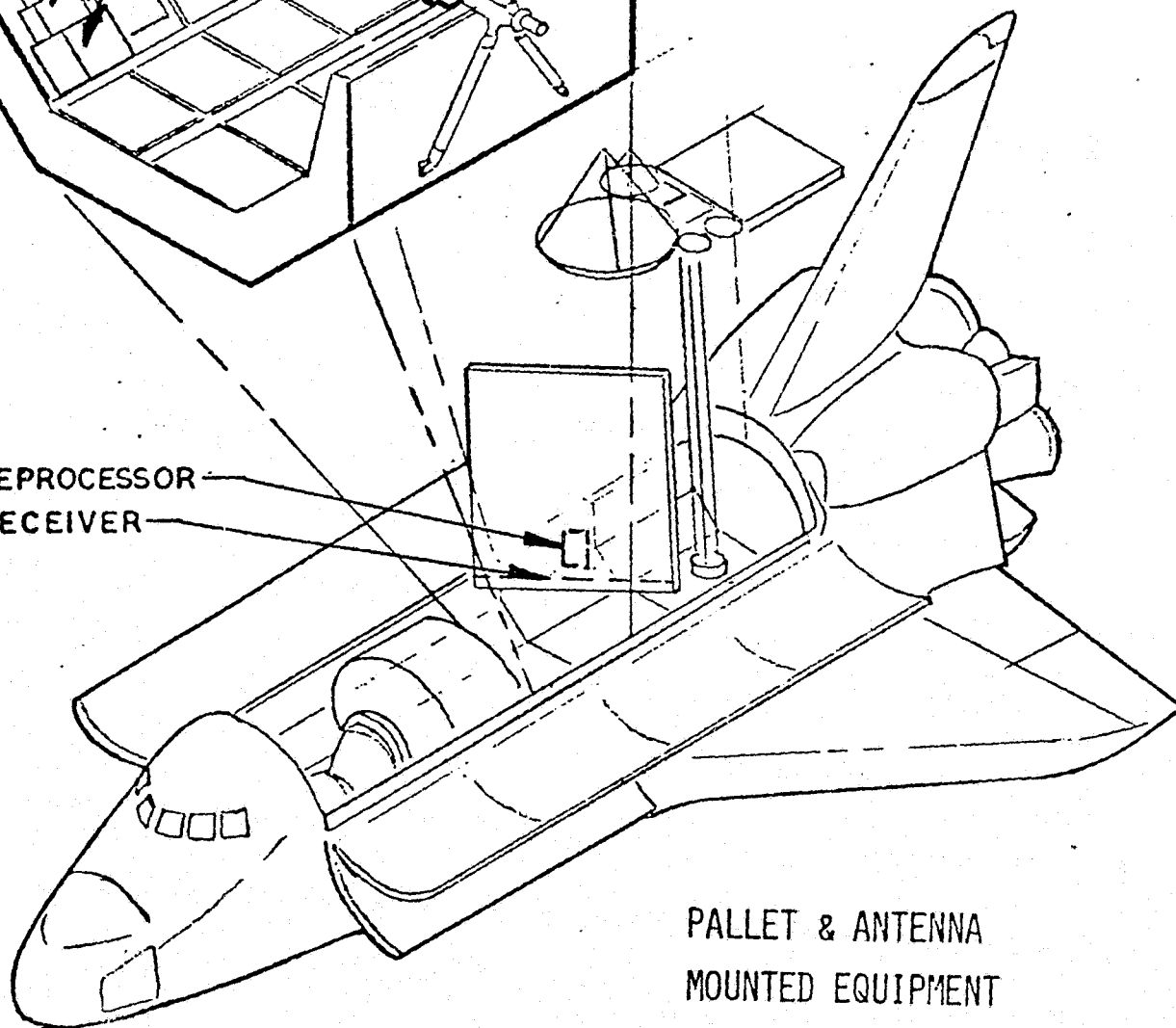
	SUB-SCALE AT 200 ± 30 KM	FULL SCALE AT 600 ± 30 KM
WAVELENGTH	3 CMS	3 CMS
RESOLUTION	3 x 3 x 1 KM	3 x 3 x 1 KM
ARRAY DIMENSIONS, V X H	5 x 4 M	15 x 12 M
NO. OF RECEIVE ELEMENTS	185	555
TRANSMITTER:		
PEAK POWER	8 KW	24 KW
AVERAGE POWER	75 WATTS	130 WATTS
PRF, Hz	3410 Hz	1970 Hz
BURST FREQUENCY, DUTY	227 Hz, .4	66 Hz, .4
SWATH WIDTH	170 KM	545 KM
NO. OF INDEPENDENT SAMPLES	200	120
SIGNAL-TO-TOTAL NOISE RATIO	6 dB	6 dB
MEASUREMENT ACCURACY*	1.6 dBz	1.8 dBz

*80% CONFIDENCE LEVEL WITH 1.2 dBz EQUIVALENT CALIBRATION ACCURACY



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PREPROCESSOR
RECEIVER



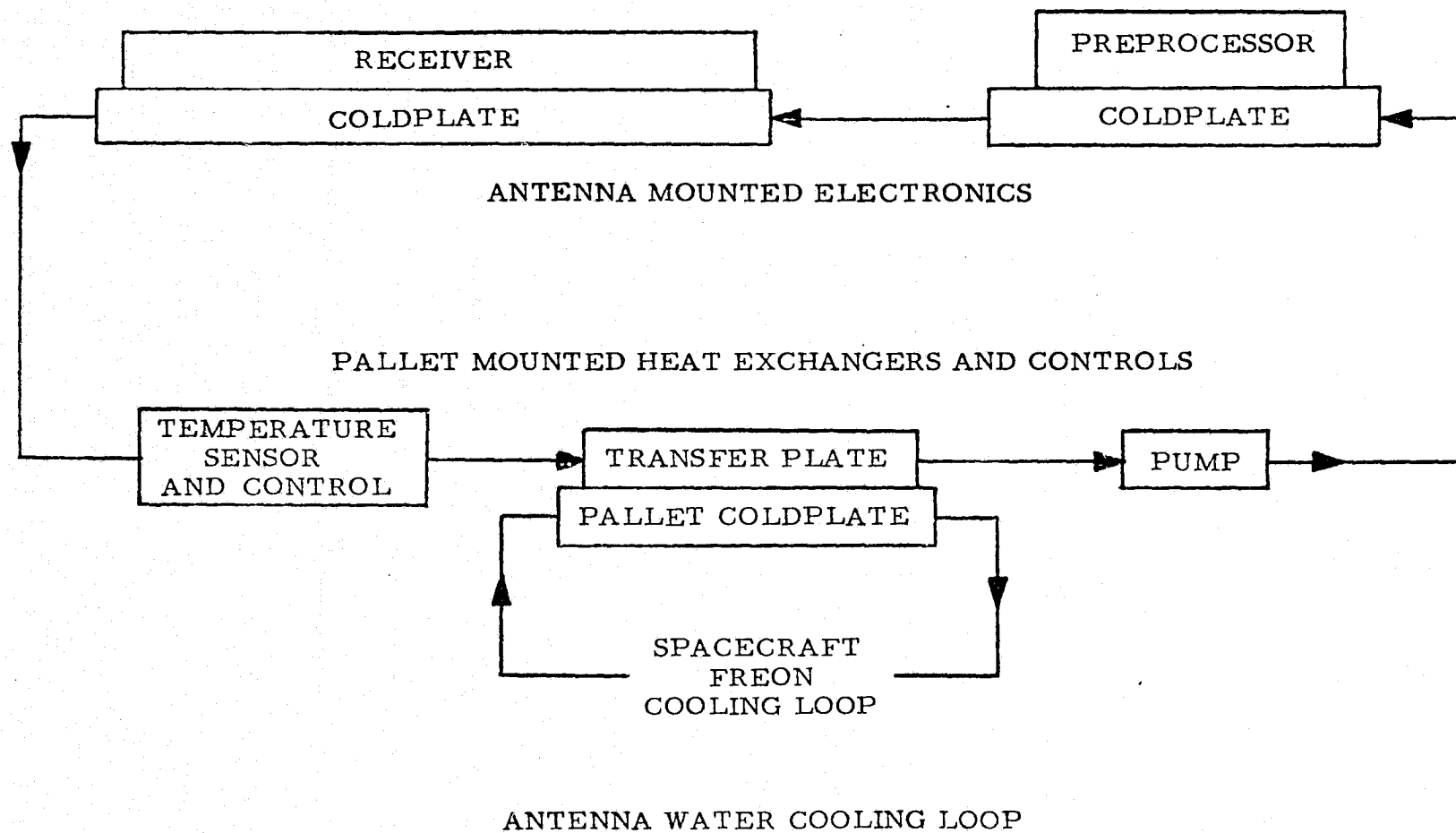
POWER, WEIGHT, VOLUME ESTIMATES

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EQUIPMENT	LOCATION	POWER WATTS	WEIGHT Kg (LB)	VOLUME M ³ (FT ³)
ANTENNA	PALLET BAY	30	275 (605)	6.1 (215)
TRANSMITTER, HVPS, LVPS, EXCITER, CALIBRATOR, TIMING & CONTROL	PALLET COLD PLATE	1530	83.6 (184)	.105 (3.71)
RECEIVERS, PRE-PROCESSOR,	ANTENNA REAR SURFACE	800	37.0 (81.4)	.06 (212)
THERMAL CONTROL	PALLET COLD PLATE		10.5 (23)	.019 (.68)
RECORDER, BUFFER/FORMATTER AND CONTROL	PRESSURIZED MODULE	680	108 (238)	.785 (27.7)
TOTALS		3040	51.1 (1131)	7.069 (249.6)

COOLING ANTENNA MOUNTED ELECTRONICS



METEOROLOGICAL RADAR FACILITY ELECTRONICS

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ELECTRONICS EQUIPMENT	MOUNTING LOCATION	THERMAL DISSIPATION (WATTS)	COOLING METHOD	WEIGHT Kg (POUNDS)	VOLUME M ³ (FT ³)	DIMENSIONS MM (IN)
RECEIVER	ANTENNA REAR SURFACE COLD PLATE	100	CONDUCTION TO COLDPLATE	25.2 (55.5)	.031 (1.09)	102 x 76 x 3993 (4 x 3 x 157.2)
PREPROCESSOR		700		11.8 (50.9)	.0287 (1.02)	254 x 686 x 165 (10 x 27 x 6.5)
TRANSMITTER AND HV POWER SUPPLY	PALLET COLD PLATE	950		43 (94)	.071 (2.49)	432 x 559 x 292 (17 x 22 x 11.5)
LV POWER SUPPLY		380		50	.013 (.451)	254 x 305 x 165 (10 x 12 x 6.5)
EXCITER/CALIBRATOR/ TIMING AND CONTROL		200		40	.021 (.752)	254 x 508 x 165 (10 x 20 x 6.5)
RECORDER	MODULE RACK	200	FORCED AIR	91 (200)	.713 25.2	530 x 1770 x 760 (20.86x69.68x29.92)
BUFFER/FORMATTER AND CONTROL		480		17.3 (38)	.072 (2.53)	572 x 165 x 760 (22.52x6.5x29.92)
TRANSFER PLATE, PUMP & TEMPERATURE CONTROL	PALLET COLD PLATE	INCLUDED IN RECEIVER AND PREPROCESSOR	CONDUCTION TO COLDPLATE	10.5 (23)	.019 (.68)	880 x 861 x 25.4 (34.6 x 33.9 x 1)

CRITICAL DESIGN



- o AREAS REQUIRING LONG LEAD TIME.
- o AREAS IN WHICH ADDITIONAL DEVELOPMENT OR TRADE-OFF IS NECESSARY FOR REDUCTION OF COST OR TECHNICAL RISK.

CRITICAL DESIGN AREAS



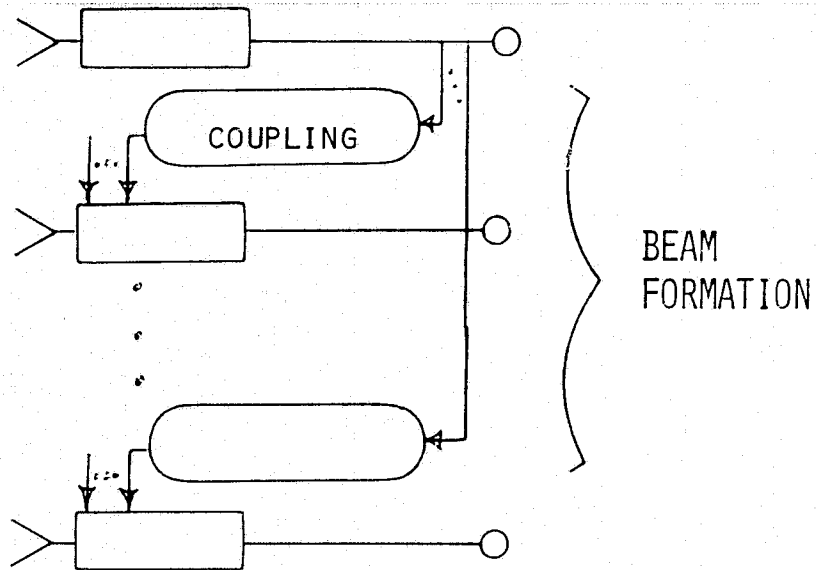
- o MULTI-CHANNEL RECEIVER DESIGN TESTS
- o ANTENNA STABILIZATION CIRCUIT DEVELOPMENT
- o ANTENNA ELECTRICAL DESIGN
- o ANTENNA STRUCTURAL/THERMAL DESIGN

- o AZIMUTH SIDELobe PERFORMANCE REQUIRES 4° (1σ) PHASE AND PHASE SLOPE MATCHING.
- o MATCHING CAN BE ACHIEVED BY FEEDBACK CONTROL, USING CALIBRATE SIGNAL, ON-BOARD, OR BY PHASE CORRECTION IN THE GROUND PROCESSOR.
- o COST AND TECHNICAL RISK OF THESE APPROACHES SHOULD BE COMPARED.

INTERCHANNEL ISOLATION

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- o 184 COUPLING PATHS TO EACH CHANNEL
- o SUMMATION OF 185 OUTPUTS FOR BEAM FORMATION
- o -70 dB ISOLATION REQUIREMENT FOR COHERENT COUPLING (GRATING LOBE FORMATION)

- o CIRCUIT DESIGN MUST MINIMIZE INTER-CHANNEL COUPLING - IN PARTICULAR, COHERENT COUPLING.

ISOLATION PROBLEM

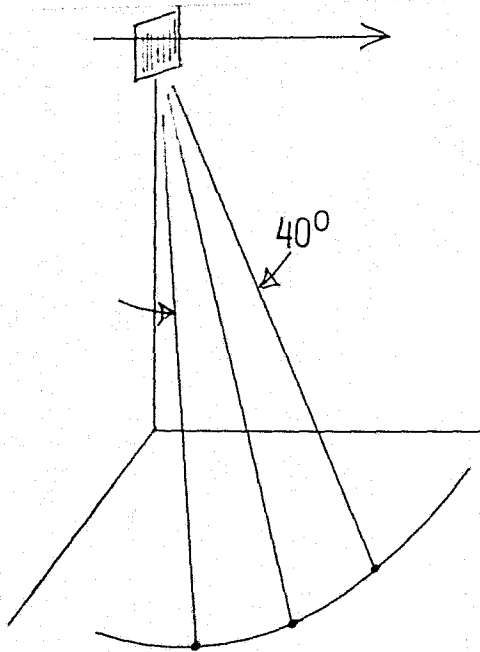
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- o SIGNAL CROSS-TALK PRODUCES SIDE-LOBES.

CROSS-TALK	ISOLATION REQUIREMENT	EFFECT
UNCORRELATED	-35 dB	NOISE LIKE
PARTIALLY CORRELATED	-58 dB	MIXED
TOTALLY CORRELATED	-81 dB	GRATING LOBES

- o APPROACH: DESIGN FOR -66 dB ISOLATION.

ANTENNA STABILIZATION CIRCUIT DEVELOPMENT



- o FORM 3 BEAMS (0° , $+20^{\circ}$, -20°)
- o ADJUST A/D TIMING SO THAT 0° BEAM SAMPLE OCCURS AT ATMOSPHERE/TERRAIN THRESHOLD.
- o ROTATE ANTENNA SO THAT SAME A/D SAMPLES OCCUR AT ATMOSPHERE TERRAIN THRESHOLD FOR $\pm 20^{\circ}$ BEAMS.
- o ANTENNA VERTICAL AXIS IS THEN NULLED TO LOCAL VERTICAL.

- o NEED SERVO-DYNAMIC DESIGN OF STABILIZATION CONTROL SYSTEM.

SHUTTLE MRF SYSTEM DESCRIPTION

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TOPICS:

SPACE SYSTEM ELEMENTS

CALIBRATION

SYSTEM PARAMETERS

BURST TIMING

SENSITIVITY TO ORBITAL VARIATION

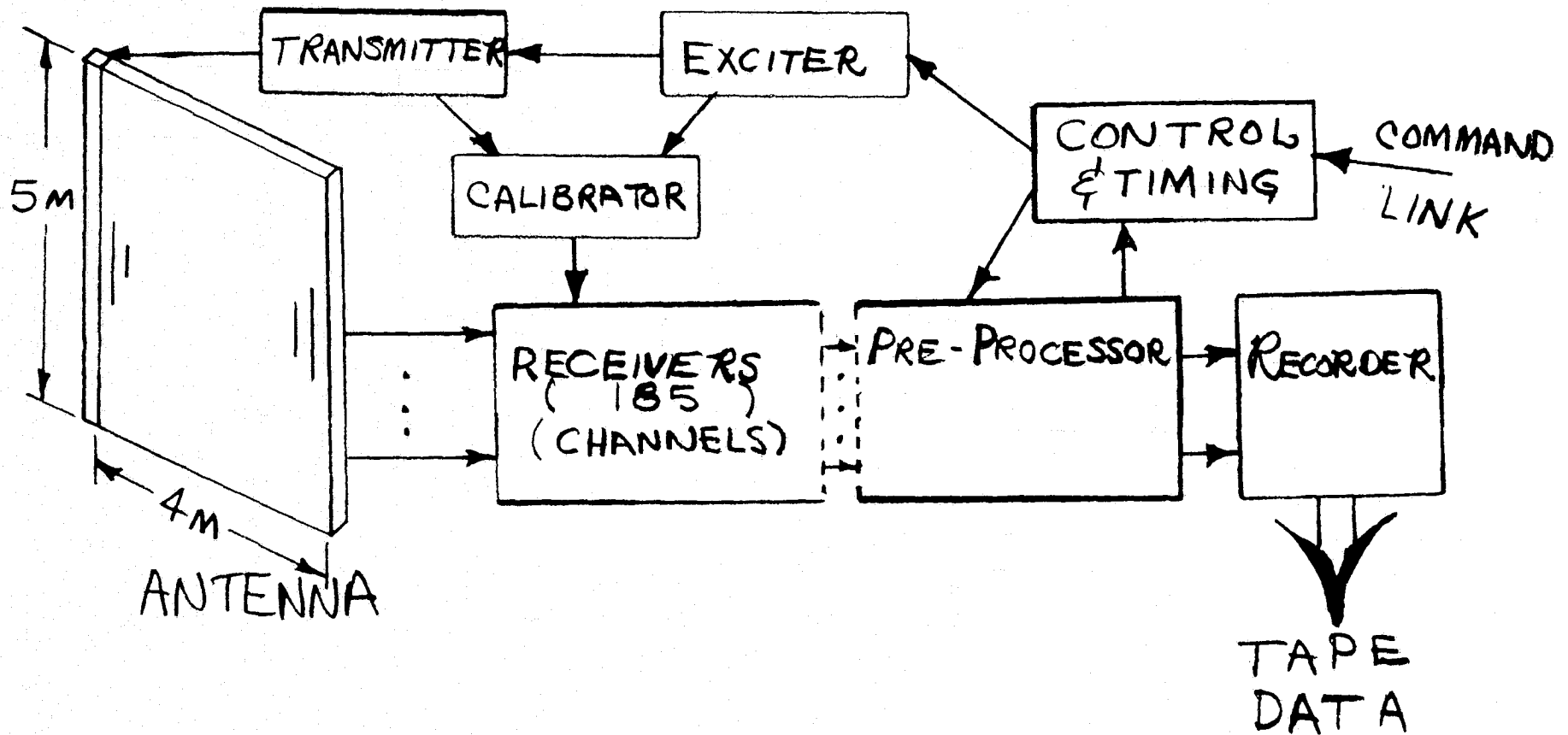
ELEVATION PATTERN/ RESOLUTION/ SURFACE CLUTTER/ DOPPLER MODE

DATA RATES

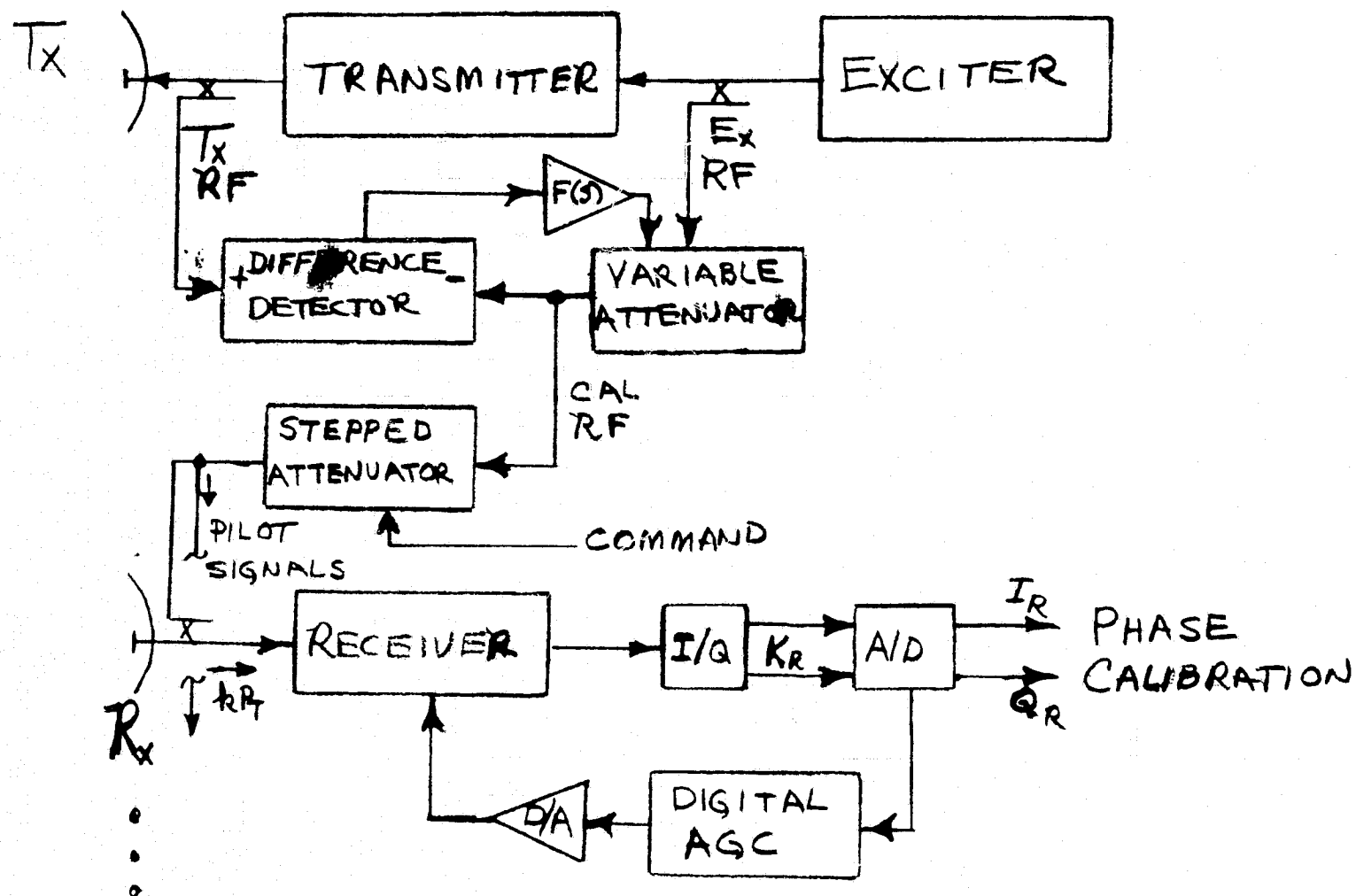
SPACE SYSTEM ELEMENTS

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CALIBRATION:
 $P_T \cdot \text{GAIN}_T = \text{CONSTANT } (K_R) \text{ AT A/D CONVERTER}$



SYSTEM PARAMETERS (1)

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ANTENNA: 5 x 4 m
FREQUENCY: 10 GHZ
ANTENNA ORIENTATION: VERTICAL & 45° TO ORBIT PLANE
VERTICAL BEAM: ~.5° TILTED AT 46.6° FROM THE NADIR
HORIZONTAL BEAMS: ~.7° AT 10° & 80° TO ~.9° AT 45° IN THE AZIMUTH PLANE
NO. OF RECEIVE
ANTENNA ELEMENTS: 185 (HORIZONTAL PLANE)
RANGE RESOLUTION: 1 KM
SPATIAL RESOLUTION (H = 200 KM):
EL: 2.8 KM
AZ: 2.7-3.3 KM
NO. OF AZIMUTH BEAMS: ≥82

SYSTEM PARAMETERS (2)



ORBIT ALTITUDE:	200 \pm 30 KM	
FREQUENCY AGILITY:	3 RF'S PER BURST	
BURST; RATE:	227 Hz	
DUTY:	.4	
DUAL MODE:	PRINCIPLE (REAL APERTURE)	SECONDARY (DOPPLER)
TRANSMITTER:	3410 Hz	6820 Hz
PEAK POWER:	8 KW	8 KW
AVERAGE POWER:	75 WATTS	150 WATTS
RECEIVERS (185):		
NOISE FIGURES:	10 DB (MAX) 8 DB (TYPICAL)	10 DB (MAX) 8 DB (TYPICAL)

SYSTEM PARAMETERS (3)

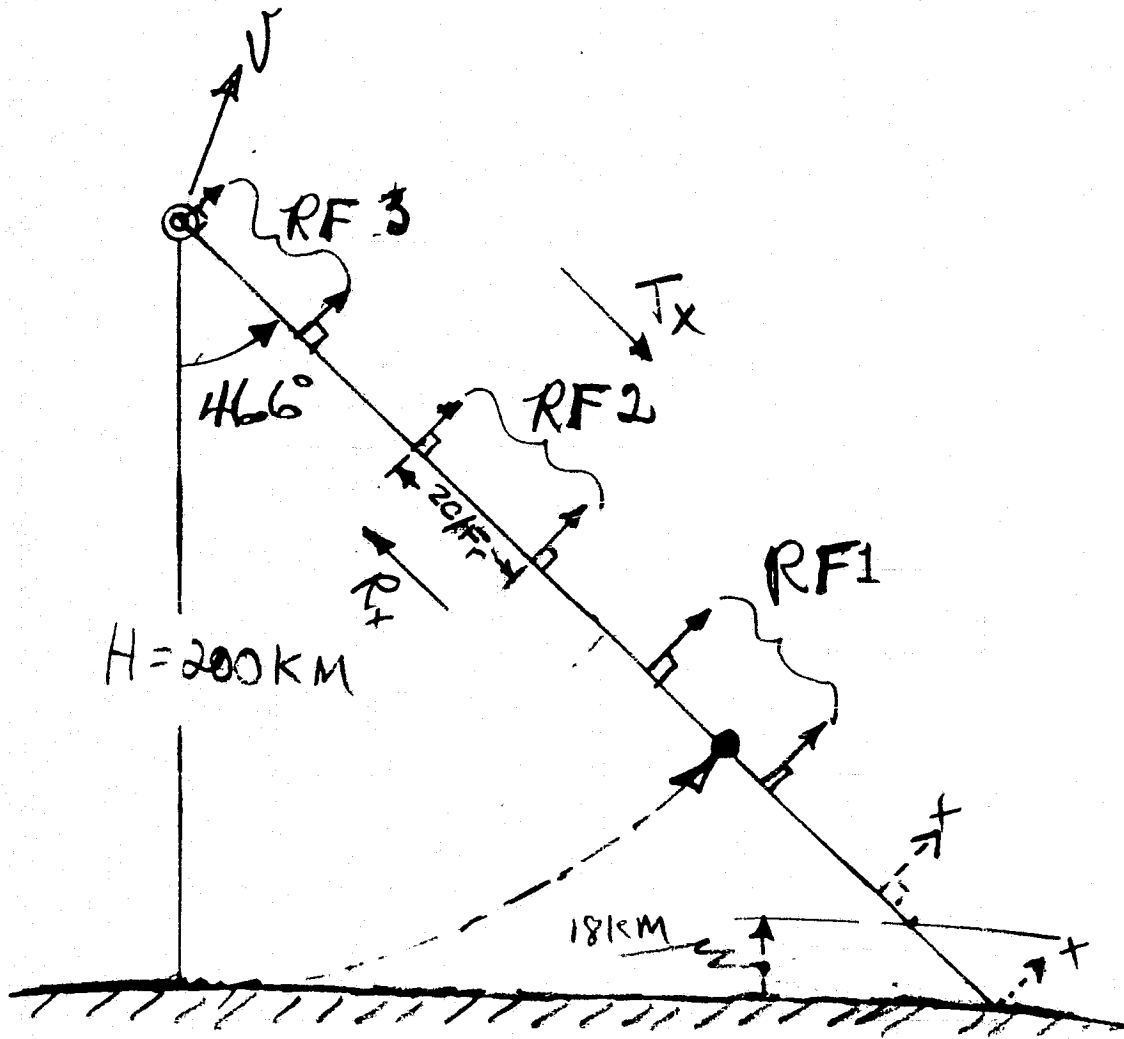


COVERAGE (H = 200 KM)

	PRINCIPLE	MODE DOPPLER
SWATH WIDTH:	170 KM	170 KM
SWATH HEIGHT:	18 KM	12 KM
NO. OF INDEPENDENT SAMPLES:	200	200
DATA (SPACE);PRECISION:	5 BITS I,Q	5 BITS I,Q
RATE:	90 MB/S	120 MB/S

BURST TIMING
PRINCIPLE MODE

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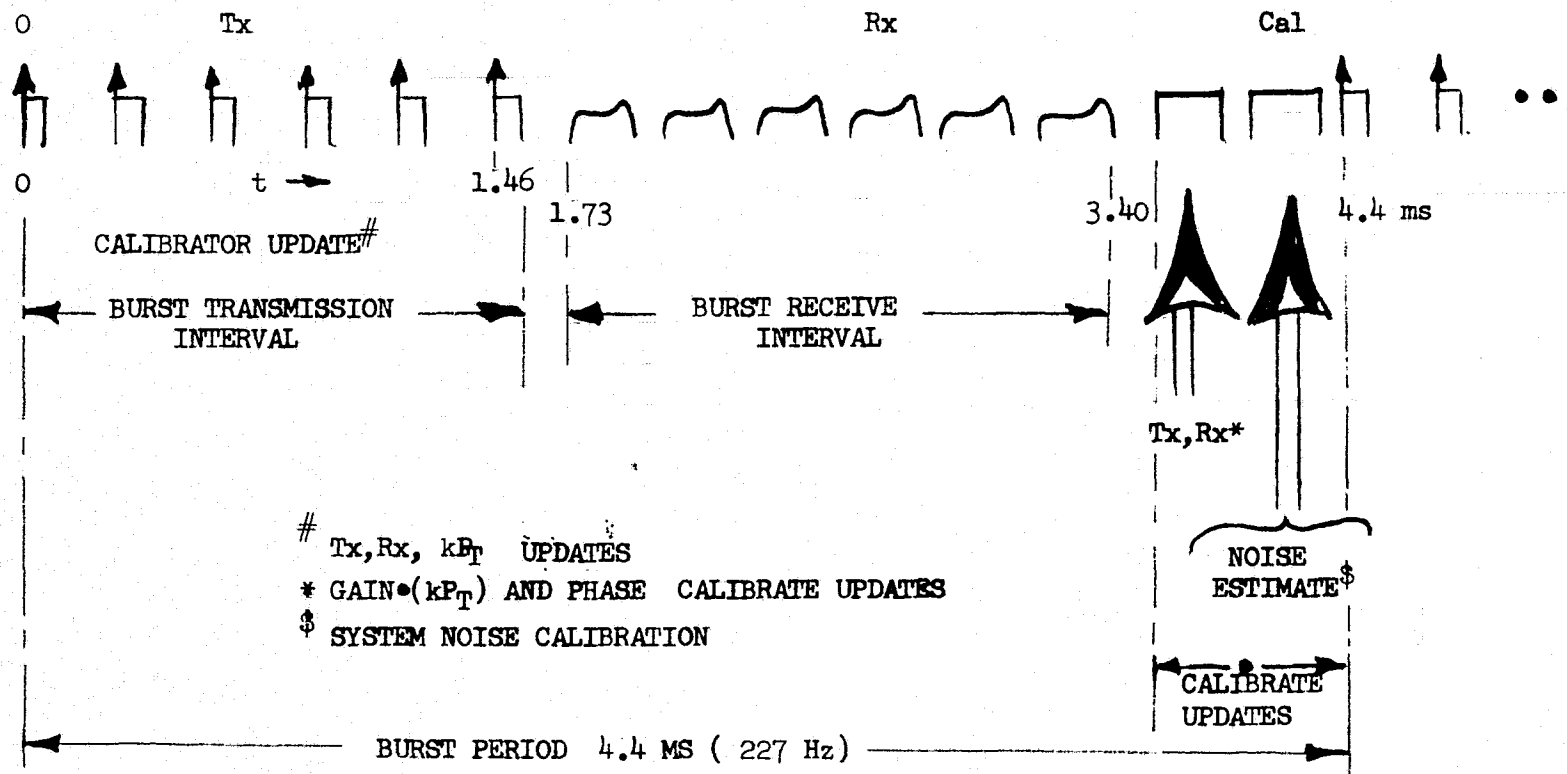


BURST TIMING

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TIME LINE; t , ms \rightarrow



SENSITIVITY TO ORBITAL VARIATION

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TRANSMISSION: RF, PRI

11 12 21 22 31 32 x x x x x x x x 11 12 etc

Next Burst

ALT.
H₀
km
↓
40-
200-
260-

H, km:

170

200

230

NADIR → 11 12 21 22 31 32

ATMOS. +
GROUND

RECEPTION: RF, PRI

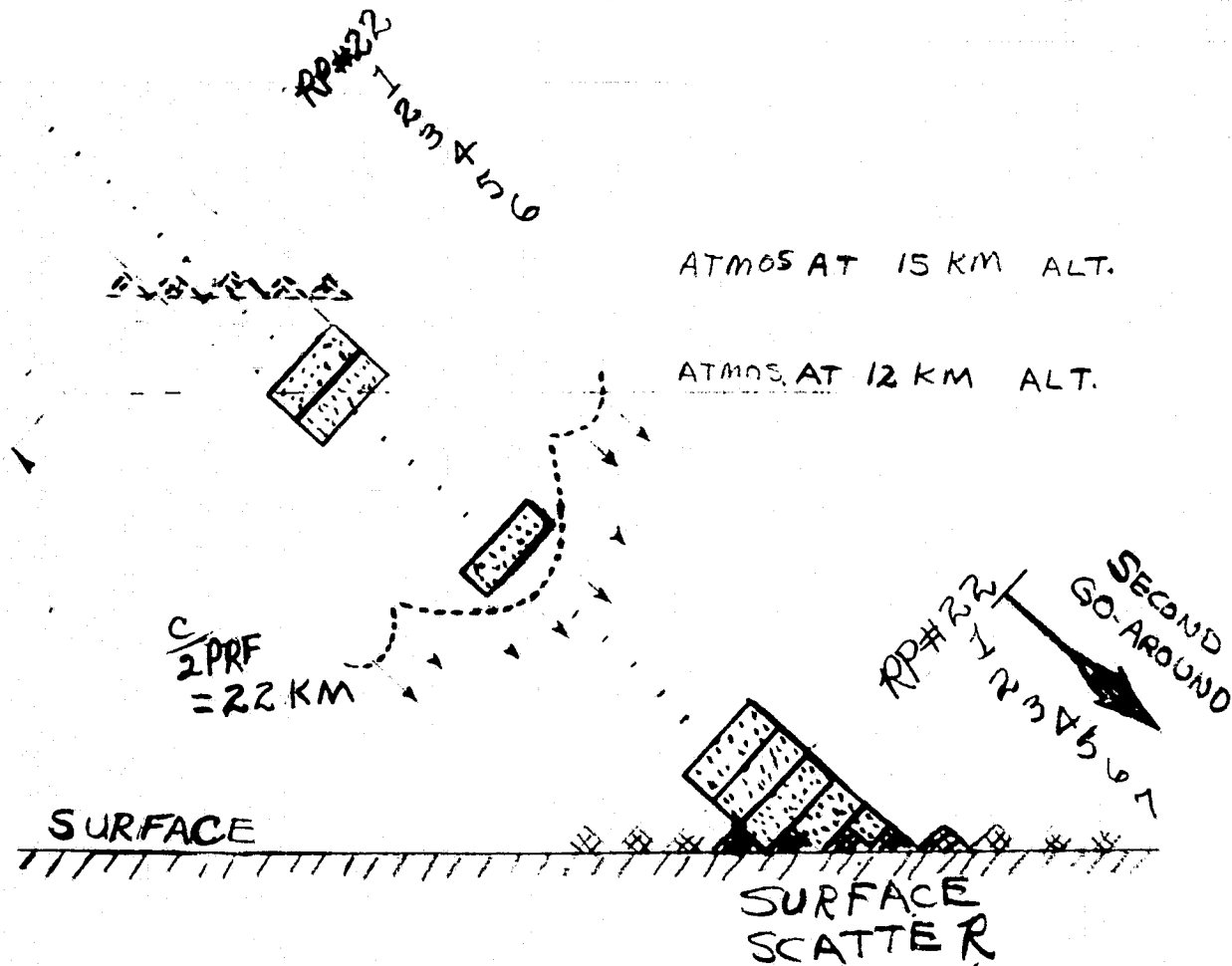
TIME, MS →

CALIBRATE

• PRF: 3410 Hz (FIXED)

ELEVATION PATTERN/RESOLUTION
SURFACE CLUTTER/SECOND GO-AROUND
DOPPLER MODE

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DATA RATES - DOPPLER MODE

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- o PER CHANNEL: 150K COMPLEX WORDS/SEC. INSTANTANEOUS.
- o AFTER 10/1 MULTIPLEXING: 1.5M REAL WORDS/SEC.
- o AFTER 4/1 MULTIPLEXING: 6M REAL WORDS/SEC.
- o AFTER A/D CONVERSION: 36M BITS/SEC.
- o AFTER BIT SELECTION: 30M BITS/SEC.
- o RATE INTO BUFFER/FORMATTER: 300 M BITS/SEC.
- o RATE INTO RECORDER: 120 M BITS/SEC.

MAJOR SYSTEM DESIGN DECISIONS



- o GROUND PROCESSING
- o AGC FOR FIXED P_T . GAIN PRODUCT
- o CALIBRATION/AGC APPROACH
- o BURST MODE
- o X-BAND
- o TIME MULTIPLEXING
- o NO RF AMPLIFICATION
- o ANTENNA ATTITUDE STABILIZATION

ADVANTAGES OF GROUND PROCESSING

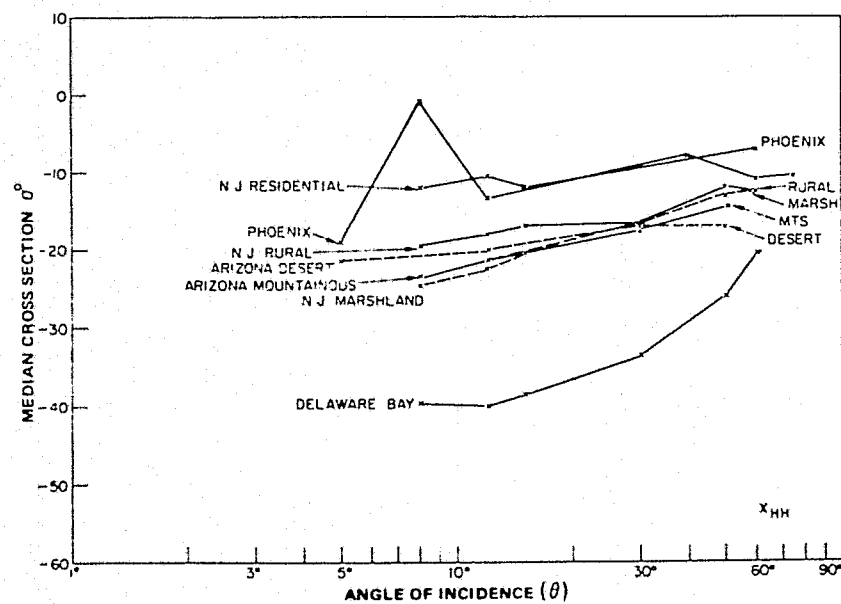


- o MAINTAINS DATA INTEGRITY
- o LESS COSTLY THAN SPACE PROCESSING
- o PROVIDES FLEXIBILITY - COMPARISON OF ALTERNATIVE APPROACHES AND ALGORITHMS
- o DATA RATES COMPATIBLE WITH RECORDER CAPABILITY
- o SAVES POWER (1 K WATT)

MEDIAN TERRAIN σ_0 AT X-BAND

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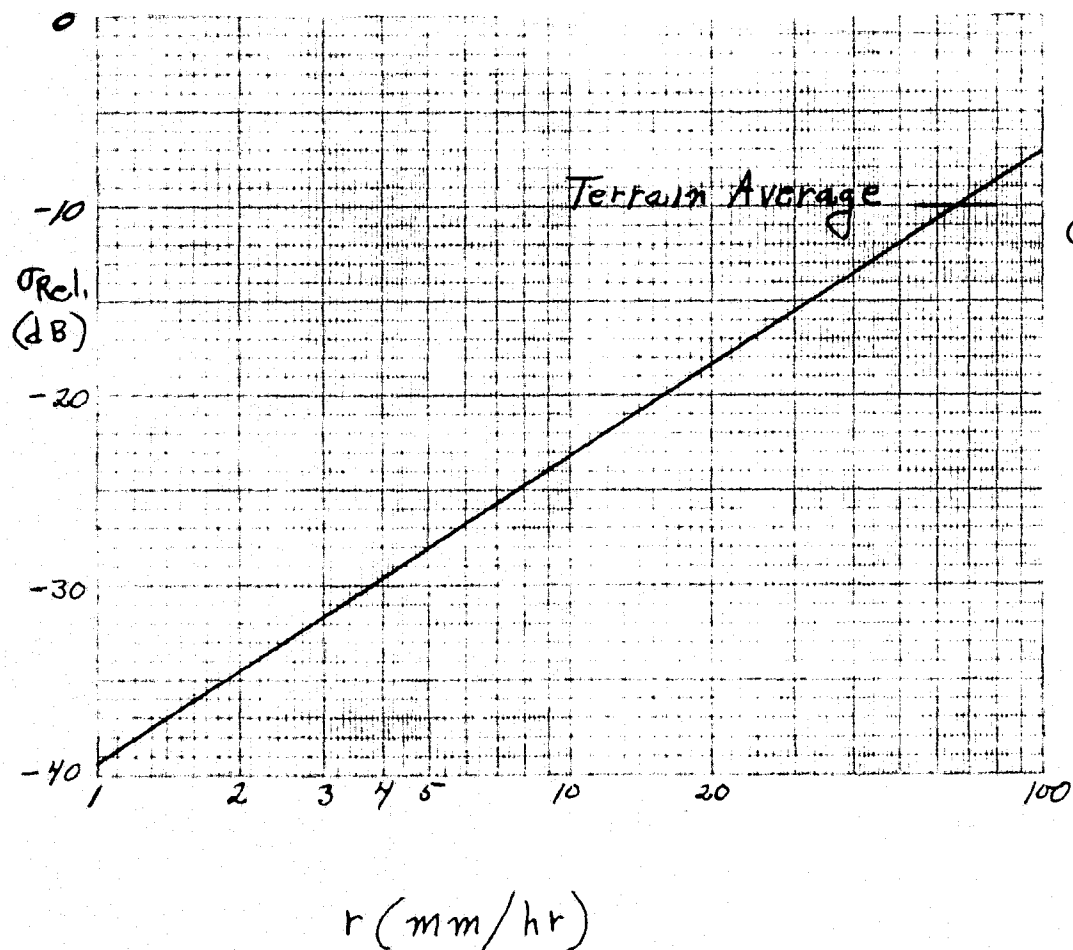
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ATMOSPHERIC RETURN RELATIVE TO GROUND RETURN

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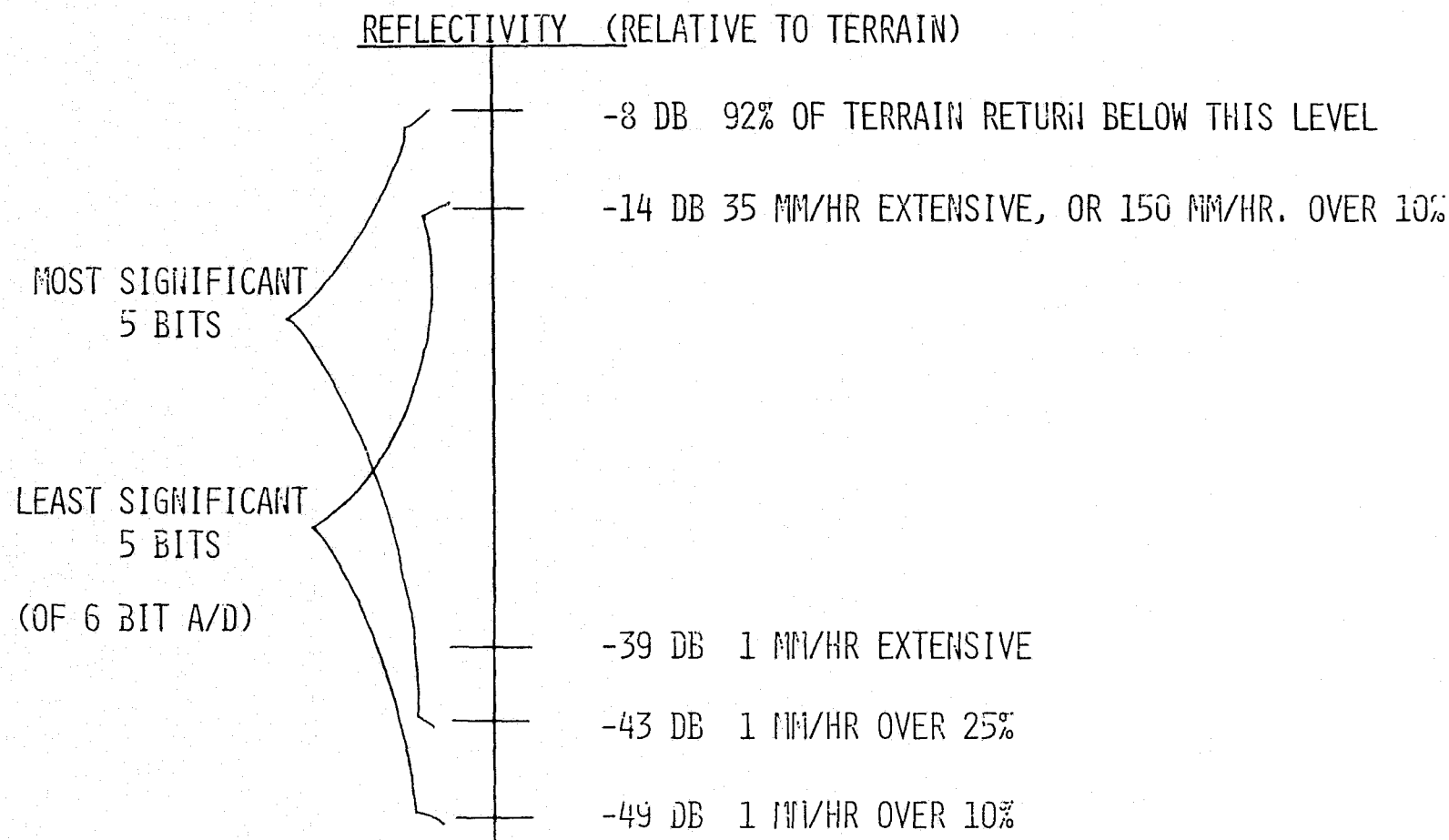
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$$\sigma_{Rel.} = \frac{2 d_r 10^{-18} \pi^5 (.93) 200 r^{1.6}}{\lambda^4}$$

$$\lambda = .03 M, d_r = 10^3 M.$$

DYNAMIC RANGE REQUIREMENTS



AGC CONCLUSION



- o AGC FOR FIXED SYSTEM GAIN (FIXED P_T . GAIN PRODUCT)
- o USE 6 BIT A/D CONVERTER
- o RECORD LEAST SIGNIFICANT 5 BITS FOR ATMOSPHERIC RETURN
- o RECORD MOST SIGNIFICANT 5 BITS FOR GROUND RETURN

o CALIBRATION REQUIREMENT: SET P_T . GAIN PRODUCT TO SELECTED VALUE

- DERIVE PILOT SIGNAL PROPORTIONAL TO TRANSMITTED POWER P_T
- INJECT PILOT SIGNALS INTO RECEIVERS FOR CALIBRATION
- AGC EACH RECEIVER FOR SELECTED OUTPUT DURING CALIBRATION

AND

o USE INJECTED PILOT SIGNALS TO SATISFY REQUIREMENT FOR PHASE CALIBRATION

BURST MODE



- o SIMPLER THAN CONTINUOUS OPERATION.
 - NO TRANSMITTER ECLOPSING IN ATMOSPHERE
 - PRF CAN BE FIXED
- o REQUIRES LESS TRANSMITTED POWER (DOPPLER MODE)
- o PROVIDES REQUIRED NUMBER OF INDEPENDENT LOOKS
- o ALLOWS GREATER FLEXIBILITY IN CHOICE OF PRF FOR DOPPLER AMBIGUITY/
ATMOSPHERE AMBIGUITY TRADE-OFF.

X-BAND

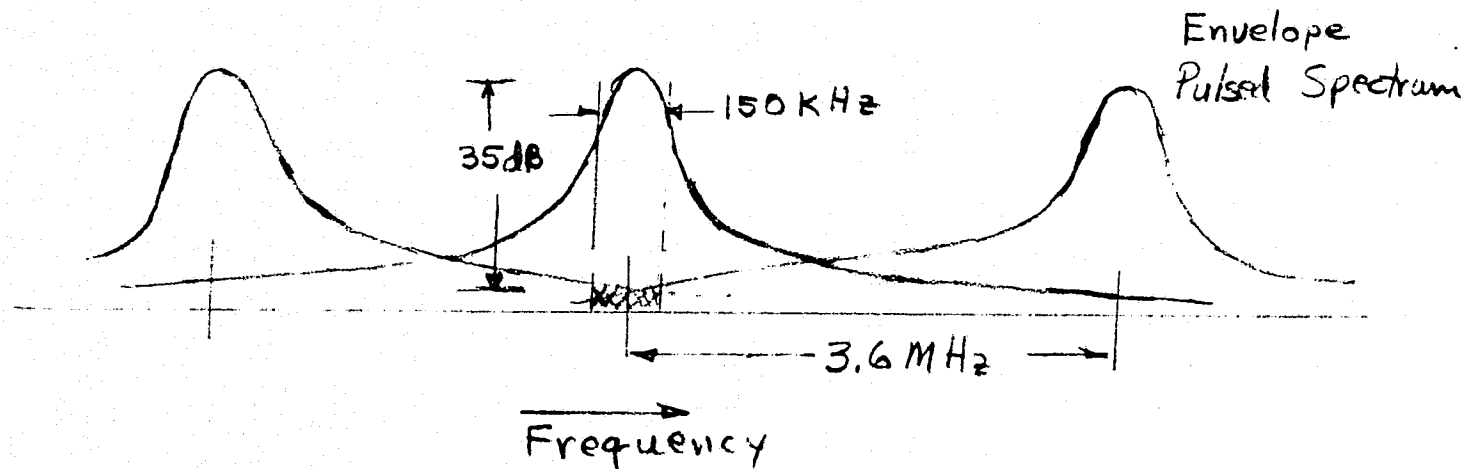


- o LOWER FREQUENCY SACRIFICES RESOLUTION AND SENSITIVITY.
- o HIGHER FREQUENCY CARRIES MAJOR COST PENALTY.

FREQUENCY MULTIPLEX ALIASING

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- ALLOWABLE CROSS-TALK POWER \leq -35 DB
- FREQUENCY SEPARATION IMPLIES:
 - A) HIGH DATA RATE ($\sim 24 \times$ NYQUIST)
 - OR
 - B) DE-MUX TO INDIVIDUAL I/Q CHANNELS

TIME MULTIPLEXING



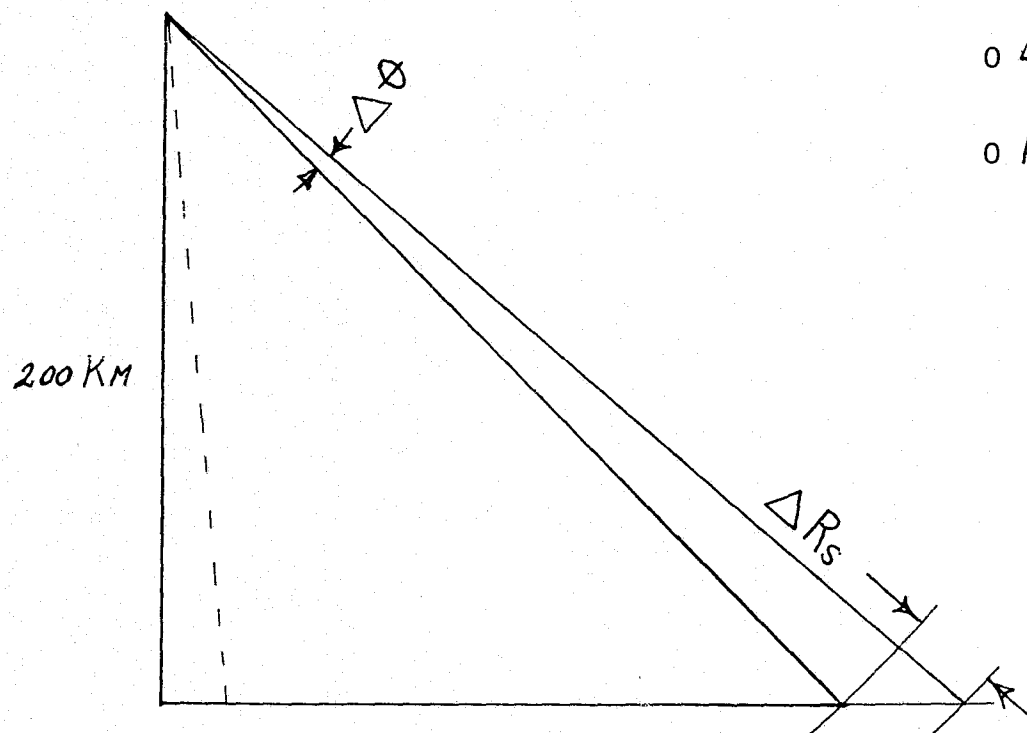
- o FREQUENCY MULTIPLEXING REQUIRES LARGE FREQUENCY SEPARATION TO REDUCE CROSS-TALK CAUSED BY ALIASING.
- o SEPARATION LEADS TO LARGE INCREASE IN DATA RATE.
- o CONCLUSION - USE TIME MULTIPLEXING.

ANTENNA ATTITUDE STABILIZATION

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- o DEVIATION OF ANTENNA AXIS FROM VERTICAL CAUSES GROUND CLUTTER CONTAMINATION OF ATMOSPHERE RETURN.



- o $\Delta R_s = 5 \text{ KM/DEGREE}$

- o ATTITUDE STABILIZATION APPROACH:
SENSE ΔR_s DIRECTLY, AND CONTROL
 $\Delta \theta$ TO NULL ΔR_s .

RF AMPLIFICATION CHOICE



	RF AMPLIFIERS	NO RF AMPLIFIERS
ADVANTAGES	<p>LOWER NOISE FIGURE (4 dB)</p> <p>REQUIRES LESS TRANS- MITTER POWER.</p>	<p>SIMPLER, LIGHTER, CHEAPER</p>
DISADVANTAGES	<p>GREATER WEIGHT, COMPLEXITY, COST.</p>	<p>HIGHER NOISE FIGURE (8 dB). REQUIRES 4 dB MORE TRANSMITTER POWER.</p>

CHOICE: NO RF AMPLIFICATION.

RECEIVER SYSTEM APPROACH TRADE-OFFS



		BEAM FORMATION	
		AT I.F. OR AT R.F.	AFTER A/D CONVERSION
MULTIPLEXING	TIME	LACK OF FLEXIBILITY IN GAIN AND PHASE BALANCE AND ARRAY WEIGHTING	FLEXIBLE. MODERATE BANDWIDTH (278 M BITS/SEC) BEFORE BUFFERING.
	FREQUENCY		FLEXIBLE. EXCESSIVE BANDWIDTH (6.7 G BITS/SEC.) REQUIRED TO REDUCE CROSSTALK.

TOPICS:

PARAMETERS

CALIBRATION ERROR BUDGET

RF LOSS BUDGET

SIGNAL-TO-NOISE RATIO VS. RAINFALL RATE

SEVERE STORM, TOTAL NOISE BUDGET

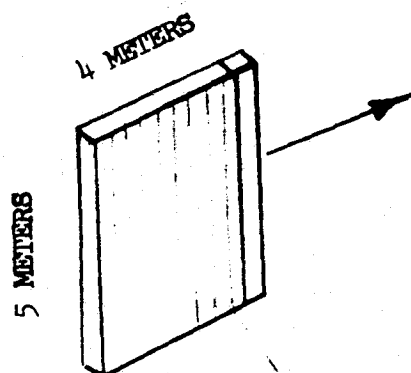
ESTIMATION BIAS

DOPPLER MODE HEIGHT LIMITS

MEASUREMENT ACCURACY

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PERFORMANCE

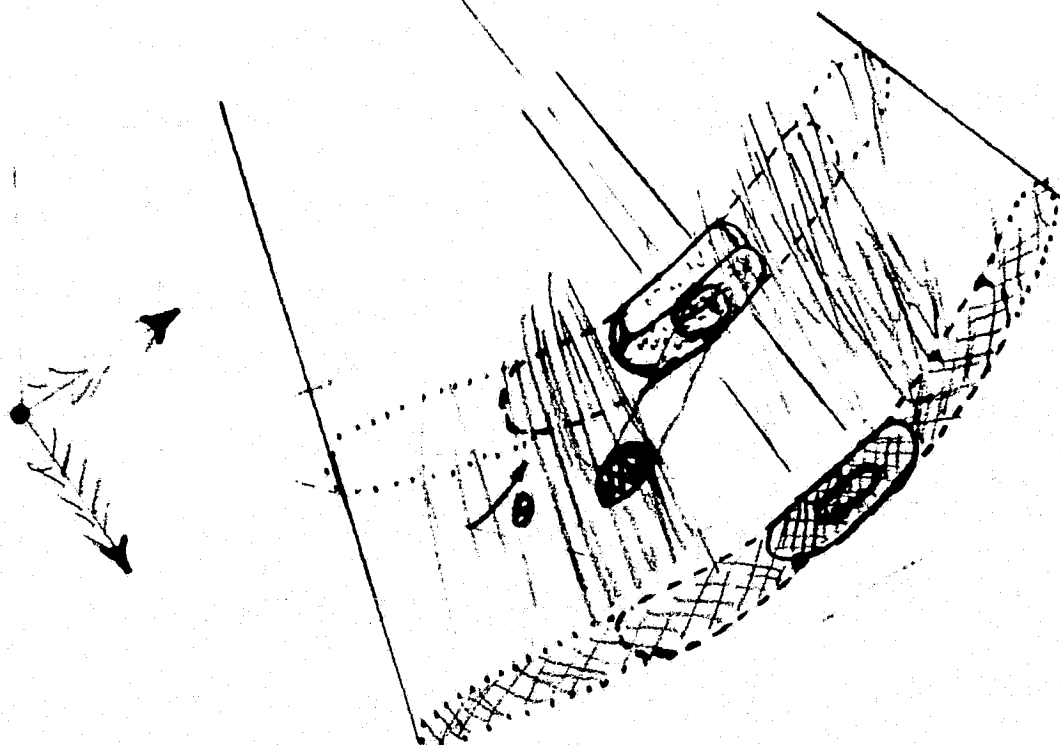
GEOMETRY

SEVERE STORM MODEL:

RESOLUTION CELL EMBEDDED IN UNIFORM
RAINFALL AT 4MM/HR, SURROUNDED BY HEAVY
RAINFALL AT 20 MM/HR WITH LAND SURFACE
CLUTTER REFLECTIVITIES OF $\sigma_0 = 0$ dB (FIRST
SIDE LOBE) AND -10 dB RMS

200 ± 30 KM

46.6°



PERFORMANCE PARAMETERS (1)



NOMINAL ORBIT ALTITUDE:	200 KM
PRINCIPLE MODE:	REAL APERTURE
SWATH: WIDTH =	170 KM
HEIGHT =	18 KM
SPATIAL RESOLUTION:	3 x 3 x 1.5 KM
NO. OF INDEPENDENT SAMPLES:	200
CALIBRATION ACCURACY*:	1.2 DB, 80% CONFIDENCE
STORM MODEL:	SEVERE, 20 MM/HR OVER 30 KM DISTANCE
CELL-OF-INTEREST:	4 MM/HR
MEASUREMENT ACCURACY*:	1.6 DB, 80% CONFIDENCE

* BIAS CONTRIBUTION CONSIDERED SEPARATELY

PERFORMANCE PARAMETERS (2)

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RECEIVERS:

NOISE FIGURES:

10 DB MAXIMUM; 8 DB TYPICAL

INTERCHANNEL ISOLATION:

35 DB NET RMS

ANTENNAS (TRANSMIT & RECEIVE):

APERTURE EFFICIENCY:

80%, MINIMUM

LOSSES:

1.2 DB OHMIC, MAXIMUM

ELEVATION SIDELOBES:

-25 DB PEAK

GRATING LOBES:

-25 DB PEAK

PRINCIPLE MODE BEAMS:

AZIMUTH SIDELOBES:

-35 DB RMS, MAXIMUM

GRATING LOBES:

-25 DB PEAK, -35 DB RMS

OFF-AXIS LOBES:

-65 DB (TWO-WAY), RMS

CALIBRATION ERROR BUDGET

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PARAMETER	COMPONENT*	
	FIXED	TEMPORAL
TRANSMITTER/RECEIVER	.3 DB	.3 DB
ANTENNA FACTORS, RSS	.6	.3
RF PLUMBING	.2	.1
SYSTEM NOISE ESTIMATE	-	.05
RSS	.70 DB	.44 DB

* RMS (1 SIGMA) ERRORS, FIXED ERRORS ARE ATTRIBUTED
TO SAMPLE (ONE) FROM ENSEMBLE OF SYSTEMS

MRF RF LOSS BUDGET

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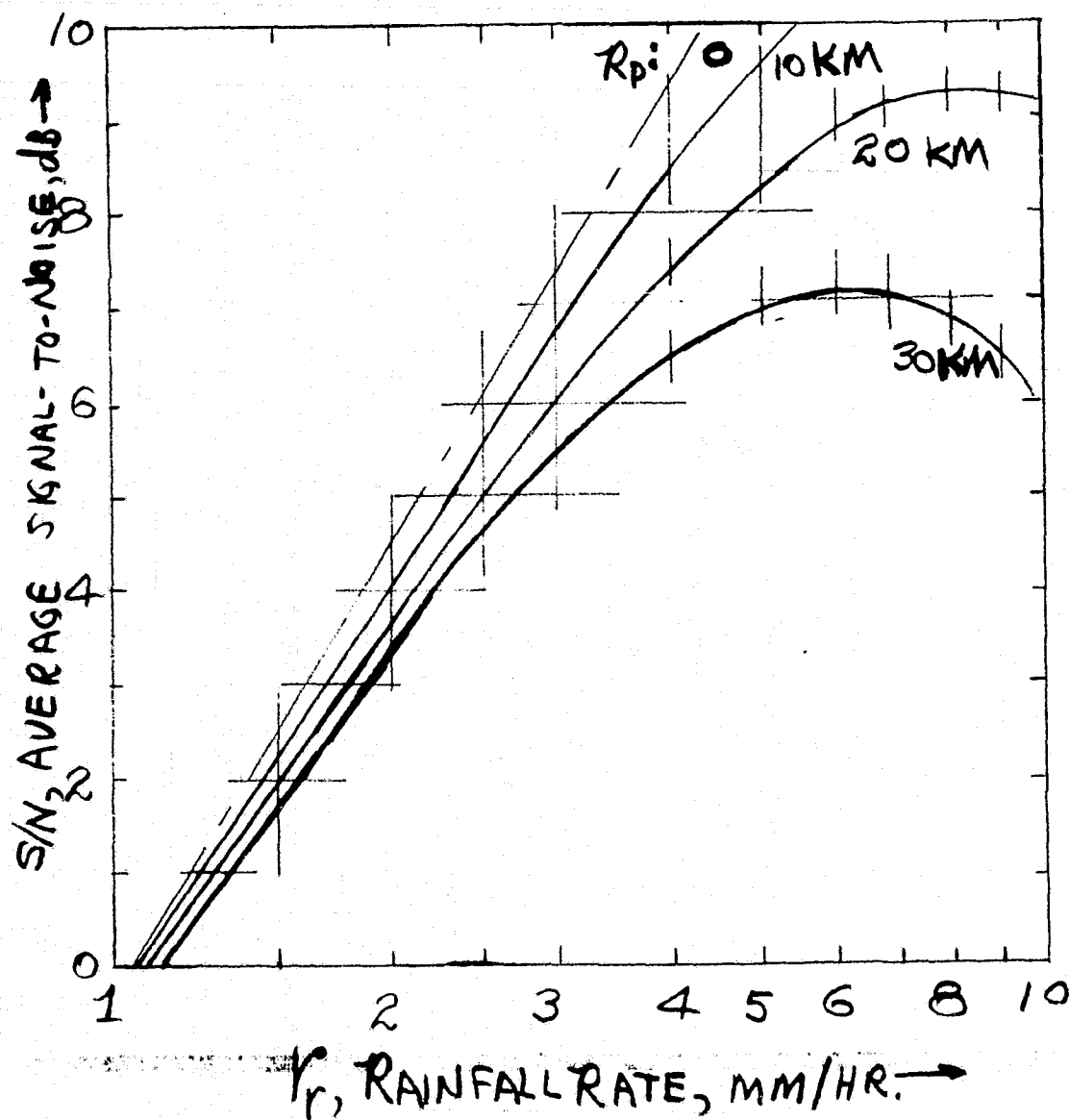
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RECEIVER NOISE FIGURE, MAX	10 DB
ANTENNA OHMIC LOSSES (TWO-WAY)	2 DB
RF COUPLING LOSSES, MAX	
TRANSMIT	1.0 DB
RECEIVE	1.8 DB
PROPAGATION LOSSES, TYPICAL	.3 DB
A/D CONVERTER & MISC.	.9 DB
	<hr/>
TOTAL	16.0 DB

SINGLE PULSE SIGNAL-TO-NOISE RATIO
VS. RAINFALL RATE

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$$\frac{S}{N} = \frac{P_T \lambda^2 G_T G_R (\Omega_R R^2 d_r) \eta_r}{(4\pi)^3 R^4 KTB} \cdot \frac{L_T L_R L_p}{F}$$

WHERE:

$$G_R \Omega_R = \frac{4\pi P_R}{\Omega_R} \Omega_R$$

 $\Omega_R R^2 d_r \eta_r$: RADAR CROSS-SECTION OF ISOTROPIC RAIN BACKSCATTER

$$\eta_r = \frac{\pi^5 |K|^2 \cdot 10^{-18}}{\lambda^4} Z_e; Z_e \rightarrow 200 r^{1.6}, r: \text{RAIN RATE, MM/HR}$$

$$\bullet \frac{S}{N} = P_T \cdot \left(\frac{\lambda}{4\pi R} \right)^2 \cdot \frac{d_r \eta_r}{KTB} \cdot \frac{P_R G_T L_T L_R L_p}{F} = \boxed{8.4 \text{ dB}}$$

$$P_T = 8 \text{ KW}; d_r \eta_r = -32 \text{ dBz} (d_r = 1 \text{ KM}); B = 200 \text{ KHz}$$

$$G_T = 29 \text{ dB}; P_R = .86; \frac{L_T L_R L_p}{F} = -16 \text{ dB}$$

TOTAL NOISE BUDGET
SEVERE STORM MODEL



SIGNAL: -32 DBZ/KM (4MM/HR) OVER CELL-OF-INTEREST
RAIN CLUTTER: -21 DBZ/KM (20 MM/HR) OUTSIDE SIGNAL CELL
SURFACE CLUTTER: (RELATIVE TO AZIMUTH SECTOR OF SIGNAL CELL):
INSIDE: $\sigma_0 = 0$ DB
OUTSIDE: $\overline{\sigma}_0 = -10$ DB

SIGNAL-TO:

THERMAL + A/D CONV. NOISE	≥ 9 DB
SURFACE CLUTTER	≥ 17 DB
RAIN CLUTTER	≥ 9 DB
<u>TOTAL NOISE</u>	≥ 5.6 DB
CLUTTER	≥ 8.5 DB

CLUTTER MODEL FOR SEVERE STORM

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<u>CLUTTER CONTRIBUTION</u>	<u>ANTENNA PATTERN REDUCTION FACTOR (DB)</u>	<u># CELLS (DB)</u>	<u>AVERAGE DBZ</u>	<u>CLUTTER CONTRIBUTION (DBZ)</u>
ELEVATION M.L., AZIMUTH S.L. (1 WAY)				
RMS	-35	+10	-21 (20MM/HR)	-46
GRATING LOBES	-25	+ 3	-21	-43
AZIMUTH M.L., ELEVATION S.L. (2 WAY)				
RMS	-60	+10	-21	-71
GRATING LOBES	-50	0	0 (GROUND CELL)	-50
AZIMUTH S.L., ELEVATION S.L.				
RMS	-65	+20	-21	-66
		+20	-10 (GROUND CELLS)	-55

CLUTTER CALCULATION FOR SEVERE STORM



GROUND CLUTTER CONTRIBUTION: - 49 dBz
RAIN CLUTTER CONTRIBUTION: - 41 dBz
TOTAL CLUTTER CONTRIBUTION: - 40.5 dBz (1.2 MM/HR)

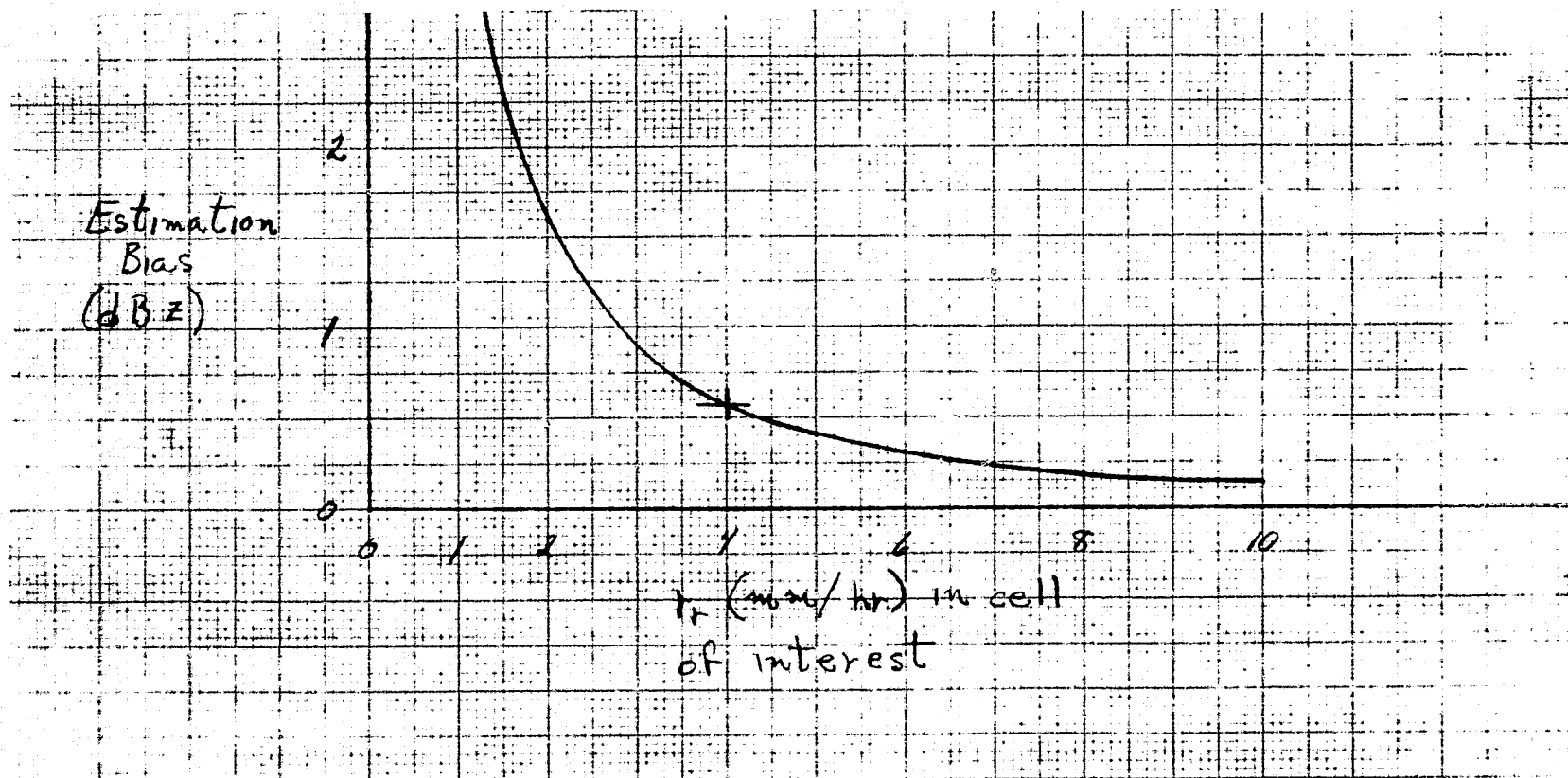
AT 4 MM/HR, S/C = 8.5 dB

ESTIMATION BIAS

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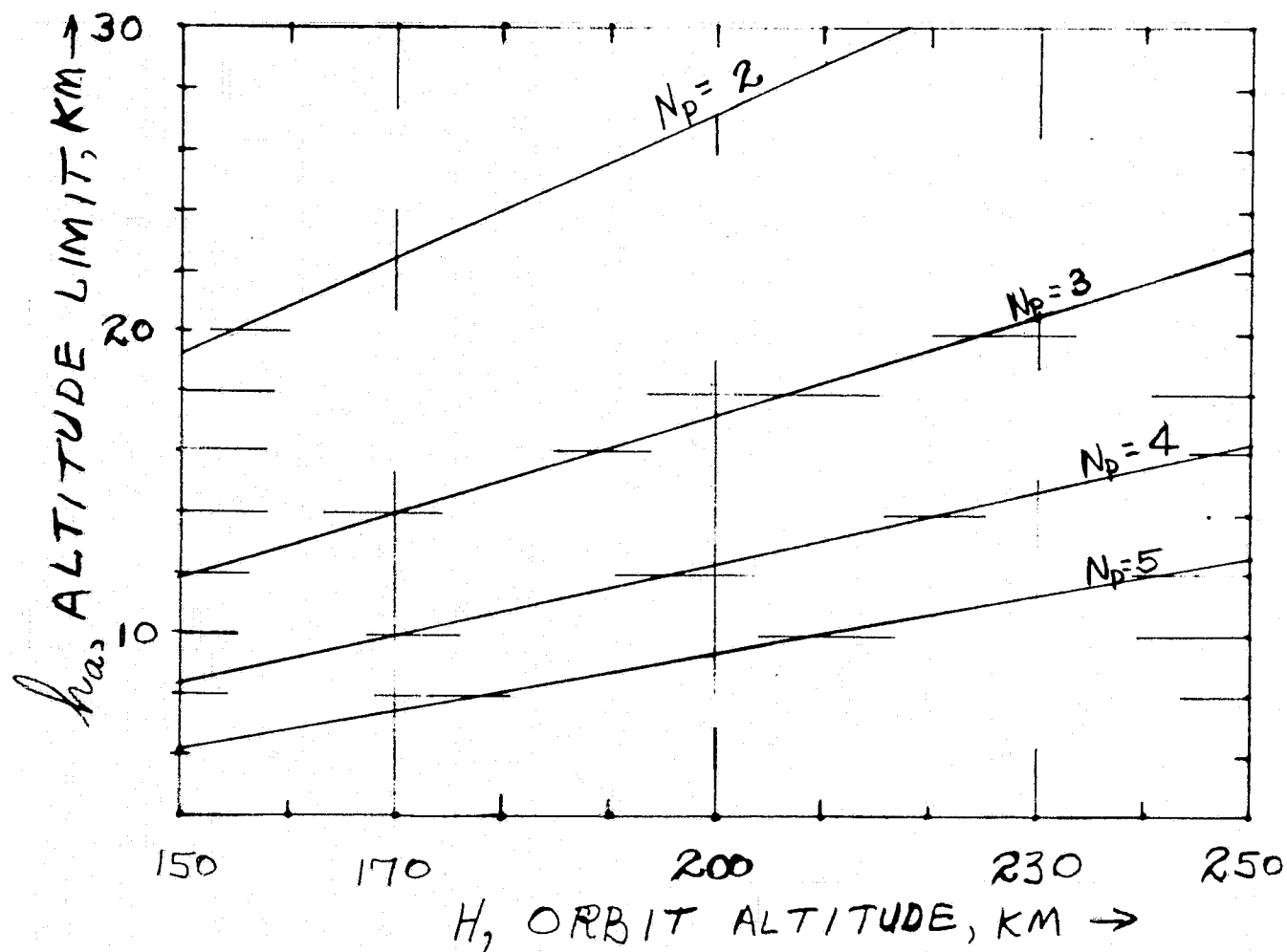
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o CAUSED BY UNCOMPENSATED CLUTTER



DOPPLER MODE
ATMOSPHERIC HEIGHT LIMITS
ORBIT ALTITUDE: 200 \pm 30 KM

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N_p = PULSES
PROCESSED PER
RF INTRA-BURST
PERIOD

NUMBER OF INDEPENDENT LOOKS M

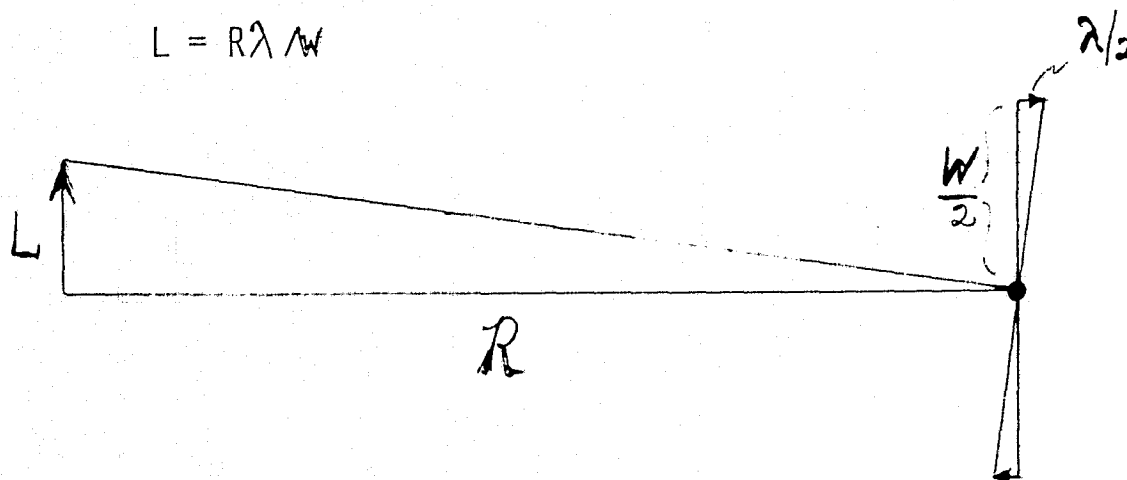


- $M = 200$ FOR ORBIT DISTANCE $D = 1.5$ KM AND:
RESOLUTION $W = 3$ KM, RANGE $R = 300$ KM
 $\lambda = .03$ M, DUTY FACTOR $F = .4$.

- $M = FD/L = FDW/R\lambda$

WHERE L IS DECORRELATION DISTANCE:

$$L = R\lambda/W$$

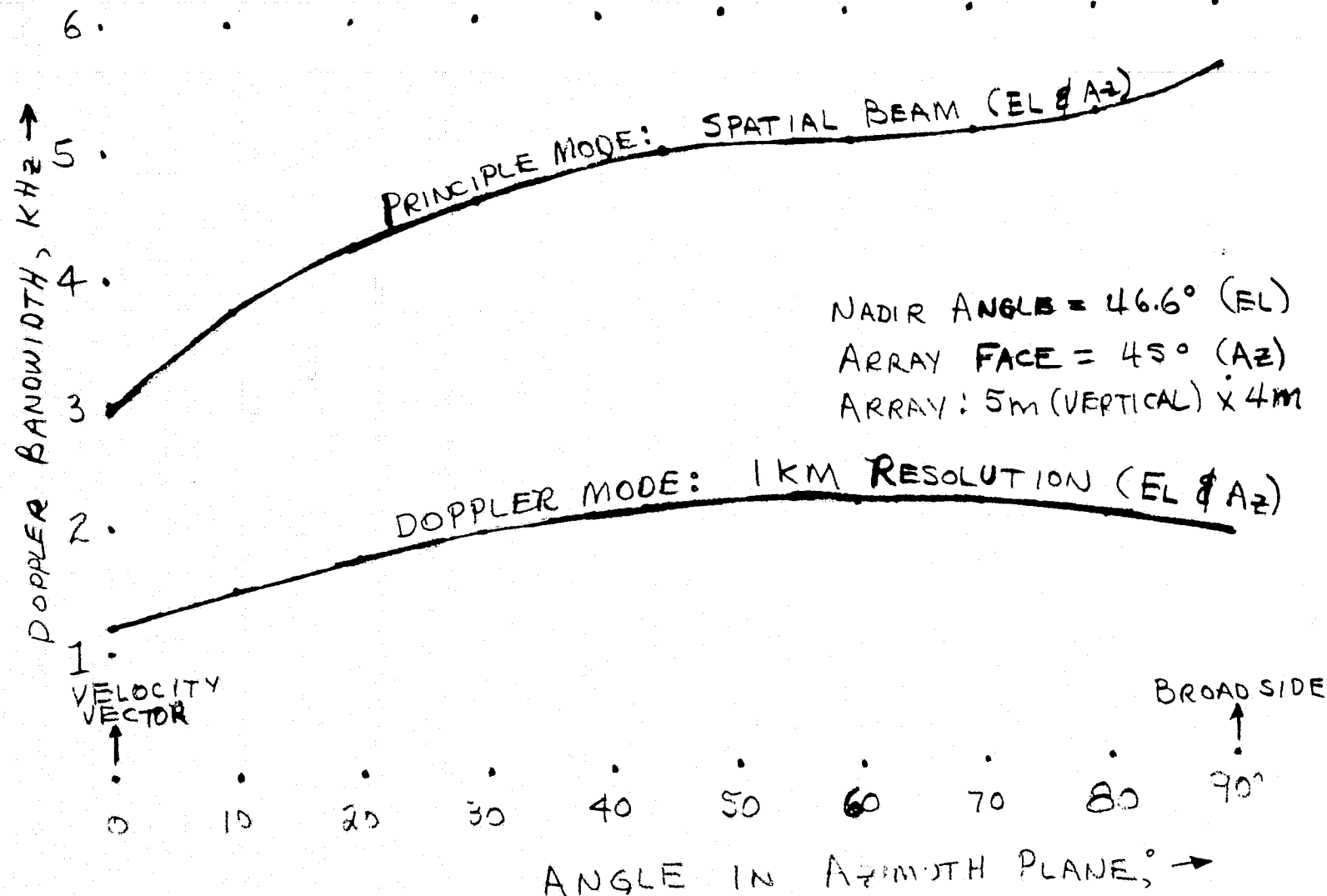


ASSUMPTIONS: NO FREQUENCY HOPPING, PRF OVERSAMPLING.

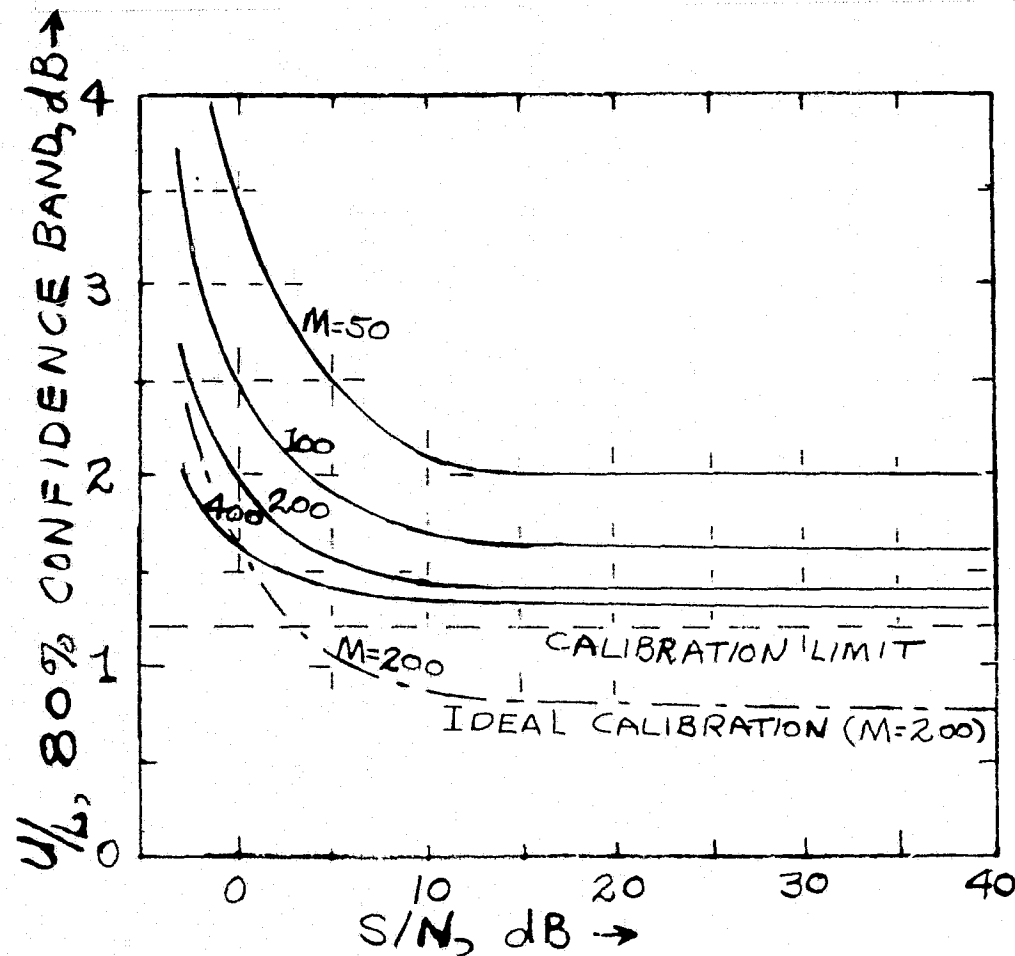
DOPPLER VS. AZIMUTH ANGLE

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MEASUREMENT ACCURACY VS. S/N & INDEPENDENT SAMPLES



$$\frac{U}{L} = \frac{1 + X_{\alpha} \sigma_N}{1 - X_{\alpha} \sigma_N}$$

$X_{\alpha} = 1.282$ FOR $\alpha = 80\%$
CONFIDENCE LEVEL

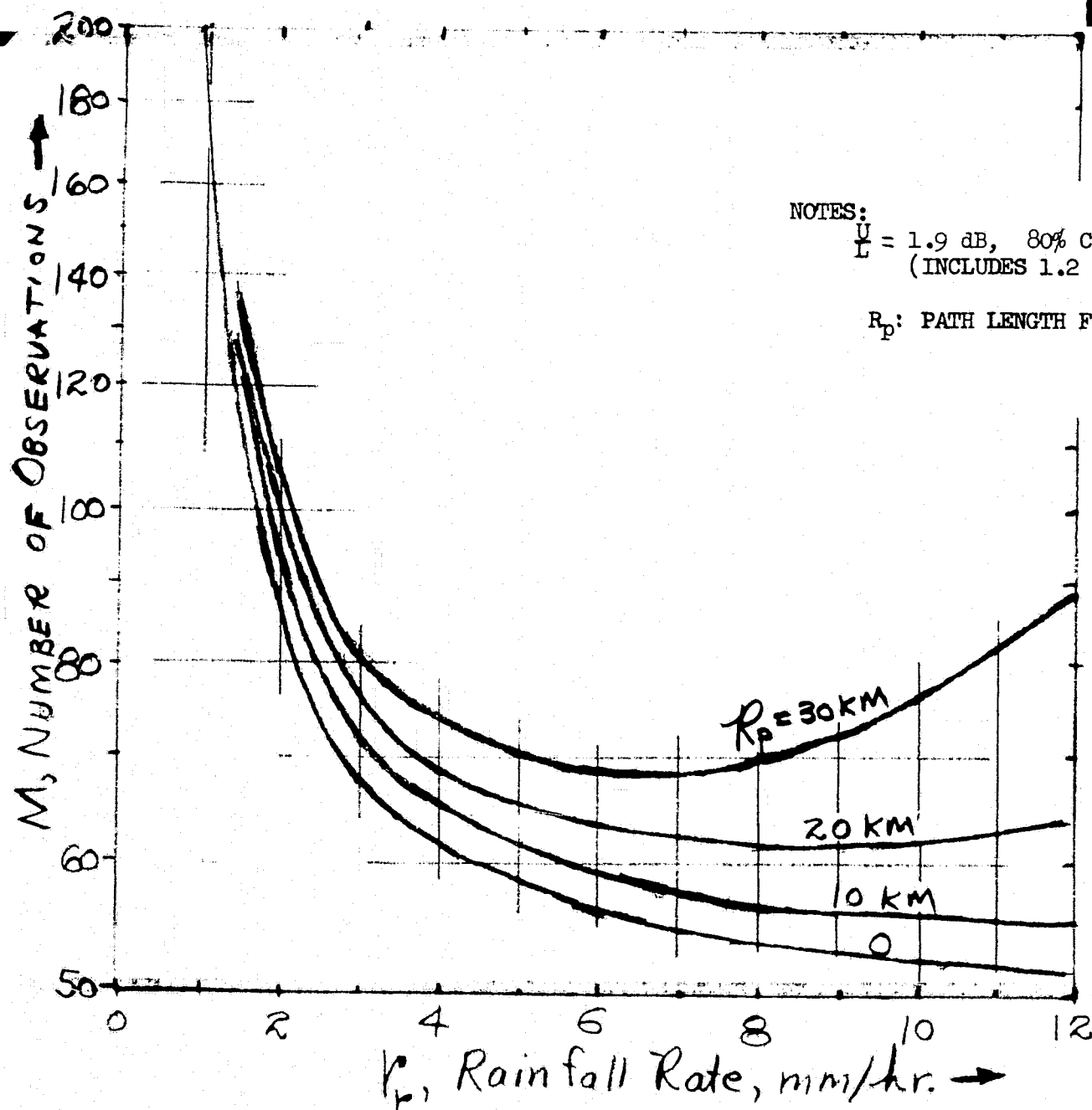
$$\sigma_N^2 = \frac{(1 + N/S)^2}{M} + \sigma_c^2$$

σ_c^2 = VARIANCE IN
CALIBRATION

OBSERVATIONS M VS. RAINFALL RATE

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NOTES:

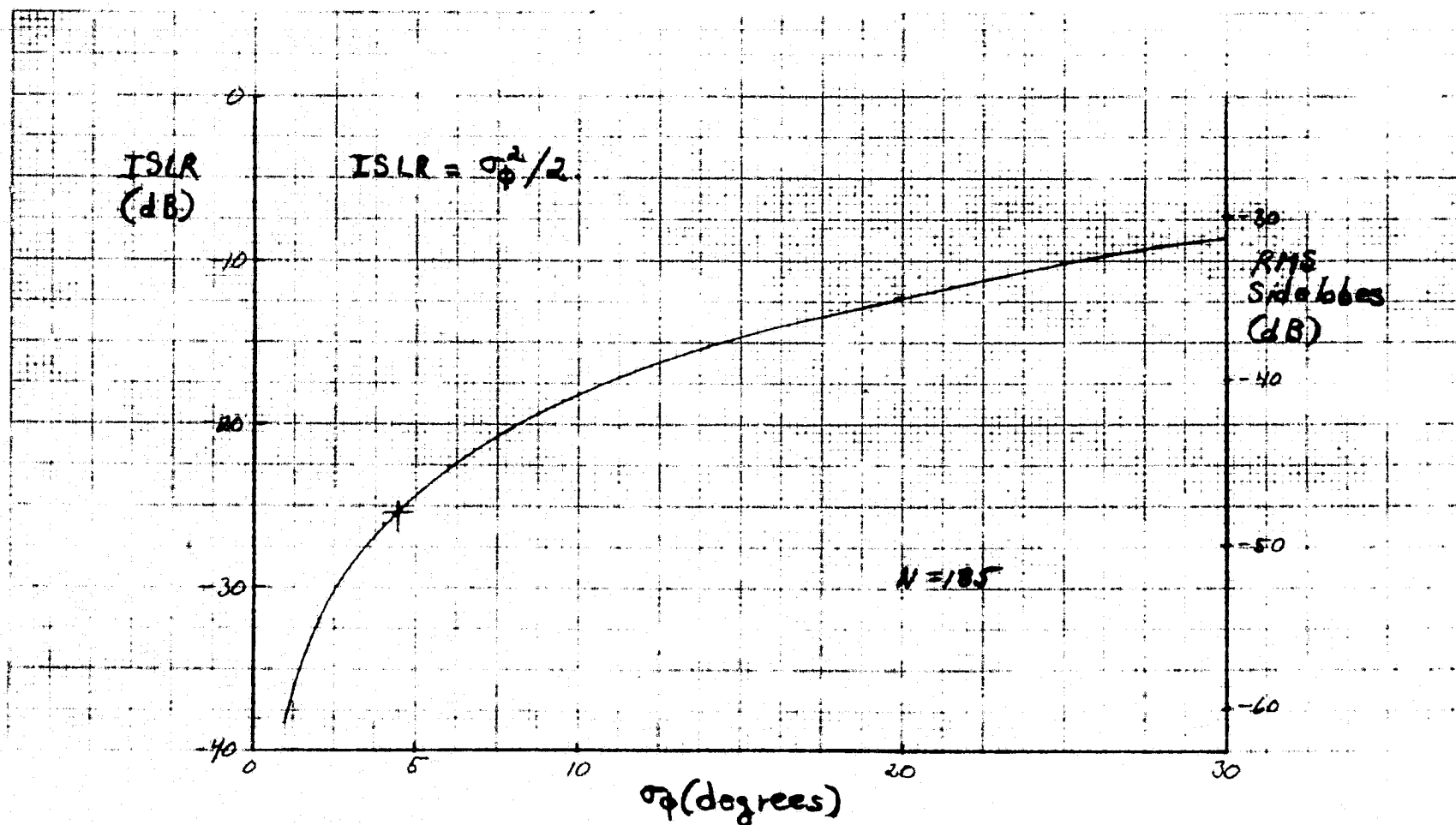
$\frac{U}{L} = 1.9$ dB, 80% CONFIDENCE BAND
(INCLUDES 1.2 dB FOR CALIBRATION)

R_p : PATH LENGTH FOR ATTENUATION @ 0.016 $r_r^{1.3}$ dB/KM

EFFECT OF PHASE ERRORS ON SIDELOBES

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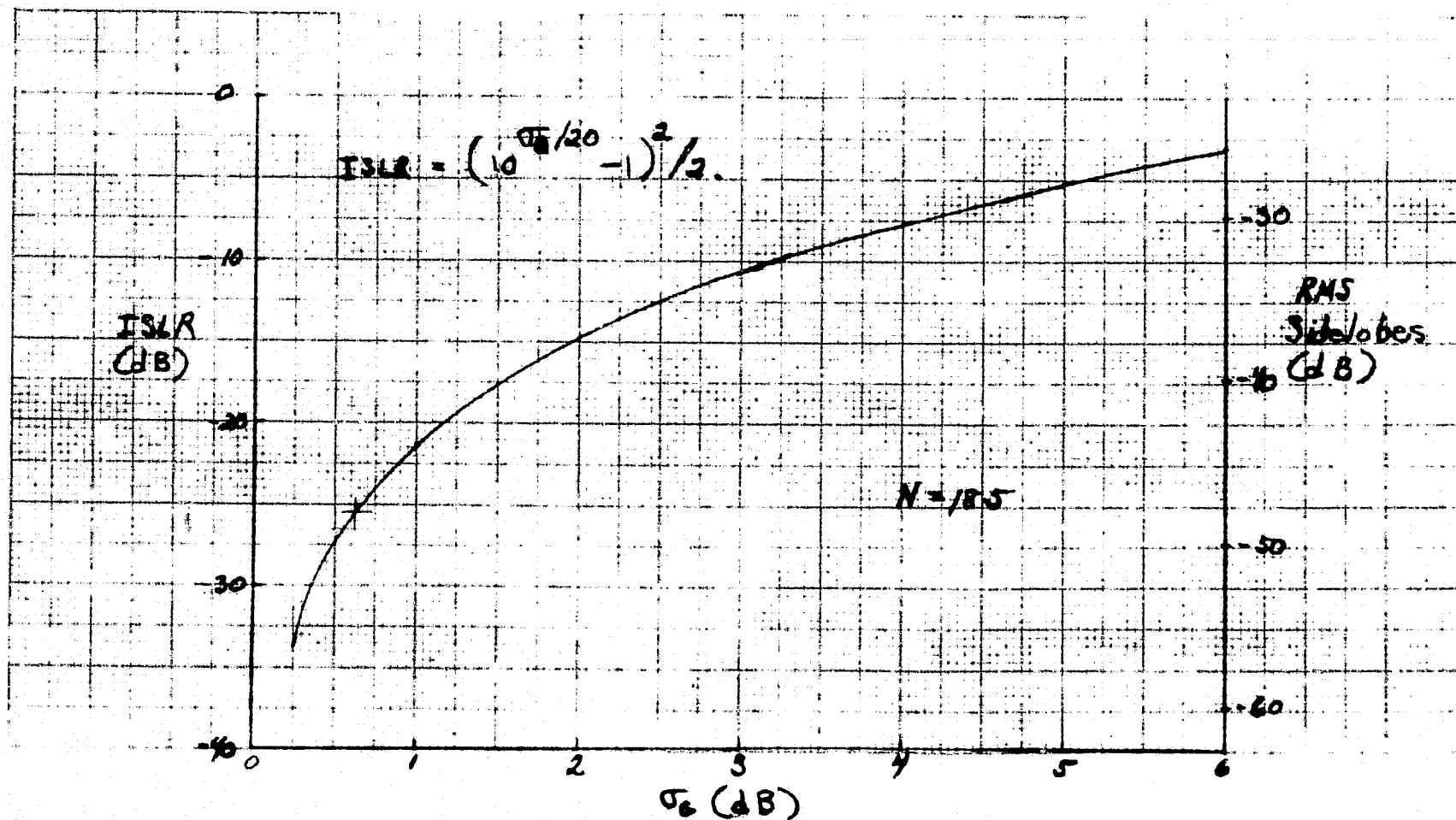
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EFFECT OF GAIN ERRORS ON SIDELOBES

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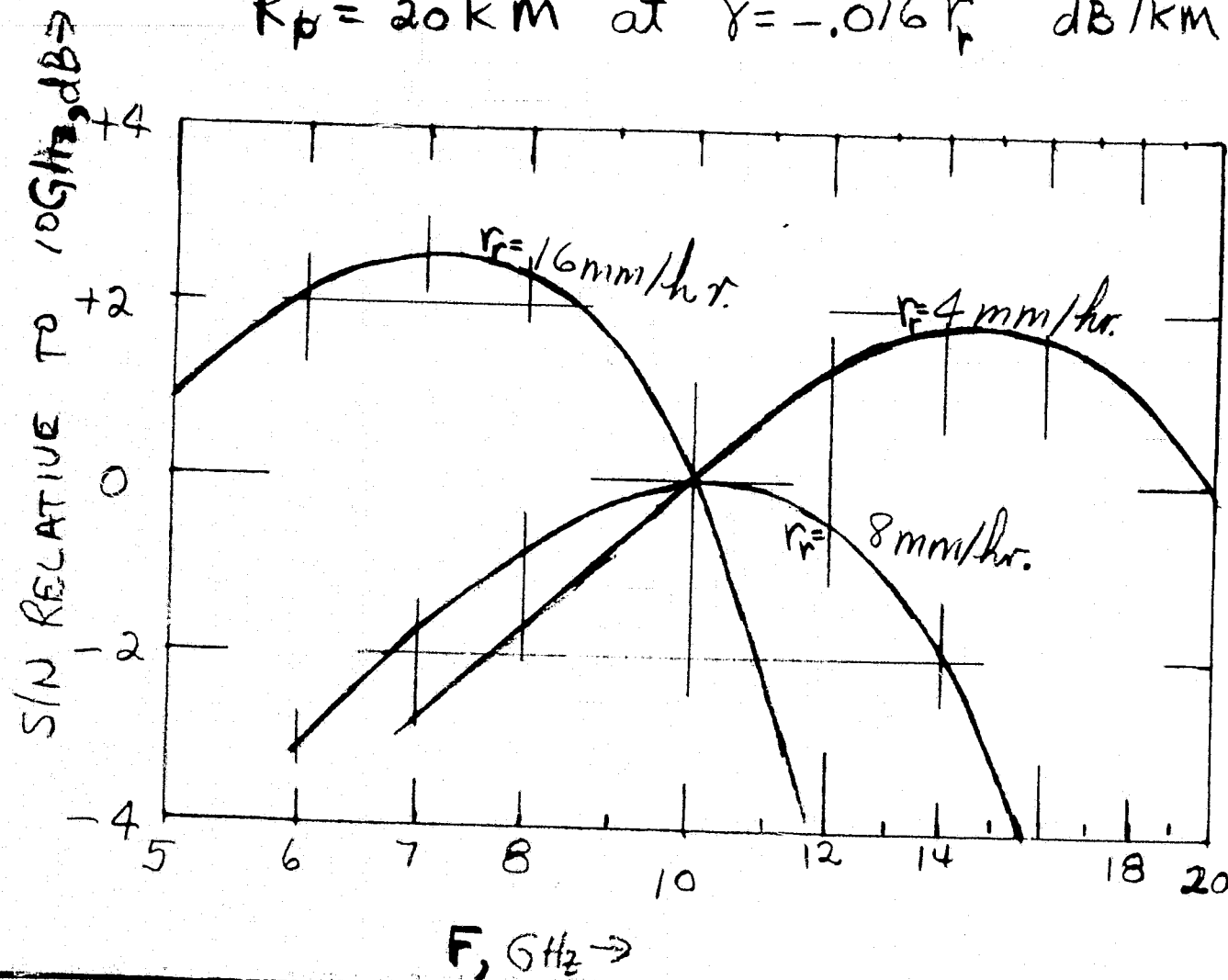


RELATIVE SENSITIVITIES VS. RF WAVELENGTH

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$$R_p = 20 \text{ km at } \gamma = -.016 r_f^{1.31} \text{ dB/km (TWO-WAY)}$$



NOTE:
CONSTANT
 TRANSMITTER
 POWER AND
 ANTENNA
 DIMENSIONS;
 (RECEIVE
 ELEMENTS $\propto F_\lambda$).

SUBSYSTEM DESCRIPTION

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- o ANTENNA

- ELECTRICAL

- THERMO-MECHANICAL

- STOWAGE & DEPLOYMENT

- o TRANSMITTER/RECEIVERS

- EXCITER

- MODULATOR

- CALIBRATION

- o PRE-PROCESSOR & RECORDER

- AGC

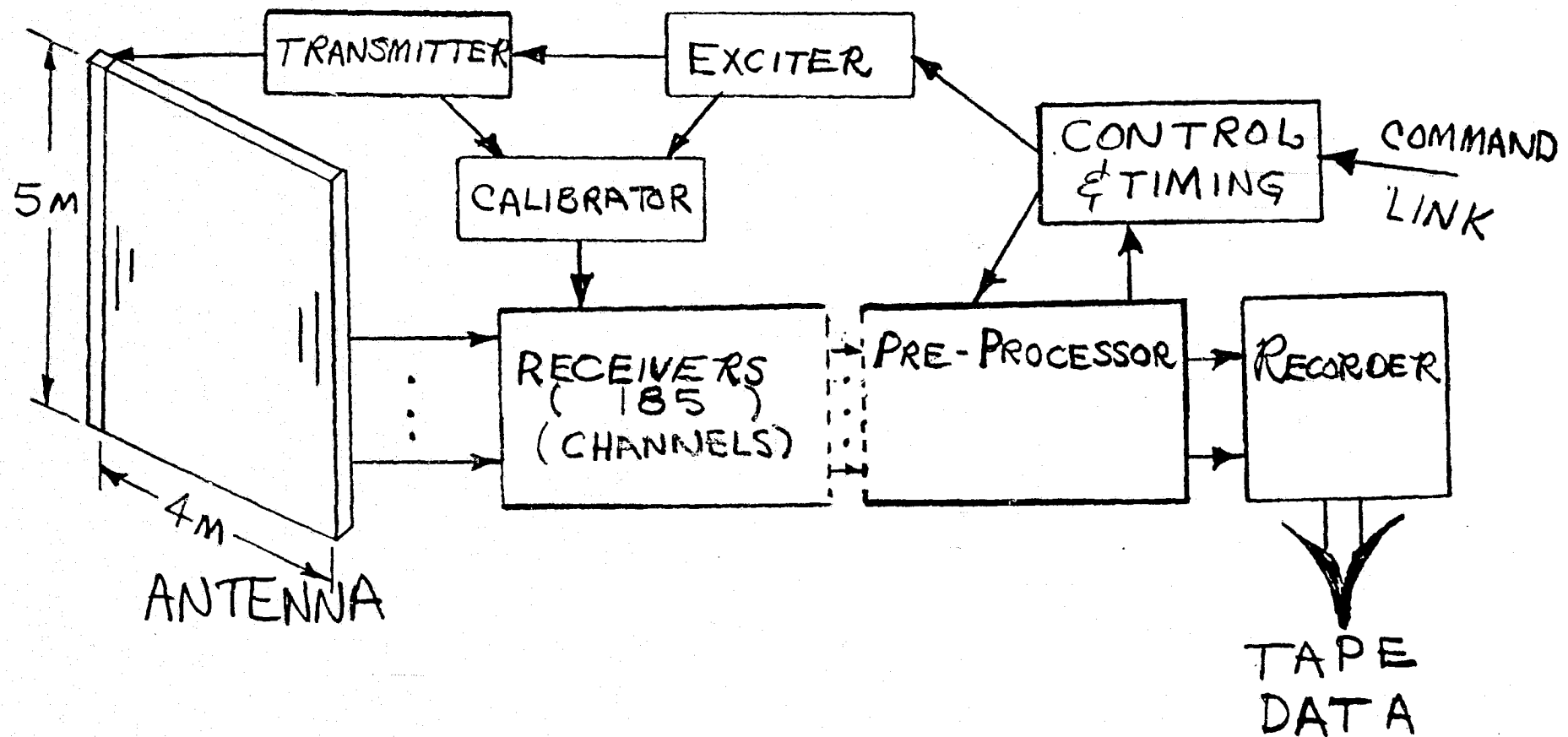
- A/D CONVERSION

- BUFFERING

SPACE SYSTEM ELEMENTS

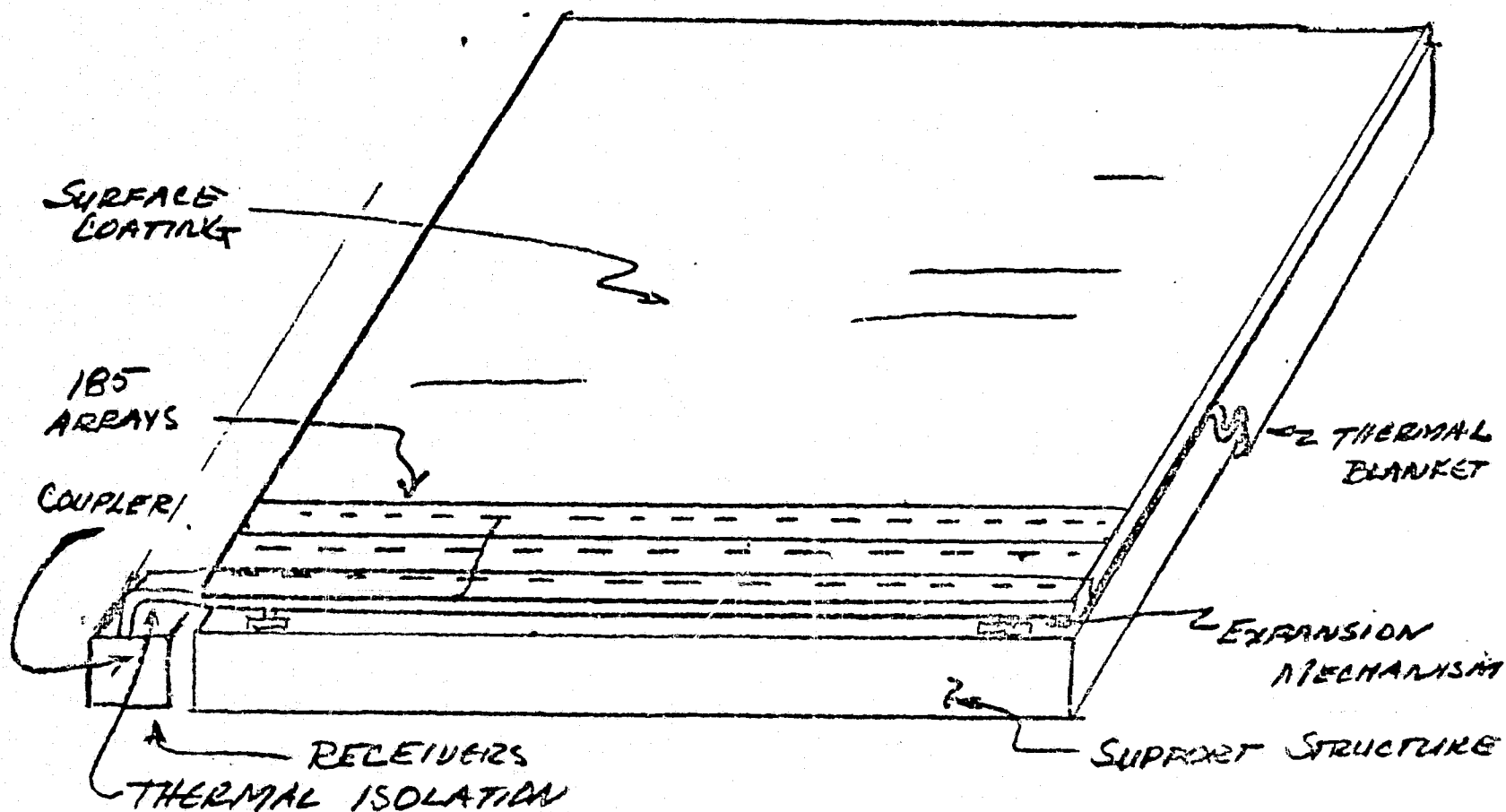
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ARRAY SCHEMATIC

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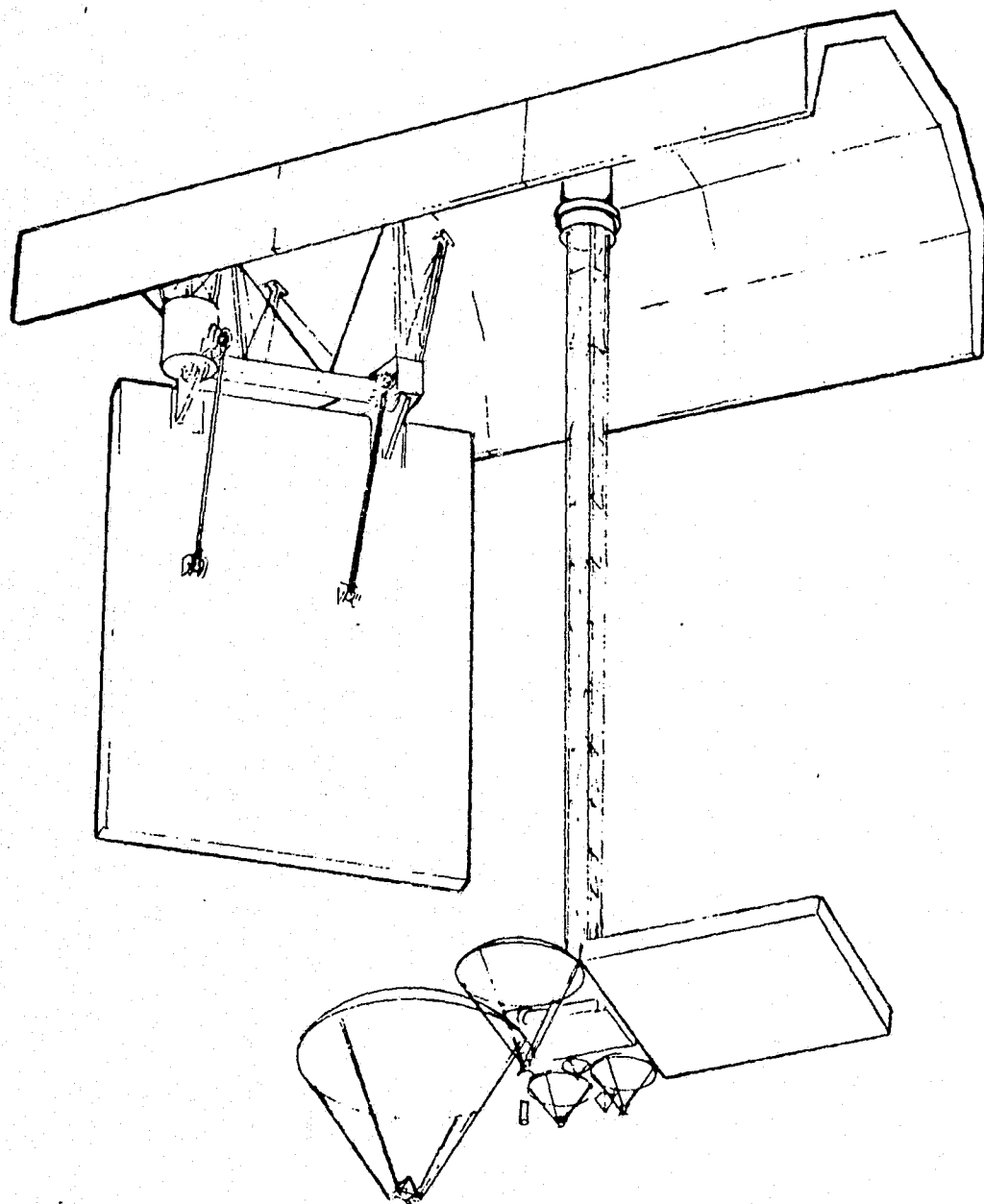


ORIGINATOR'S FACILITY/LOCATION _____

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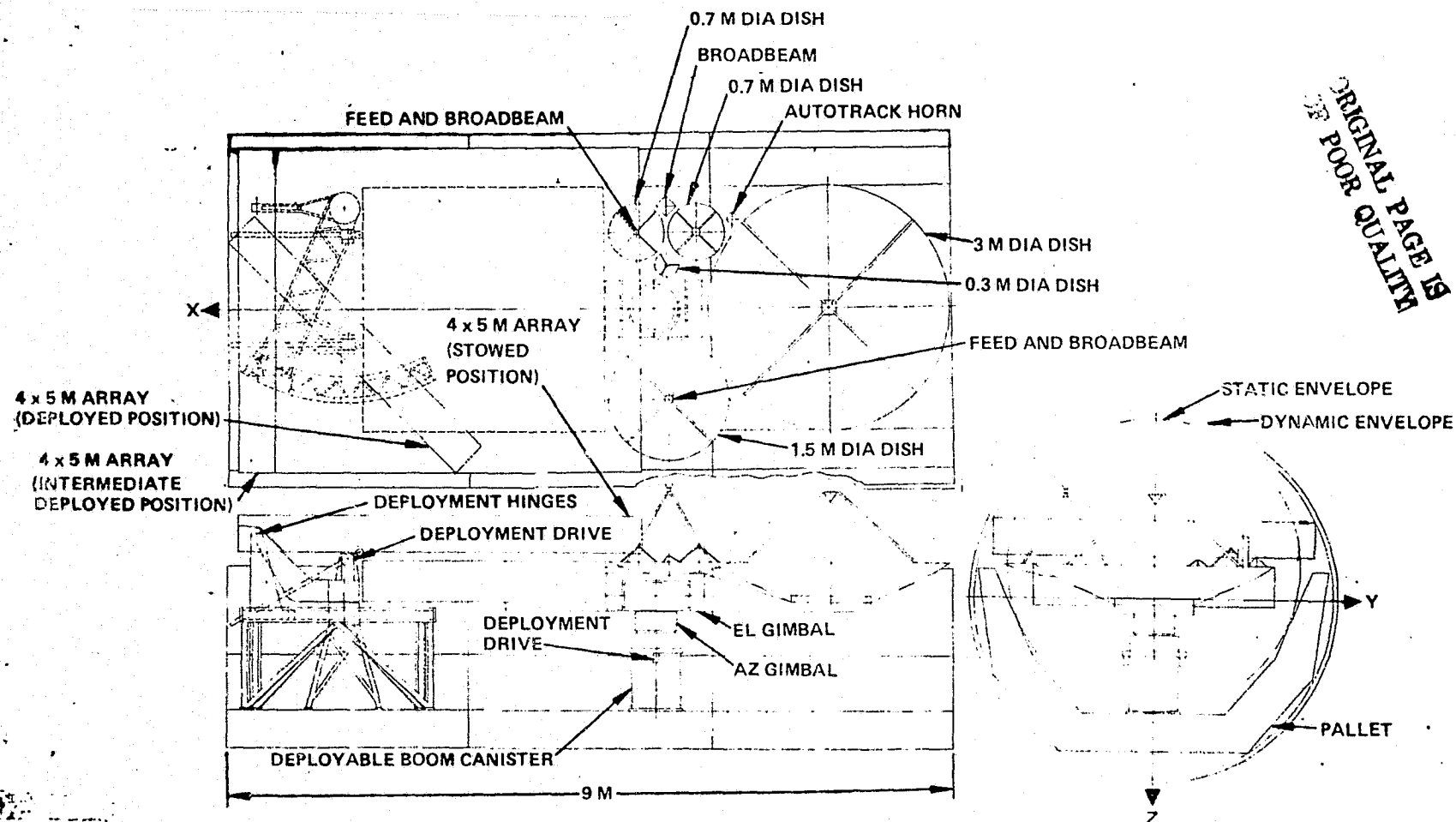
**MMAP/EEE
ANTENNAS AND
4×5-M ARRAY
SEPARATE
MOUNT**



MMAP/EEE ANTENNAS AND 4x5-M ARRAY SEPARATE MOUNT

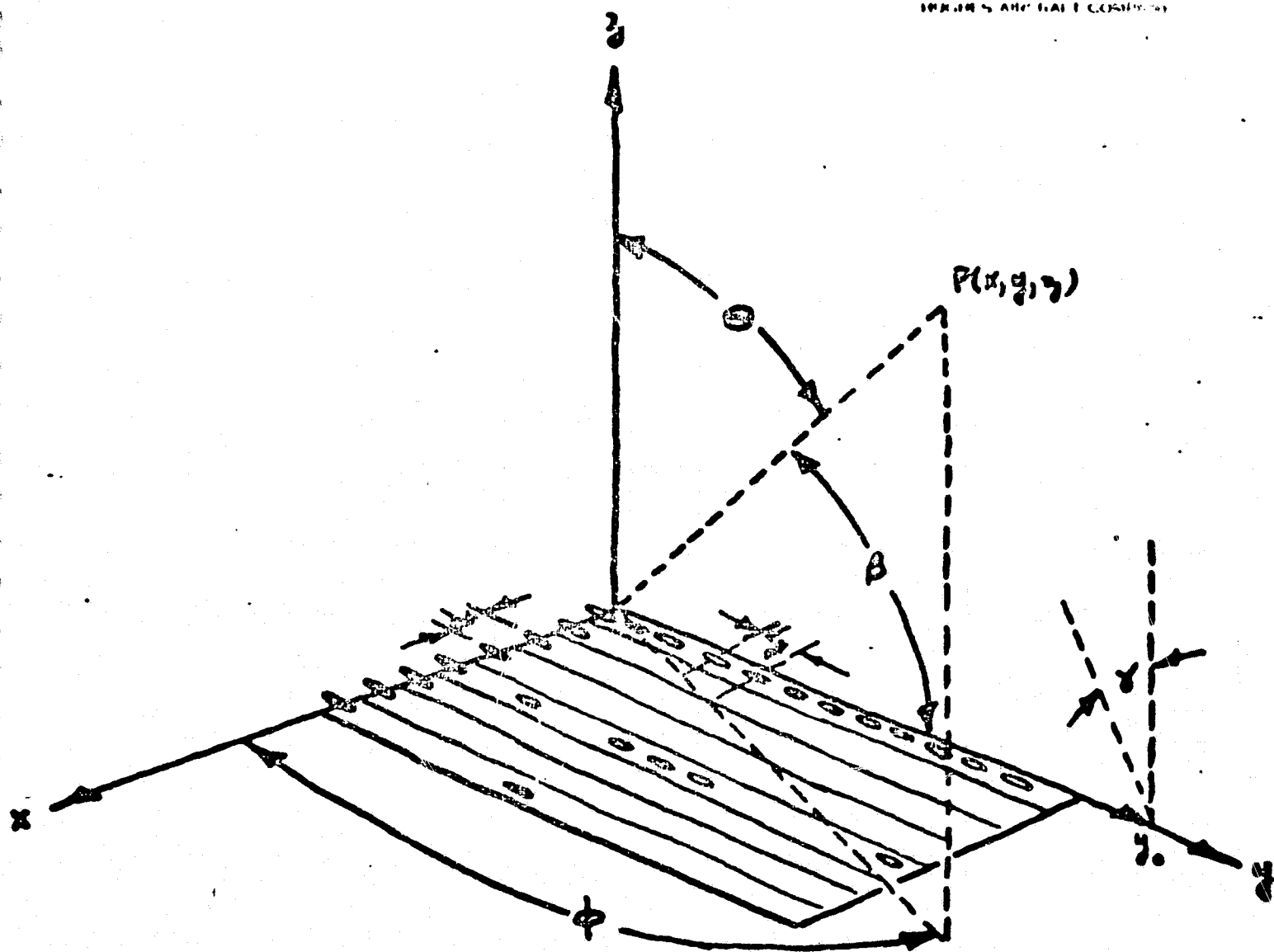
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IMAGES AND HALF COSINES

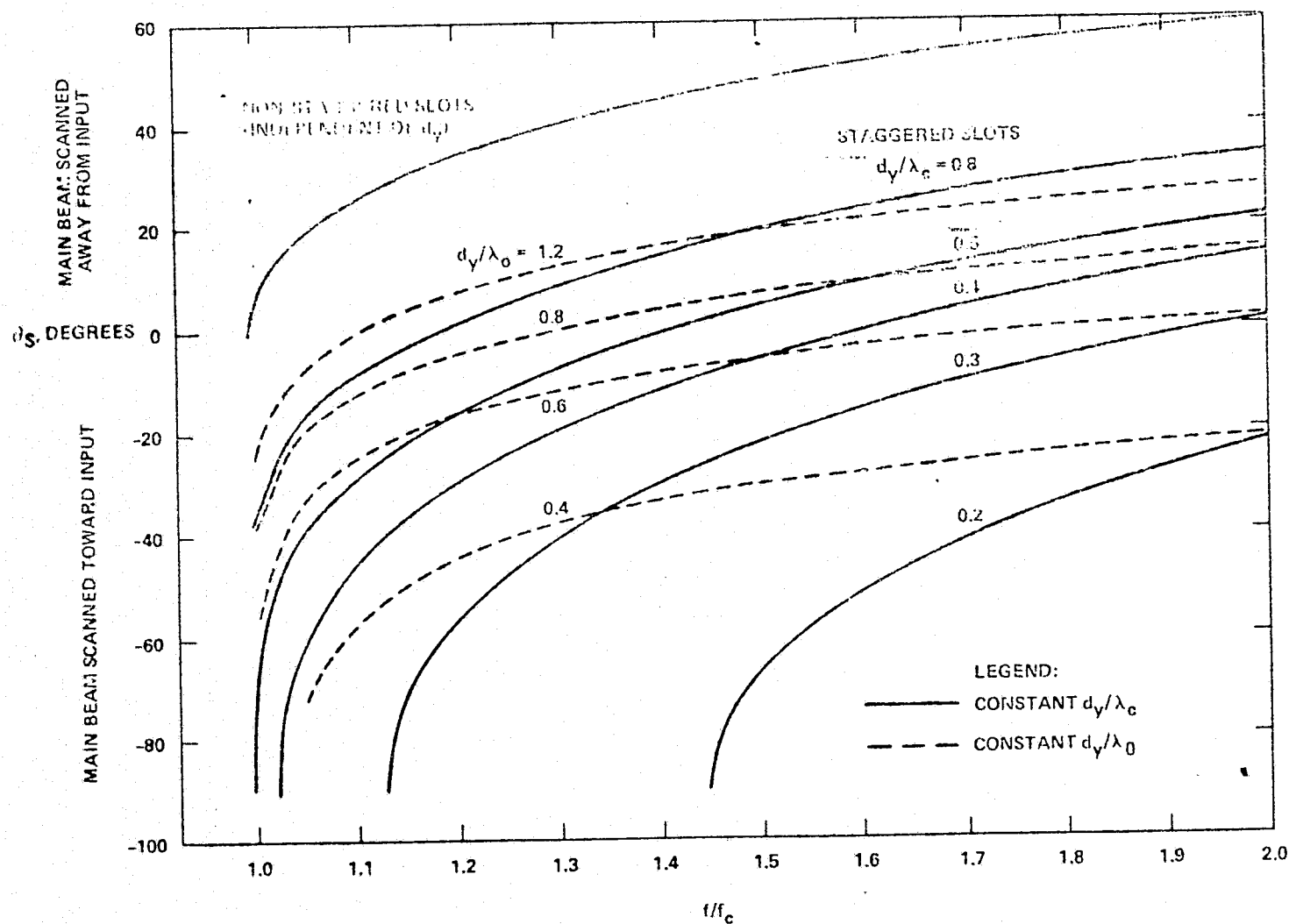


MRF PLANAR ARRAY IN COORDINATE SYSTEM

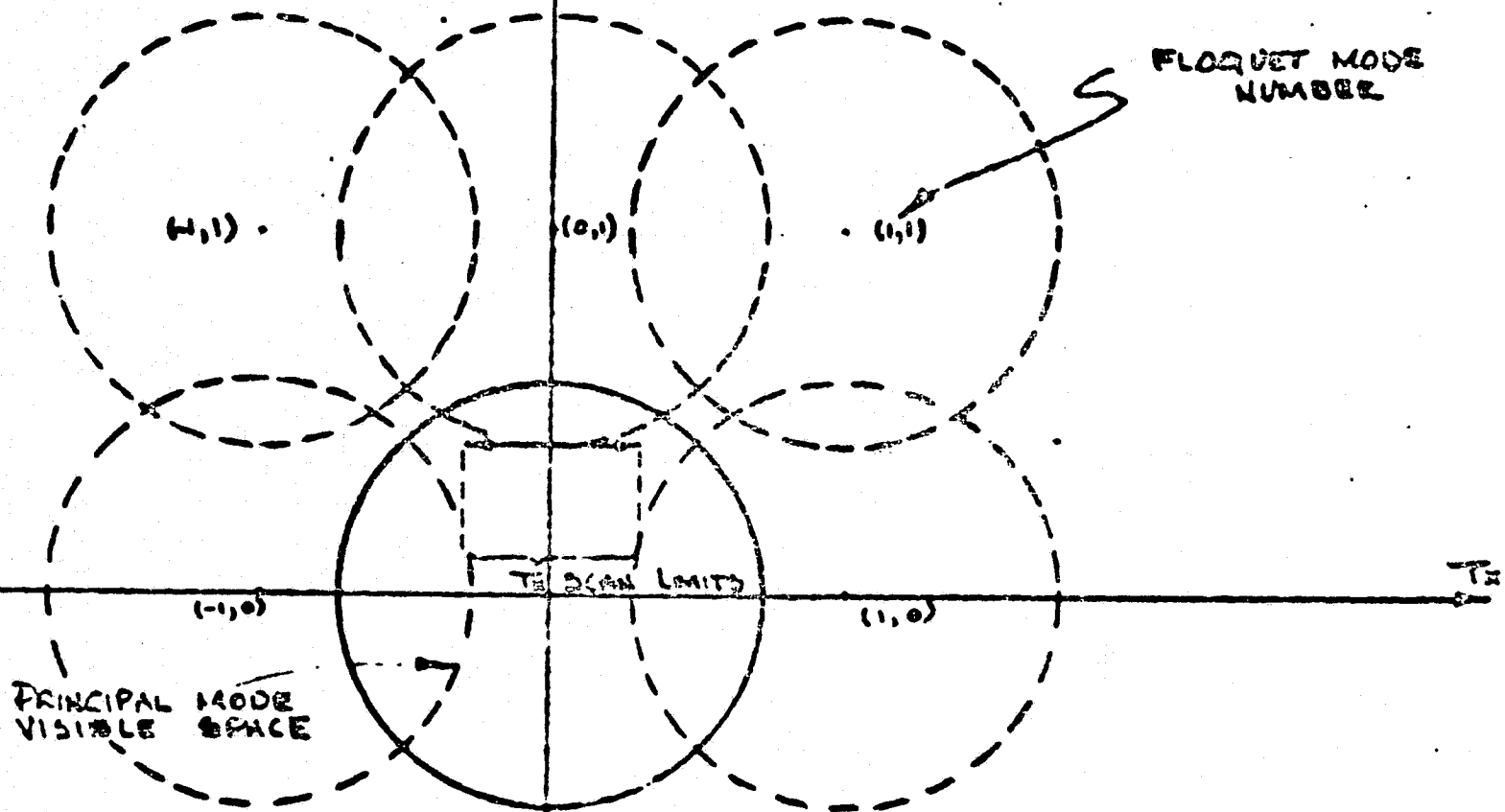
TRAVELING WAVE SLOT ARRAY SCAN ANGLE RELATIONSHIPS

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ORIGINAL PAGE IS
OF POOR QUALITY

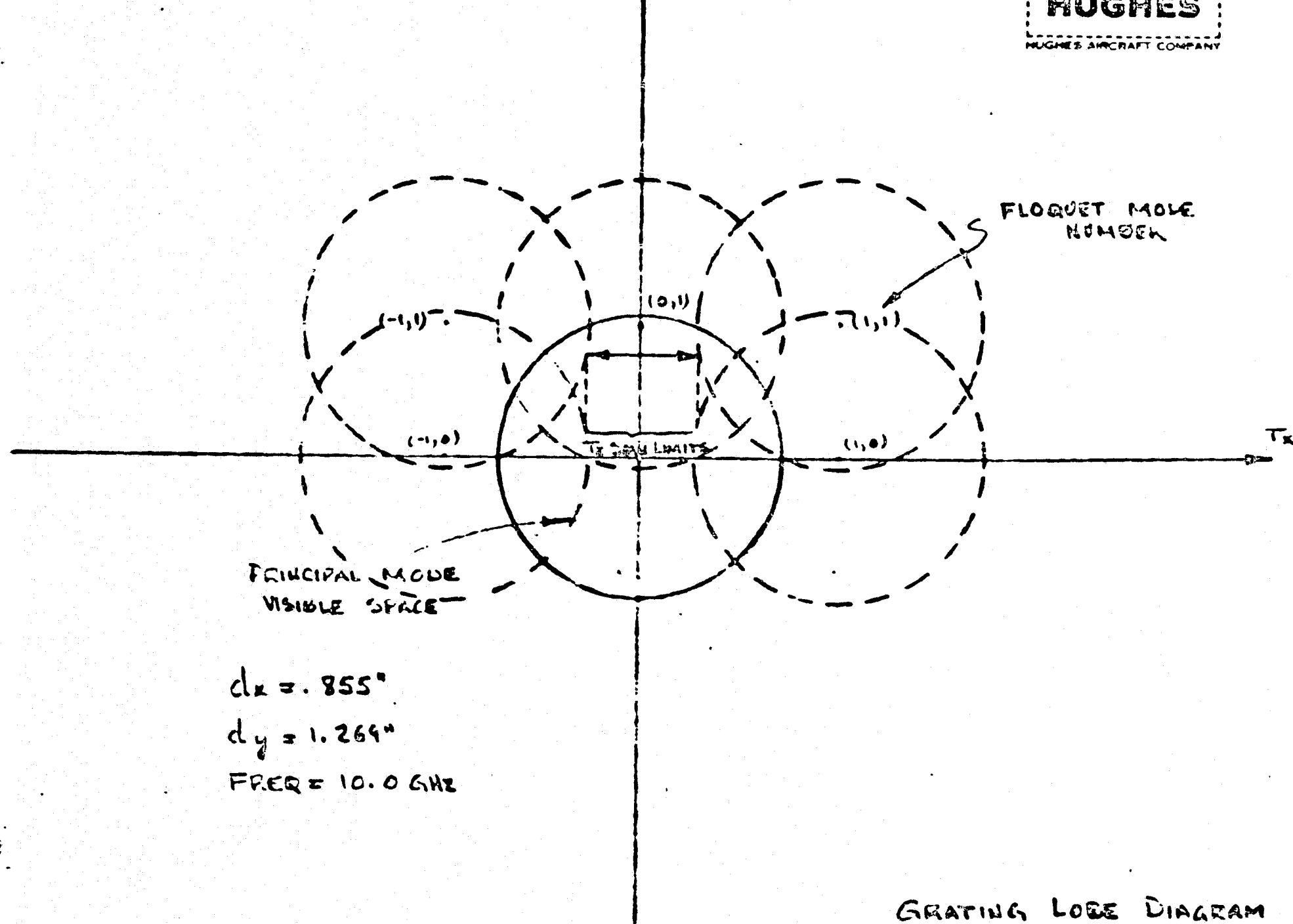


$$d_x = .855"$$

$$d_y = .691"$$

$$\text{FREQ} = 10 \text{ GHz}$$

GRATING LOBE DIAGRAM



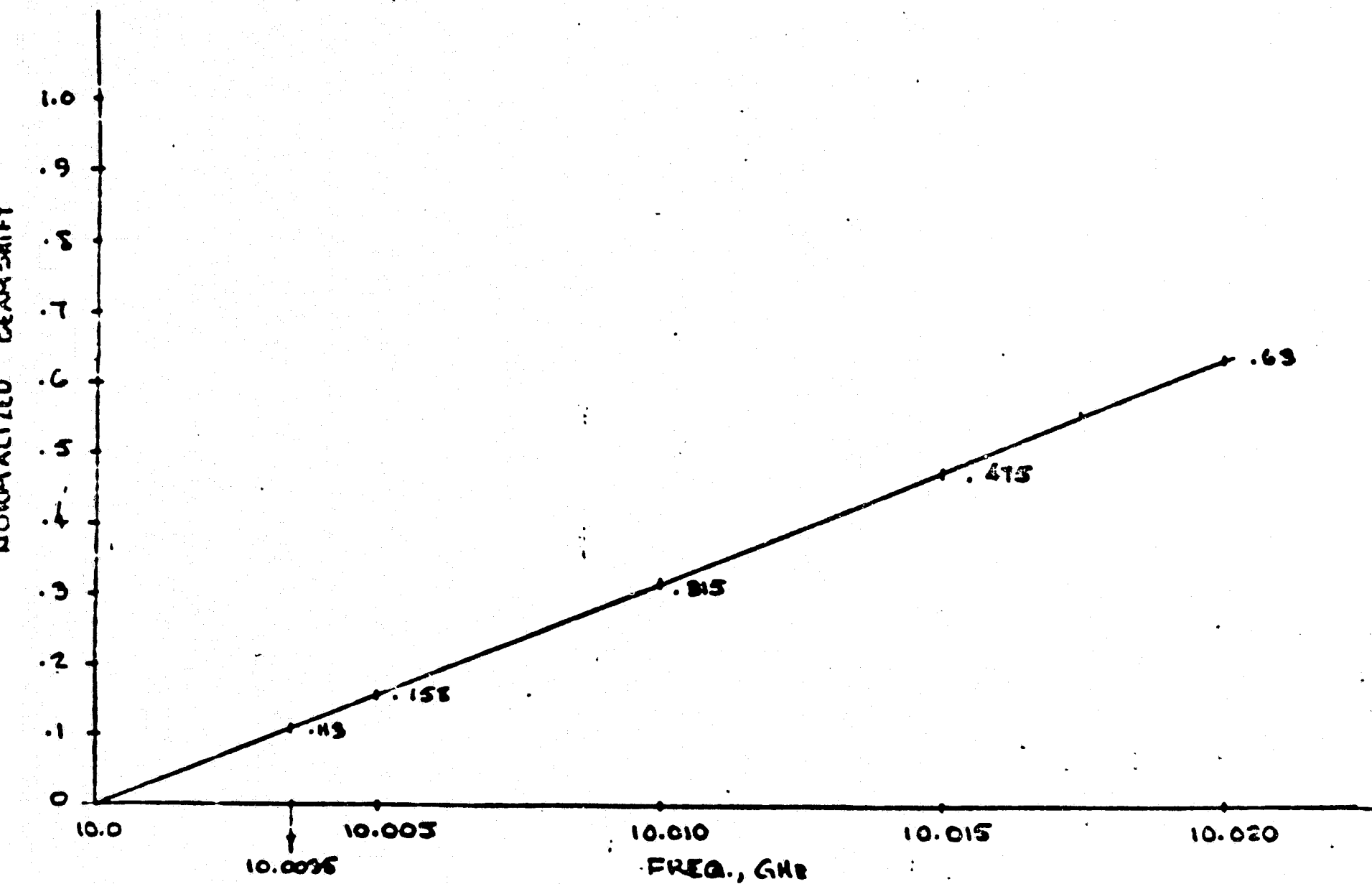
$$dx = .855\lambda$$

$$dy = 1.264\lambda$$

$$\text{FREQ} = 10.0 \text{ GHz}$$

GRATING LOBE DIAGRAM

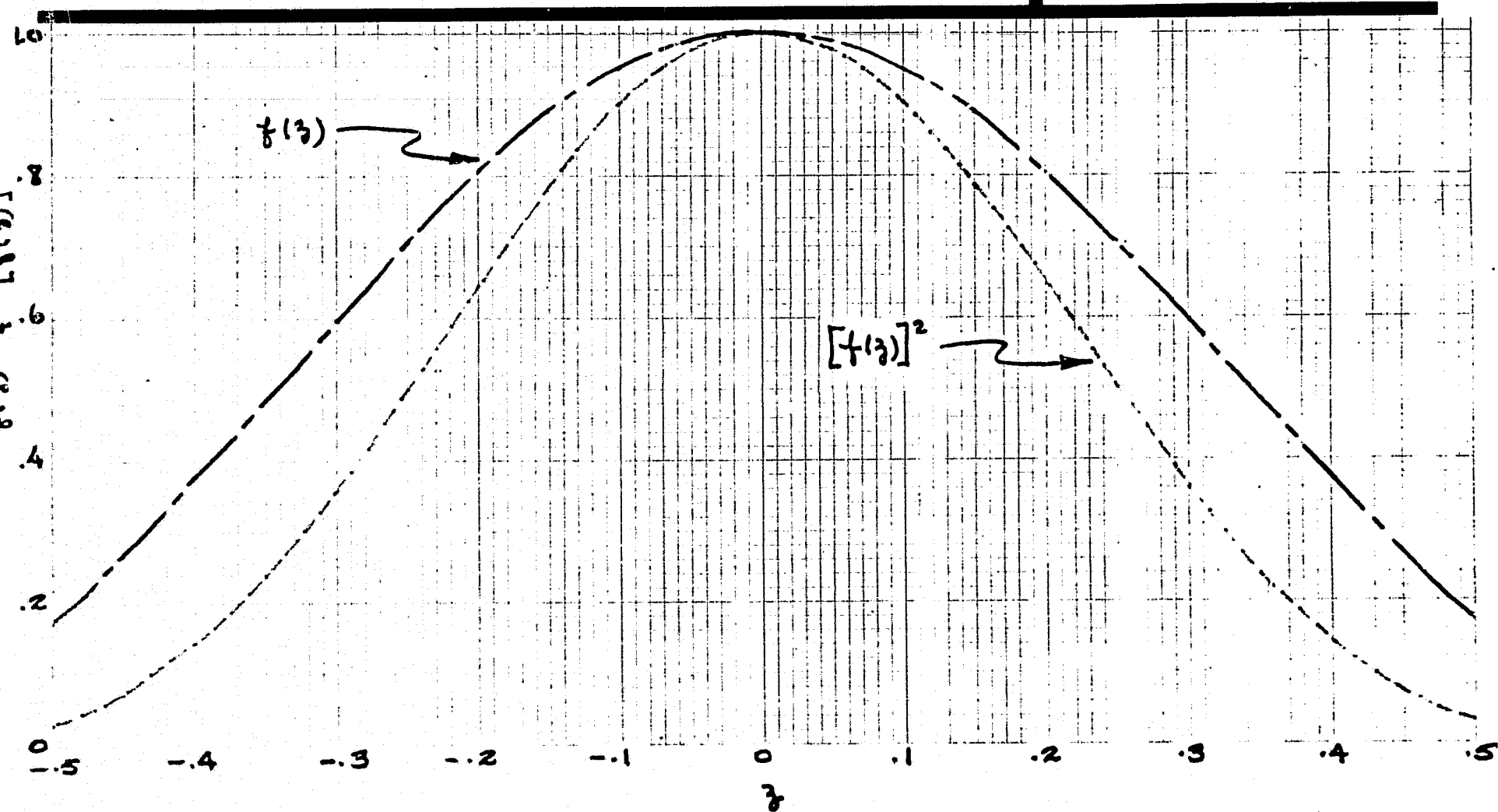
WAVEGUIDE BROAD DIMENSION = .835"



25 dB MODIFIED TAYLOR DISTRIBUTION (AMPLITUDE AND POWER)

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NORMALIZED CONDUCTANCE
MRF 5 M. & 18 M. ARRAYS

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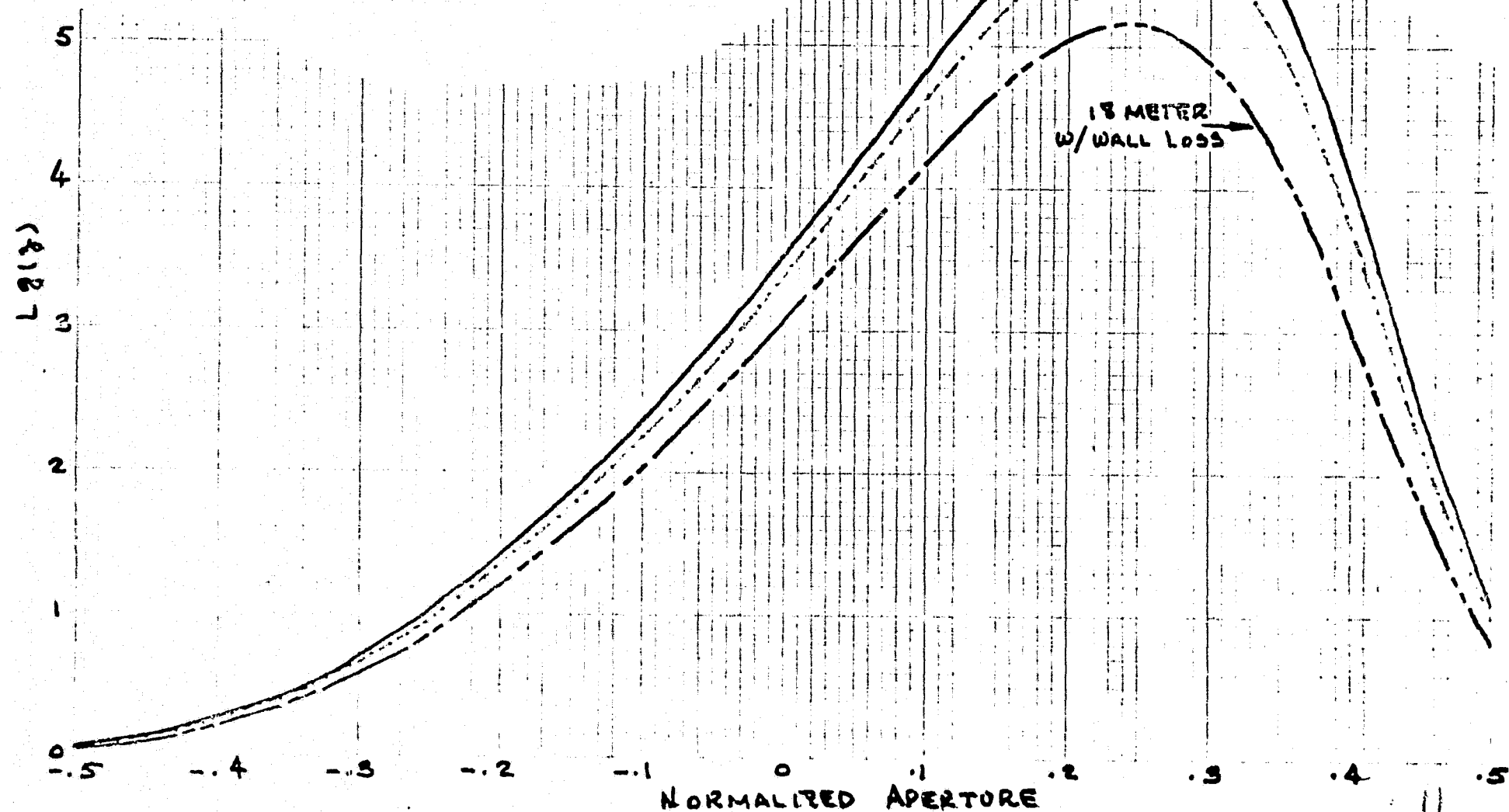
HUGHES AIRCRAFT COMPANY

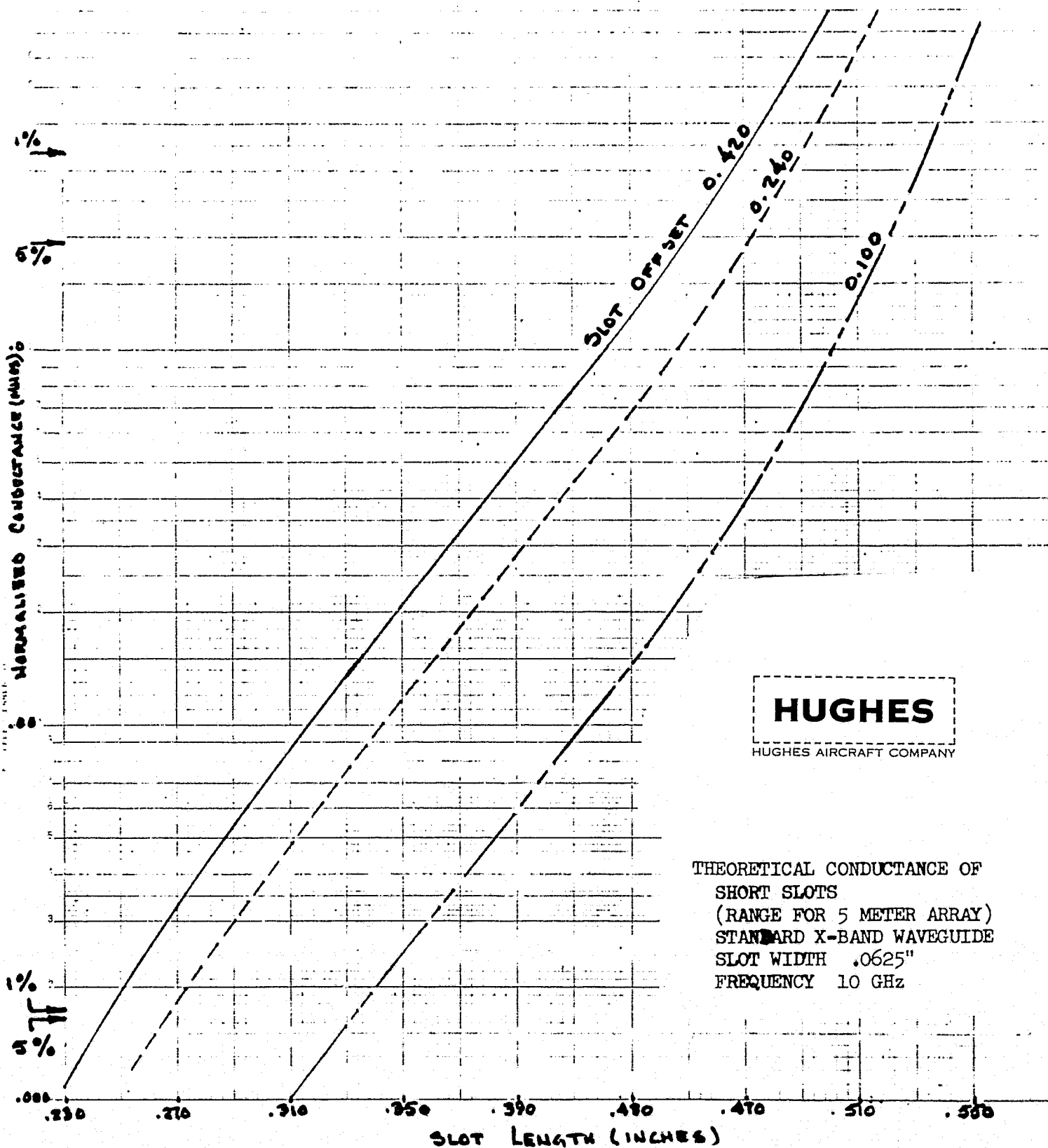
LOSSLESS
(UNIVERSAL)

25 dB MODIFIED TAYLOR DISTRIBUTION
STANDARD ALUMINUM X-BAND WAVEGUIDE WALL LOSS
5% POWER TO LOAD

5 METER
W/WALL LOSS

18 METER
W/WALL LOSS





THEORETICAL SUSCEPTANCE OF SHORT SLOTS
(RANGE FOR 5 METER ARRAY)

HUGHES

HUGHES AIRCRAFT COMPANY

STANDARD X-BAND WAVEGUIDE
SLOT WIDTH .0625"
FREQUENCY 10 GHz

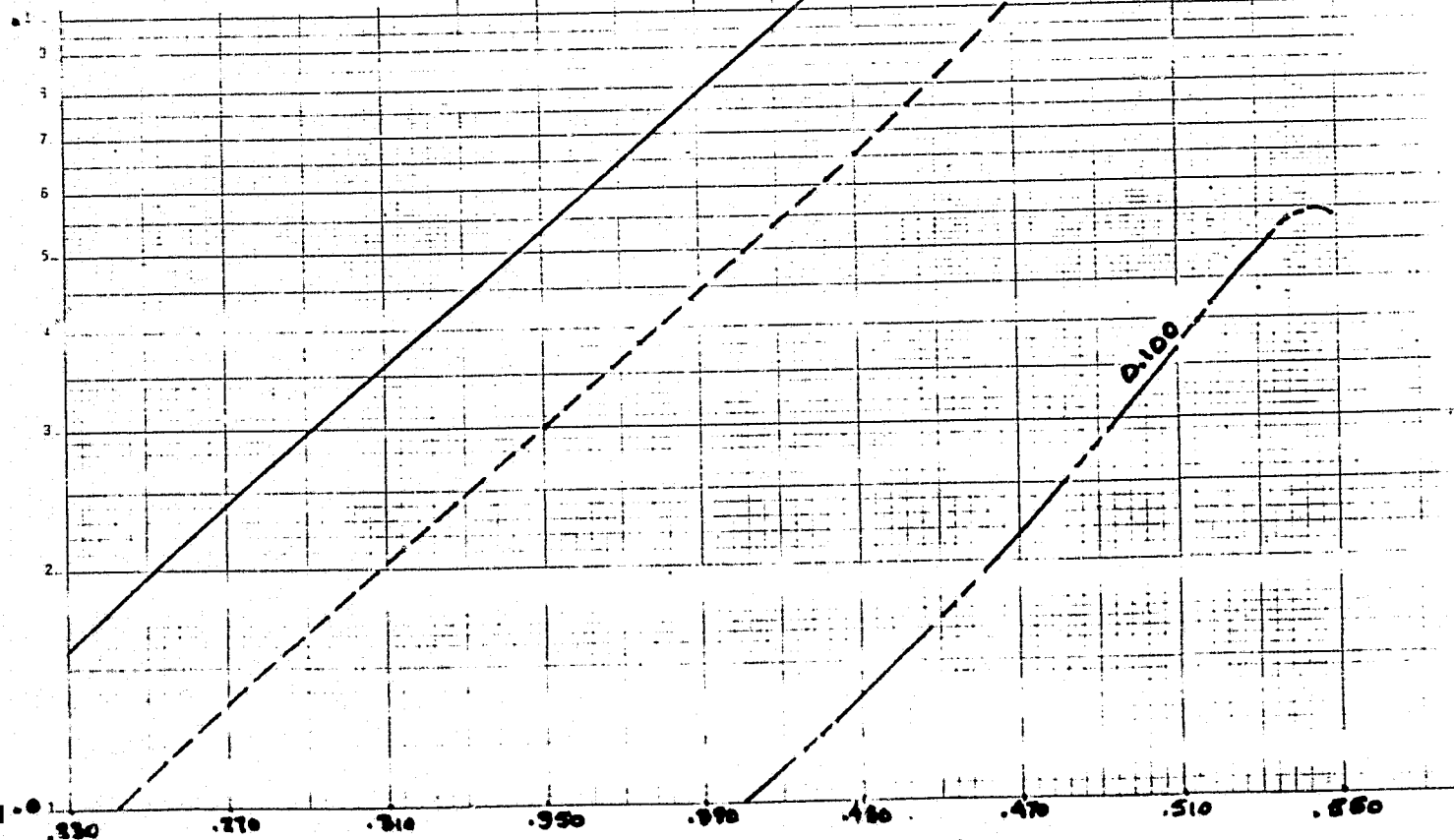
NORMALIZED SUSCEPTANCE (MHOS)

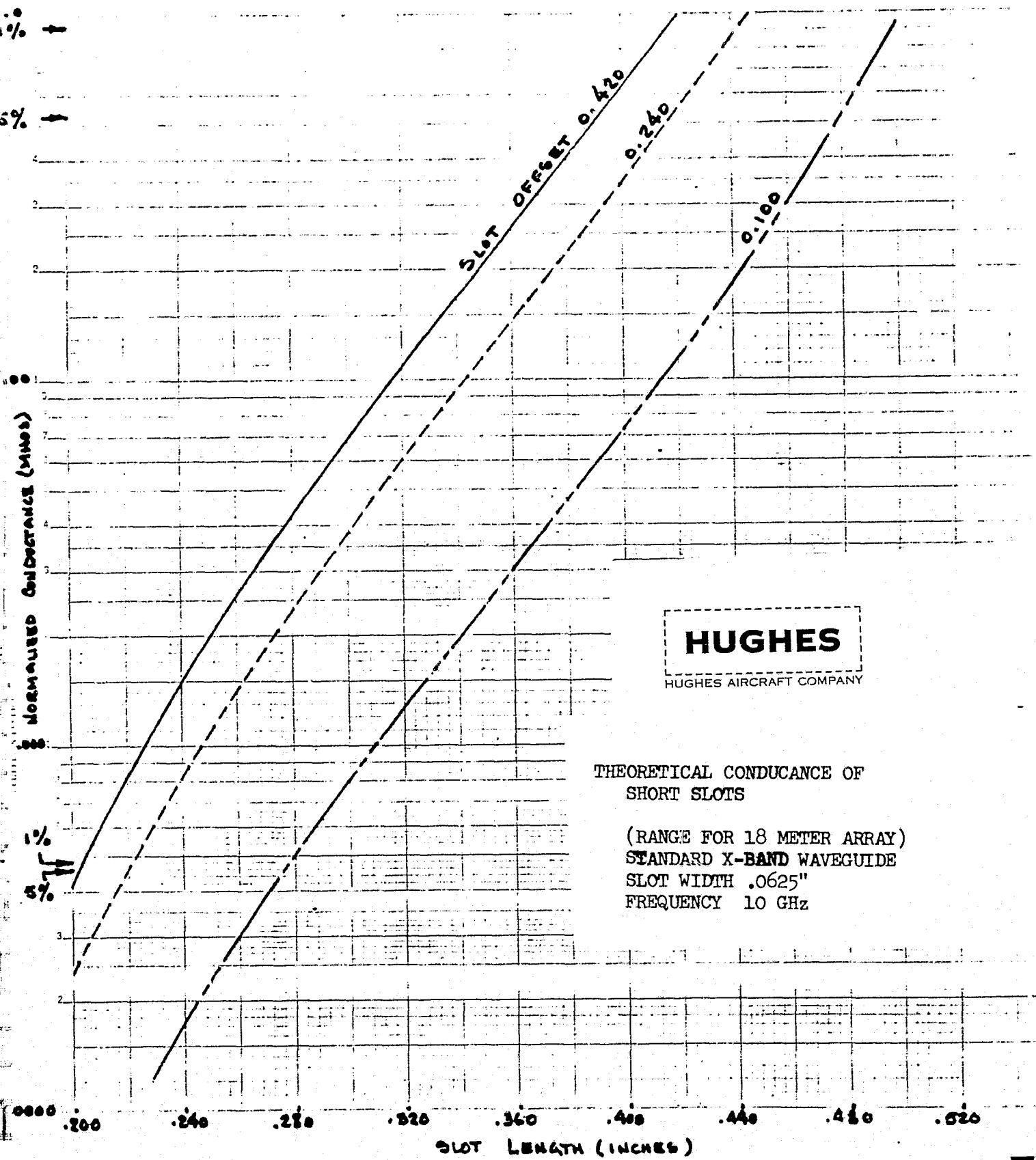
SLOT OFFSET 0.420

0.240

0.100

SLOT LENGTH (INCHES)





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THEORETICAL CONDUCTANCE OF
SHORT SLOTS

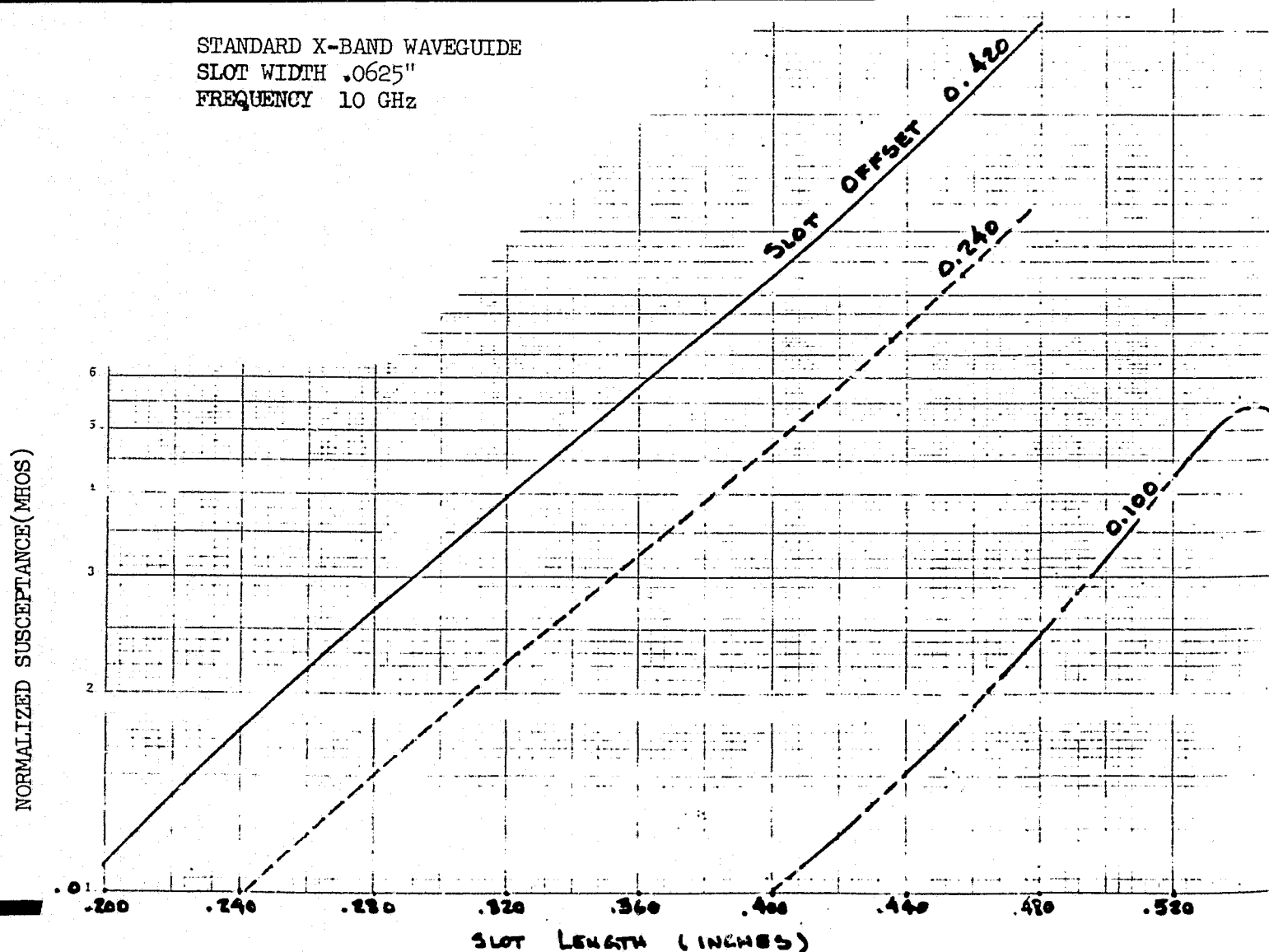
(RANGE FOR 18 METER ARRAY)
STANDARD X-BAND WAVEGUIDE
SLOT WIDTH .0625"
FREQUENCY 10 GHz

THEORETICAL SUSCEPTANCE OF SHORT SLOTS
(RANGE FOR 18 METER ARRAY)

HUGHES

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STANDARD X-BAND WAVEGUIDE
SLOT WIDTH .0625"
FREQUENCY 10 GHz

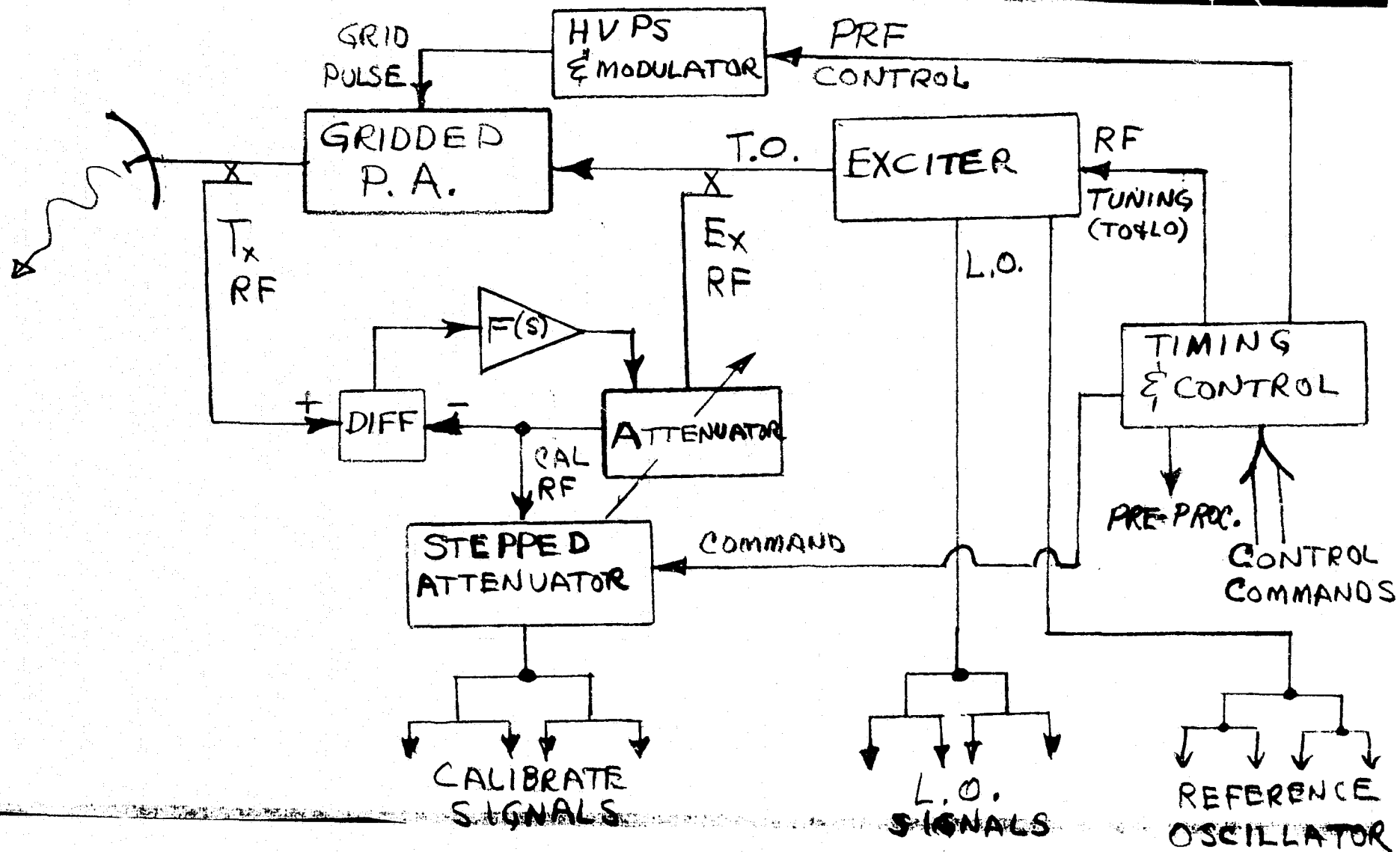


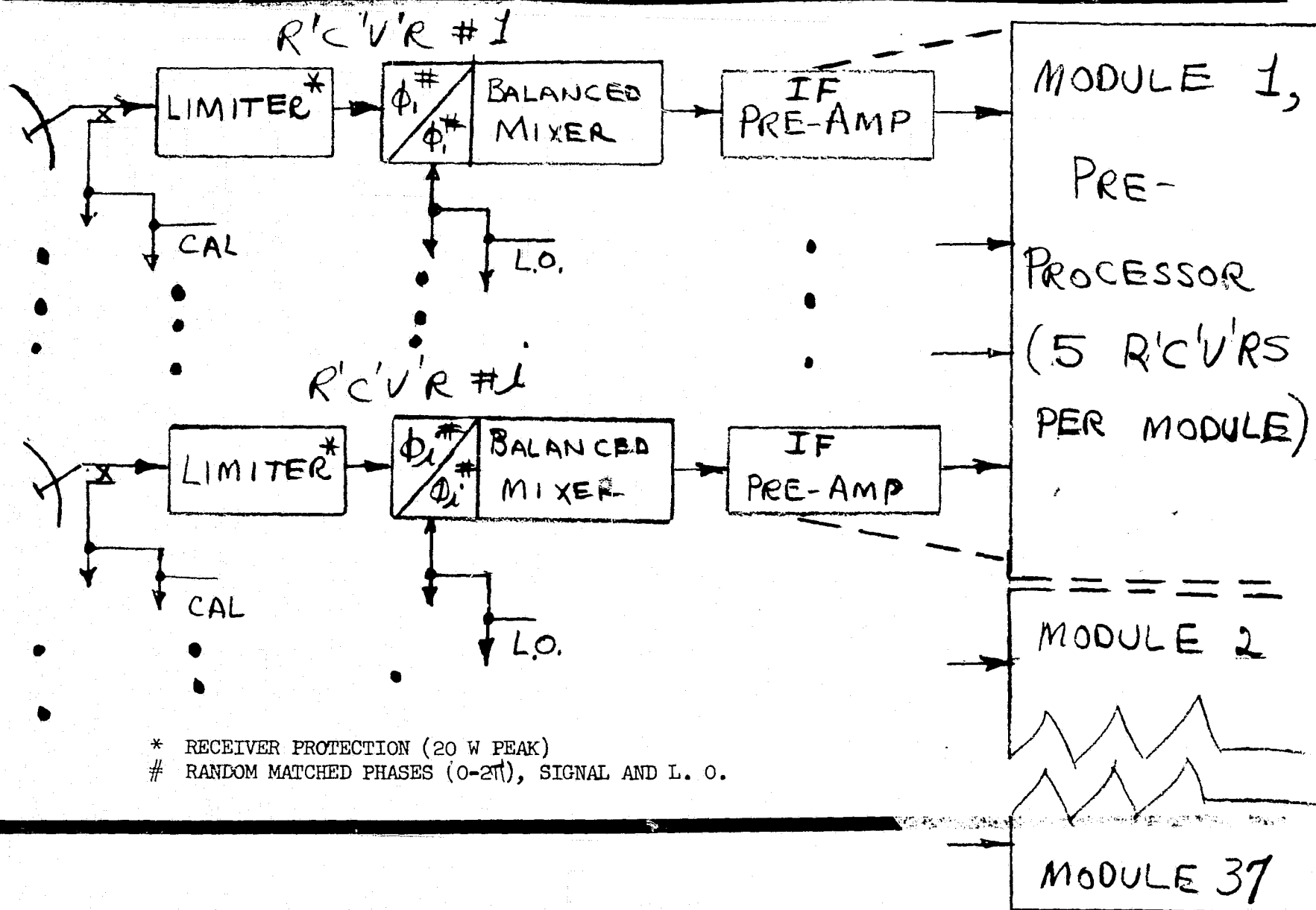
R F GROUP

ANTENNA/TRANSMITTER/EXCITER/CALIBRATOR

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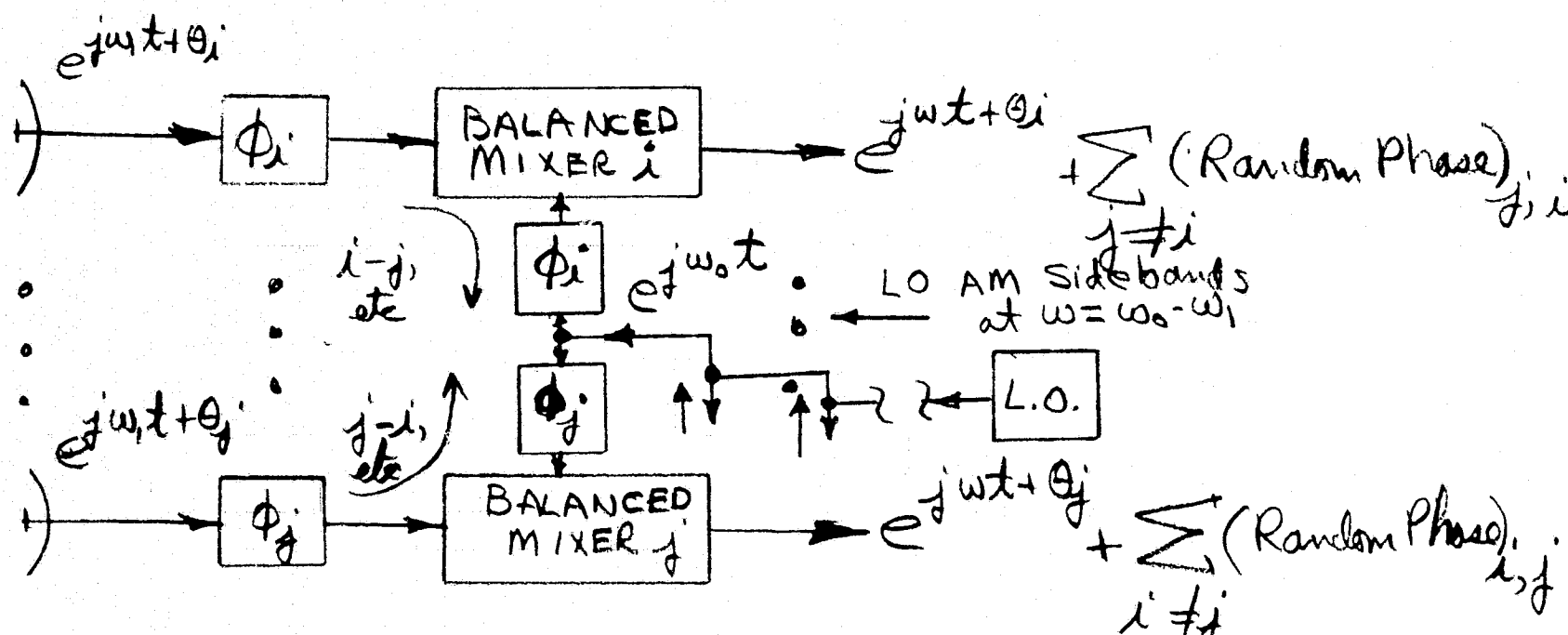
PHASE RANDOMIZATION

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NON-COHERENT INTER-CCHANNEL INTERFERENCE

- INTER-CHANNEL ISOLATION REQUIREMENT LESS THAN FOR CORRELATED INTERFERENCE
- AM NOISE SIDEBAND REQUIREMENT FOR COMMON L.O. SOURCE RELAXED
- * (L.O. MANIFOLD IS A PRINCIPLE PATH FOR INTERCHANNEL COUPLING).



X-BAND TRANSMITTER OPTIONS FOR MRF



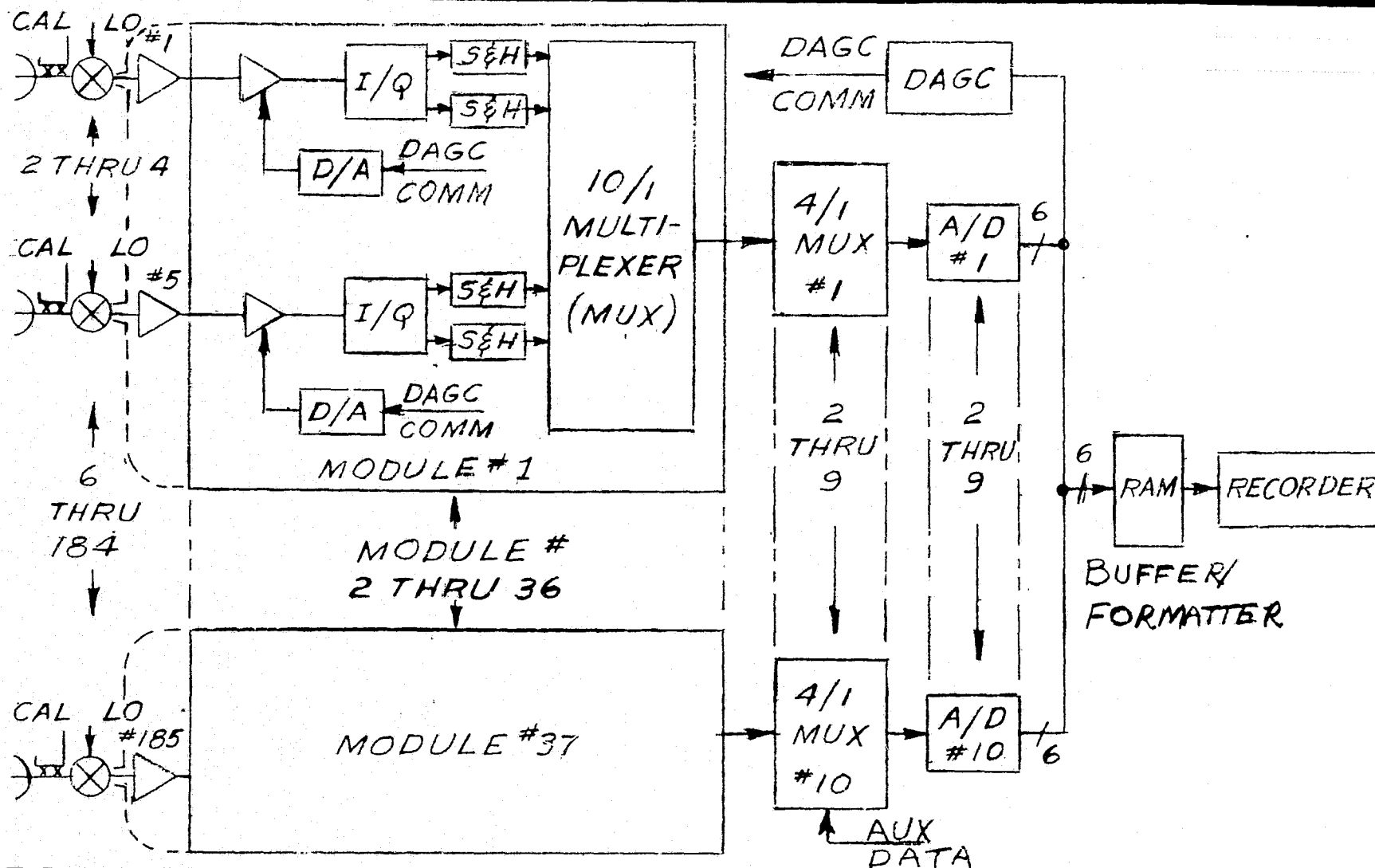
1. EXISTING DESIGN AT HUGHES
TYPE: GRIDDED TWT
FREQUENCY BAND: 9.6-9.8 GHz
POWER OUTPUT: 8-9 KW PK, 200-250 w. AVG.
DRIVE POWER: 20 MW (MAX)
INPUT REQUIREMENTS: 950 WATTS
APPLICATION: DOPPLER RADAR, MILITARY

2. PROPOSED DESIGN FOR SPACE (SIR)
TYPE: GRIDDED KLYSTRON
FREQUENCY: 9.0 GHz (75 MHz BW, 9-11 GHz)
POWER OUTPUT: 17 KW PK, 500 w. AVG.
RF DRIVE: .6 w (MAX)
INPUT REQUIREMENTS: 1400 WATTS
APPLICATION: COHERENT SYNTHETIC ARRAY RADAR

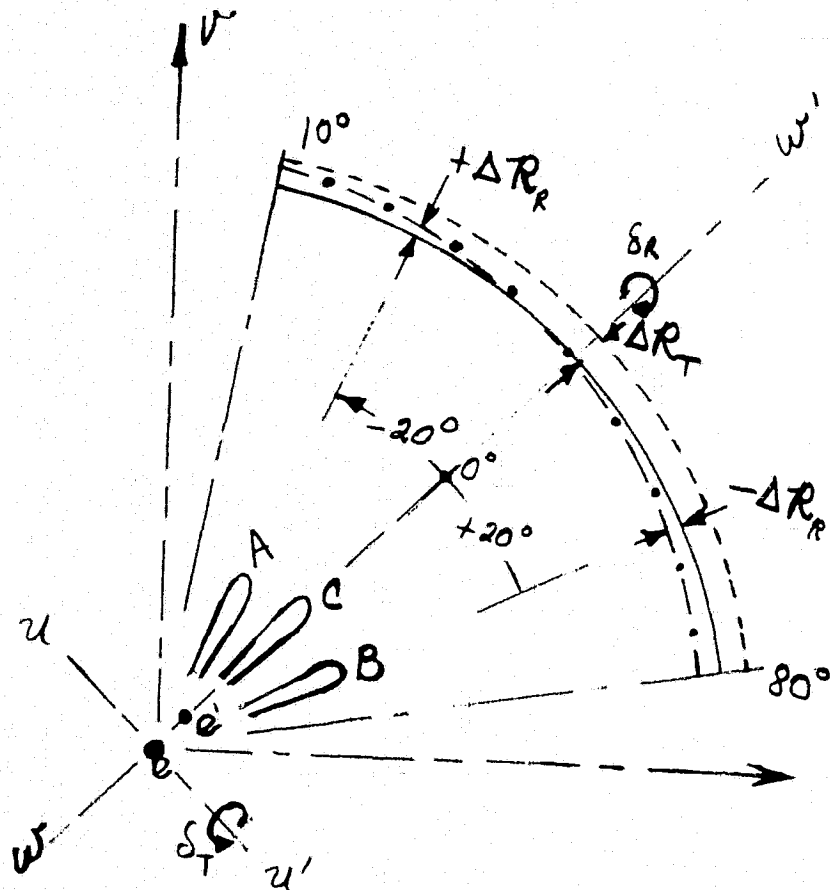
PRE-PROCESSOR ORGANIZATION

HUGHES

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TILT AND ROTATION ERROR SENSOR: THREE BEAMS AT 0(C), 20(B), -20 (C) DEGREES
(RELATIVE TO ROTATIONAL AXIS W-W')



• CLUTTER RANGE SENSITIVITIES TO ANTENNA POSITION:

ROTATIONAL SENSITIVITY ΔR_R : ABOUT 2 KM/°

TILT SENSITIVITY ΔR_T : ABOUT 6 KM/°

• SENSOR SENSITIVITIES:

TO ROTATION: $K_R = A-B$, ABOUT 4KM/°

TO TILT: $K_T = C - \frac{1}{2}(A+B)$, ABOUT .36KM/°

NOTES:

ORBIT ALTITUDE: 200 KM

ANTENNA BEAMS AT NADIR ANGLE 46.6°

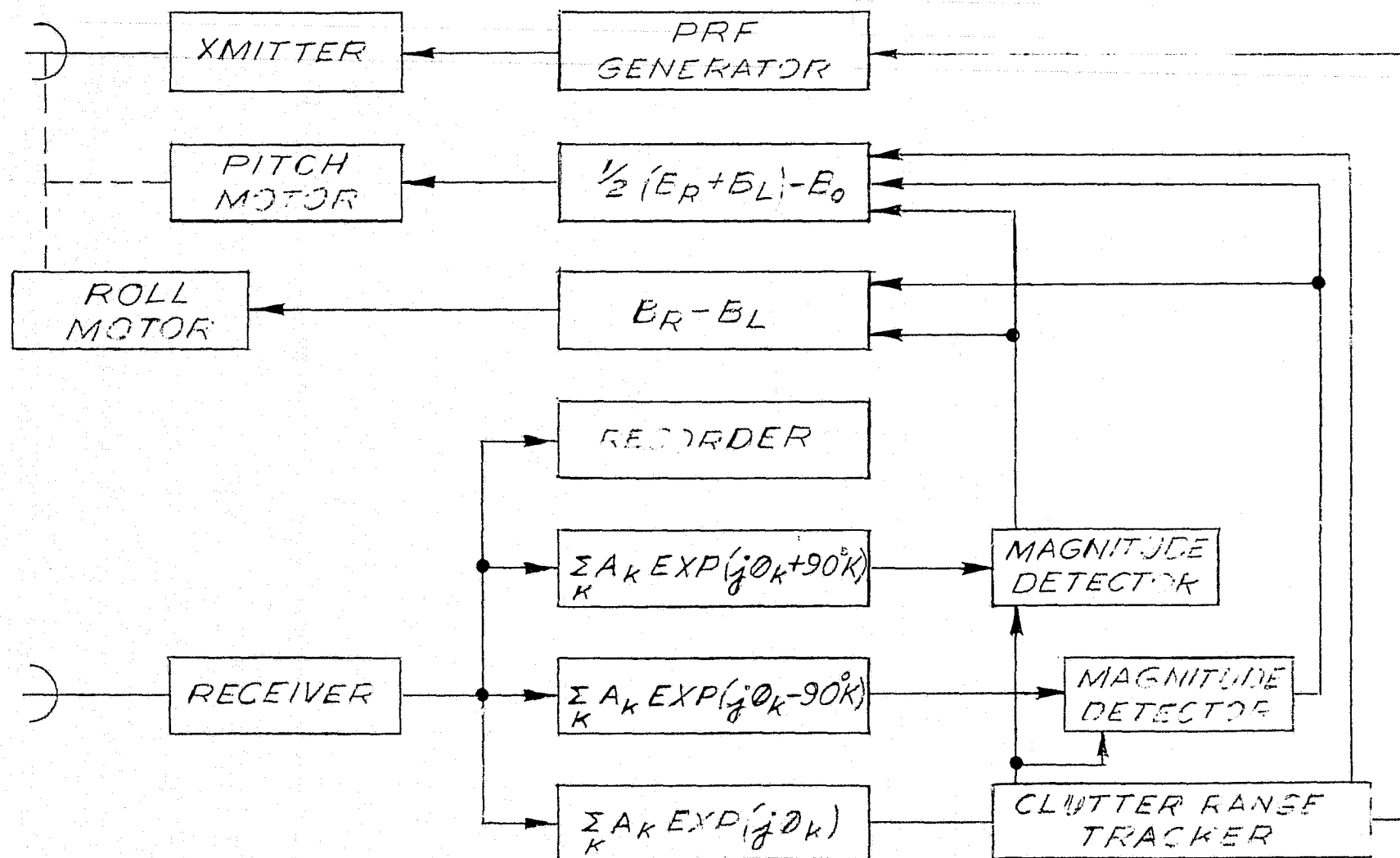
W-W': ROTATIONAL AXIS

U-U': TILT AXIS

ACTIVE RANGE CONTROL

HUGHES

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 ORIGINAL PAGE IS
OF POOR QUALITY

RECORDER OPTIONS FOR MRF

HUGHES

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1. RCA HDMR 240
TRACKS: \geq 120 FOR SIGNAL DATA
BIT RATE: 120 MB/S AT 152 CMS/SEC (60 IPS)
RECORD TIME PER REEL: 30 MIN. AT 120 MB/S
POWER/WEIGHT: 200 w/90 Kg
STATUS: UNDER PHASED DEVELOPMENT, FLIGHT MODEL 1st QUARTER 1979?
2. ADVANCED DEVELOPMENTS;
E.G: AMPEX AR1700
BIT RATE: 100 MB/S ON 28 TRACKS AT PACKING DENSITIES
OF 11.8 KB/CM (30 KB/IN.)
RECORD TIME PER REEL: 15 MIN AT 100 MB/S (120 IPS)
POWER/WEIGHT: 450 w/40 Kg
STATUS: UP-GRADING DEVELOPMENT MODELS; AVAILABLE 90-120 DAYS ARO

SPECIFICATIONS

HUGHES

HUGHES AIRCRAFT COMPANY

TOPICS:

SYSTEM

ANTENNA

TRANSMITTER

EXCITER

RECEIVERS

CALIBRATOR

PRE-PROCESSOR

DISTRIBUTION NETWORKS

SELECTED SYSTEM SPECIFICATIONS

HUGHES

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CARRIER FREQUENCY F_X : TO BE SELECTED IN BAND 9.5 TO 10.5 GHz (10.0 GHz BASELINE)

ORBIT ALTITUDE: 200 ± 30 KM

ORBIT INCLINATION: AS REQUIRED

SPACELAB LOCAL VERTICAL: EARTH ORIENTED

DRIFT: TBD DEGREES/MINUTE

ACCURACY: TBD DEGREES RMS

ANTENNA

DIMENSIONS: 4X5 METERS $\pm 10\%$

POLARIZATION: LINEAR HORIZONTAL

ELEVATION SIDELOBES: -25 dB PEAK (ONE WAY)

GRATING LOBES: -25 dB (ONE WAY)*

RECEIVE ELEMENTS: 175-195 (PROPORTIONAL TO F_X ; 185 @10 GHz)

AZIMUTH SIDELOBES (LIMIT IMPOSED BY REAL ARRAY): -40 dB RMS (ONE WAY)*

ELEMENT PATTERN BEAMWIDTHS: 70 DEGREES MINIMUM IN AZIMUTH; .6 DEGREES MAXIMUM IN ELEVATION

* OUTSIDE ± 4 BEAMWIDTHS OF MAINLOBE

TRANSMITTER

PEAK POWER: 8KW MINIMUM

POWER AMPLIFIER: GRIDDED KLYSTRON OR TWT

TUBE BANDWIDTH: 25 MHz MINIMUM

NOMINAL PULSE WIDTH: 6.67 μ s

AVERAGE POWER OUTPUT: 250 WATTS MAXIMUM

EXCITER

CARRIER FREQUENCIES (3): $F_1 = F_X$, $F_2 = F_X + 1.5$ MHz, $F_3 = F_X - 1.5$ MHz

OUTPUTS; DRIVE: .3 WATT MINIMUM

L. O.: 2.0 WATTS MINIMUM

REF. OSC.: .1 WATT MINIMUM

RECEIVERS

NOISE FIGURES: 10 dB MAXIMUM

IF: 30 MHz WITH BANDWIDTHS OF $1.0 \pm 10\%$ AT -3dB AND 2.3 MHz MAXIMUM AT -20 dB

GAIN AND PHASE BALANCES: .6 dB, 4° RMS OVER BANDWIDTH OF 330 KHz $\pm 10\%$

MIXER LO CARRIER SUPPRESSION: 20dB MINIMUM

CALIBRATOR

OUTPUT (REFERENCED TO TRANSMITTER SAMPLES $P_C=10$ MW, MINIMUM):

-15 dB TO -63 dB IN 3dB STEPS WITH ACCURACY $\pm .15$ dB RMS

PRE-PROCESSORS

IF POSTAMPLIFIER NOMINAL GAIN: 50 ± 3 dB MAXIMUM

DIGITAL GAIN CONTROL RANGE: 30 dB WITH .1 dB RMS ACCURACY

MUTUAL DE-COUPLING: AT LEAST 50 dB ISOLATION BETWEEN RECEIVERS IN A COMMON MODULE AND
80 dB ISOLATION BETWEEN RECEIVERS IN SEPARATE MODULES;
10 RECEIVERS MAXIMUM PER MODULE

TIME MULTIPLEX: TWO CASCADED STAGES TO MULTIPLE PARALLEL A/D CONVERTER CHANNELS

SAMPLE/HOLD APERTURE TIME: 100 NS MAXIMUM

DE-COUPLING: 40 dB MINIMUM ISOLATION BETWEEN ADJACENT DIGITAL WORDS

A/D CONVERTER BIT OUTPUT (BIT SELECTION): 5 MOST OR 5 LEAST SIGNIFICANT BITS (I&Q)
SELECTED FROM 6 BITS I AND Q

CLUTTER RANGE TRACKER: 500 METERS MAXIMUM RMS ERROR TO MEAN MAIN LOBE CLUTTER RANGE

DIFFERENTIAL CLUTTER RANGE SENSOR: SENSITIVE TO MEAN CLUTTER RANGE DIFFERENCES OF
100 METERS OR LESS AT BEAM POSITIONS OF $0^\circ \pm 20^\circ$
RELATIVE TO ARRAY BROADSIDE

DISTRIBUTION NETWORK SPECIFICATIONS



LOCAL OSCILLATOR (185 PORTS);

FORM: CORPORATE FEED
INSERTION LOSS: 7 dB MAXIMUM
GAIN BALANCE: 1 dB RMS
PHASE BALANCE: 4° RMS
INTER-CHANNEL RF SIGNAL ISOLATION:* 41 dB MINIMUM INCLUDING CARRIER SUPPRESSION CONTRIBUTION OF 20 dB MINIMUM PER RECEIVER MIXER

CALIBRATOR (185 PORTS):

FORM: CORPORATE FEED
INSERTION LOSS: 7 dB, MAXIMUM
GAIN BALANCE: .8 dB RMS
PHASE BALANCE: 3° RMS
INTER-CHANNEL RF SIGNAL ISOLATION:* 50 dB, MINIMUM INCLUDING 50 dB MINIMUM PER CHANNEL COUPLER PAIR

* ISOLATION REFERS TO RF SIGNAL PORT-TO-IF SIGNAL PORT OVER RELEVANT COUPLING NETWORK PATH.

DISTRIBUTION NETWORK SPECIFICATIONS (CONT'D)



REFERENCE OSCILLATOR (185 INJECTION POINTS IN GROUPS OF 10 MAXIMUM EACH):

GAIN BALANCE: 1 DB RMS

PHASE BALANCE: 4° RMS

INTER-CHANNEL ISOLATION:*

INTRA-GROUP: 50 DB MINIMUM

INTER-GROUP: 80 DB MINIMUM

* INCLUDING ACTIVE ELEMENTS, AS REQUIRED; ISOLATION REFERS TO IF SIGNAL PORT-TO-VIDEO
SIGNAL PORT OVER RELEVANT COUPLING NETWORK PATH

TRANSMITTER SPECIFICATIONS

HUGHES

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OPERATING TEMPERATURE RANGE -20° TO $+40^{\circ}$ C

PEAK POWER, MINIMUM

8.0 KW

GAIN MINIMUM

45 DB

DRIVE MAXIMUM

0.3 WATT

PULSE DURATION, NOMINAL

6.67 μ s

PRF, MAXIMUM

10.0 KHz

AVERAGE DUTY FACTOR, MAXIMUM (1)

2.5%

GAIN DRIFT, MAXIMUM

0.3 DB IN 5 MINUTES

PM AND AM SIDEBANDS

MAXIMUM, ANY F 1 KHz

-40 DB PER 100 Hz

RF POWER DROOP IN 10 μ s, MAXIMUM

0.3 DB

TRANSMITTER TUBE BANDWIDTH, MINIMUM

25 MHz

NOTES:

(1) ONE (1) SECOND MAXIMUM AVERAGING TIME

(2) AFTER 10 MINUTE WARMUP

EXCITER SPECIFICATIONS



OPERATING TEMPERATURE RANGE

-20⁰ TO +40⁰C

CARRIER FREQUENCIES⁽¹⁾

$F_1 = F_x$, $F_2 = F_x + 1.5 \text{ MHz}$, $F_3 = F_x - 1.5 \text{ MHz}$

DRIVE OUTPUT (GATED)

0.3 WATT, MINIMUM

LOCAL OSCILLATOR OUTPUTS:

FREQUENCIES⁽²⁾

$F_i + 30.0 \text{ MHz}$; $i = 1, 2, 3$

POWER

2.0 WATTS, MINIMUM

TUNING TIME

25 us, MAXIMUM

STABILITIES:

CARRIER FREQUENCY F_x

$\pm 0.2\%$

TO AND LO NOISE SIDEBANDS, MAXIMUM

-55 DB PER KHz AT $F > 1 \text{ KHz}$

-75 DB PER KHz AT $F > 20 \text{ KHz}$

DRIVE POWER OUTPUT

MAXIMUM DEVIATION

$\pm 5 \text{ DB}$

MAXIMUM DRIFT

$\pm 2 \text{ DB IN } 5 \text{ MINUTES}$

LOCAL OSCILLATOR AM NOISE SIDEBAND

-113 DB PER 100 KHz AT 30 MHz

REFERENCE OSCILLATOR

OUTPUT POWER

100 mw, MINIMUM

FREQUENCY TUNING RANGE

29.7 TO 30.3 MHz

(1) F_x 10 GHz (NOMINAL) FOR THE BASELINE DESIGN: F_x WILL BE SELECTED IN THE RANGE 9.5-10.5 GHz, DEPENDING UPON FREQUENCY ALLOCATION AND TRANSMITTER TUBE AVAILABILITY. THE BASELINE DESIGN PROVIDES FREQUENCY AGILITY WITH THREE CARRIER FREQUENCIES STAGGERED 1.5 MHz.

(2) LOCAL OSCILLATOR FREQUENCIES ARE TUNED WITH A TIME DIFFERENTIAL RELATIVE TO TRANSMISSION OF 1.46 MS (170 KM ALTITUDE) TO 2.06 ms (230 KM ALTITUDE).

RECEIVER SPECIFICATIONS



OPERATING TEMPERATURE RANGE

-20° TO +40°C

NUMBER

185

NOISE FIGURE, MAXIMUM

10 DB

IF

30 MHz

BANDWIDTHS:

3 DB

1.0 MHz $\pm 10\%$

20 DB

2.3 MHz MAXIMUM

PRE-AMP GAIN:

20 ± 2 DB

GAIN BALANCE (1)

.6 DB RMS (1 σ)

PHASE BALANCE (1)

4° RMS (1 σ)

RECEIVER PROTECTION:

20 WATTS PEAK AT 10 μ s DURATION

MIXER PHASE:

CHANNEL-TO-CHANNEL SIGNAL RF-TO-IF OUTPUT PHASE MATCHED WITH MIXER RF INPUT/LO
INPUT PHASES UNIFORMLY DISTRIBUTED OVER 2π .

MIXER LO CARRIER SUPPRESSION 20 DB, MINIMUM

(1) GAIN AND PHASE OF RECEIVERS MUST TRACK WITHIN SPECIFIED TOLERANCE OVER THE MIDDLE
THIRD OF THE RECEIVER BANDWIDTH (330 KHz $\pm 10\%$).

CALIBRATOR SPECIFICATIONS



OPERATING TEMPERATURE RANGE:

-20° TO +40°C

INPUTS: T.O.: 10 mw PEAK, MINIMUM, GATED OR CW

P_C = TRANSMITTER: 10 mw PEAK, MINIMUM, GATED

OUTPUT, REFERENCED TO P_C INPUT:

LEVELS:

-15 DB TO -63 DB IN 3 DB STEPS

ACCURACIES:

RMS (1 σ) DEVIATION = $\pm .15$ DB MAXIMUM

INPUT COMMAND:

5 BIT DIGITAL

PRE-PROCESSOR SPECIFICATIONS

HUGHES

HUGHES AIRCRAFT COMPANY

1. DIGITAL GAIN CONTROL

NOMINAL GAIN OF POST AMPLIFIER: 50 DB \pm 3 DB MAXIMUM

DYNAMIC RANGE: 30 DB MAXIMUM

SENSOR INPUT DURATION: 25 μ s MINIMUM

SETTLING TIME: TBD

ACCURACY: .1 DB RMS (1 σ)

MUTUAL DE-COUPLING: NOTE A

2. SYNCHRONOUS DOWN-CONVERSION (I/Q DETECTION) & VIDEO FILTER

MIXER LO CARRIER SUPPRESSION: 20 DB, MINIMUM

VIDEO FILTER BANDWIDTH: 275 KHz \pm 10%

QUADRATURE PHASE BALANCE: 3 $^{\circ}$ RMS (1 σ)

QUADRATURE GAIN BALANCE: .5 DB (1 σ)

VIDEO OUTPUT CHANNEL-TO-CHANNEL BALANCE FOR VIDEO FREQUENCIES FROM DC TO 125 KHz:

PHASE: 4 $^{\circ}$ RMS (1 σ)

GAIN: .6 DB RMS (1 σ)

MUTUAL DE-COUPLING: NOTE A

3. SAMPLE-AND-HOLD (S/H) DETECTION

APERTURE TIME: 100 NS MAXIMUM

SAMPLE TIME ERROR AND JITTER: 30 NS RMS (1 σ)

MUTUAL DE-COUPLING: NOTE A

NOTE A: AT LEAST 50 DB MUTUAL ISOLATION BETWEEN RECEIVERS IN A COMMON MODULE AND 80 DB ISOLATION BETWEEN RECEIVERS IN SEPARATE MODULES; 10 RECEIVERS MAXIMUM PER MODULE.

PRE-PROCESSOR SPECIFICATIONS, CONTINUED



4. MULTIPLEXERS AND A/D CONVERTERS

FORM: TIME MULTIPLEX OF 370 VIDEO CHANNELS

IN TWO CASCADED STAGES TO MULTIPLE PARALLEL A/D CONVERTER CHANNELS;

VIDEO CHANNELS/MULTIPLEX STAGE: 20 MAXIMUM

A/D CONVERTERS: 4 MINIMUM

BITS/COMPLEX WORD: 6I, 6Q

SAMPLE RATE: 7×10^6 COMPLEX WORDS/SECOND

DECOUPLING: 40 DB MINIMUM BETWEEN WORDS

5. A/D CONVERTER OUTPUT:

BIT SELECTION - 6 BITS I AND Q SELECTED FOR

5 MOST SIGNIFICANT OR 5 LEAST SIGNIFICANT

BITS I AND Q OUTPUT, DEPENDING UPON LOGIC COMMAND UPDATED AT BURST
RATE (~ 220 Hz).

PRE-PROCESSOR SPECIFICATIONS, CONTINUED



6. BUFFER/FORMATTER:

INPUT DATA RATE: 28×10^6 MAXIMUM COMPLEX WORDS (5 BITS I, 5 BITS Q) PER SECOND

OUTPUT DATA RATE: 12.6×10^6 COMPLEX WORDS (5 BITS I, 5 BITS Q) PER SECOND

BUFFER DUTY FACTOR: .45 MAX WITH AVERAGING TIME OF 5 MS MAXIMUM

7. RECORDER:

RATE REQUIREMENTS: 150 MB/S, MAXIMUM

BIT ERROR RATE: 1 PART IN 10^5 (RANDOM)

RECORD TIME PER REEL: 30 MINUTES AT 120 MB/S

REEL SIZE, MAXIMUM: DIAMETER = 35 CM., WIDTH = 5 CM

REEL WEIGHT: 8.5 Kg, MAX

8. CLUTTER RANGE TRACKER:

500 M. MAXIMUM RMS ERROR TO THE MEAN RANGE OF MAIN LOBE CLUTTER.*

9. DIFFERENTIAL CLUTTER RANGE SENSOR:

TO PRODUCE PROPERLY SIGNED MONOTONIC ERROR SIGNALS FOR 100 M. MINIMUM DIFFERENCES IN MEAN CLUTTER RANGES AT AZIMUTH ANGLES OF $+20 \pm 2^\circ$, 0° , $-20 \pm 2^\circ$ RELATIVE TO ARRAY BROADSIDE.*

* MEAN CLUTTER RANGE IS DEFINED AS THE NEAR RANGE TO THE MAIN LOBE CLUTTER SIGNALS 6 DB BELOW MEAN PEAK CLUTTER MAGNITUDE. THE SPECIFICATIONS ARE APPLICABLE TO GENERAL TERRAIN WITH AVERAGE SURFACE REFLECTIVITIES $\sigma_0 = -15$ DB AND FOR AVERAGING TIMES OF 1 SECOND, MINIMUM.

SUPPLEMENTARY MATERIAL

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DISPLAY POSSIBILITIES

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- o CRT DISPLAY OF SELECTED CUTS THROUGH THE THREE-DIMENSIONAL DATA.
- o DYNAMIC CRT DISPLAY, SHOWING CUT PASSING THROUGH THE DATA.
- o DYNAMIC CRT DISPLAY, SHOWING DATA IN CONICAL FAN BEAM, DURING PROCESSING.
- o THREE-DIMENSIONAL STEREOSCOPIC DISPLAY, WITH PERSPECTIVE AND VIEWING ANGLE CONTROLLED BY OPERATOR.

CONDUCTION COOLED SUBASSEMBLY

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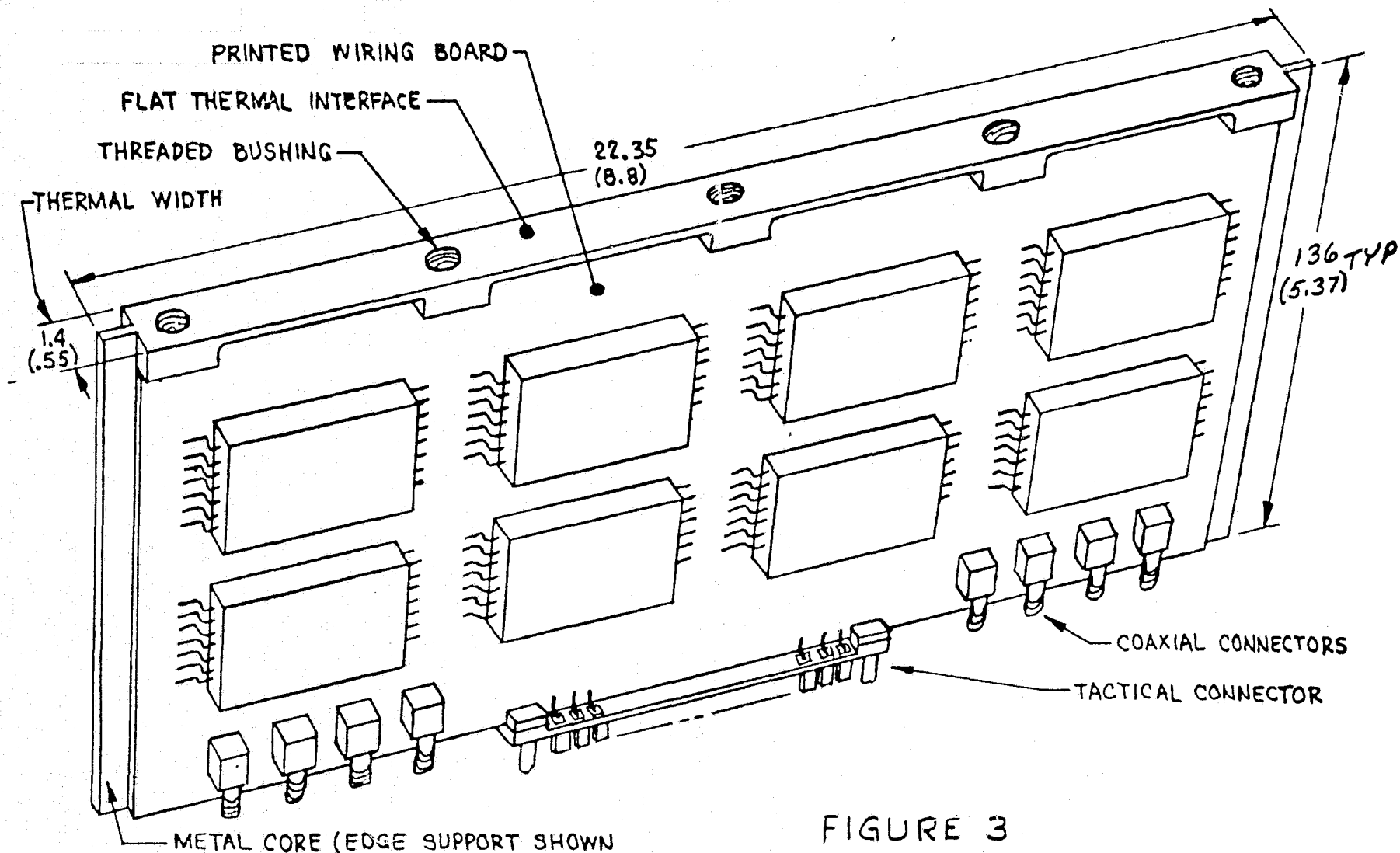


FIGURE 3

STANDARD ELECTRONIC SUBASSEMBLY ENVELOPE

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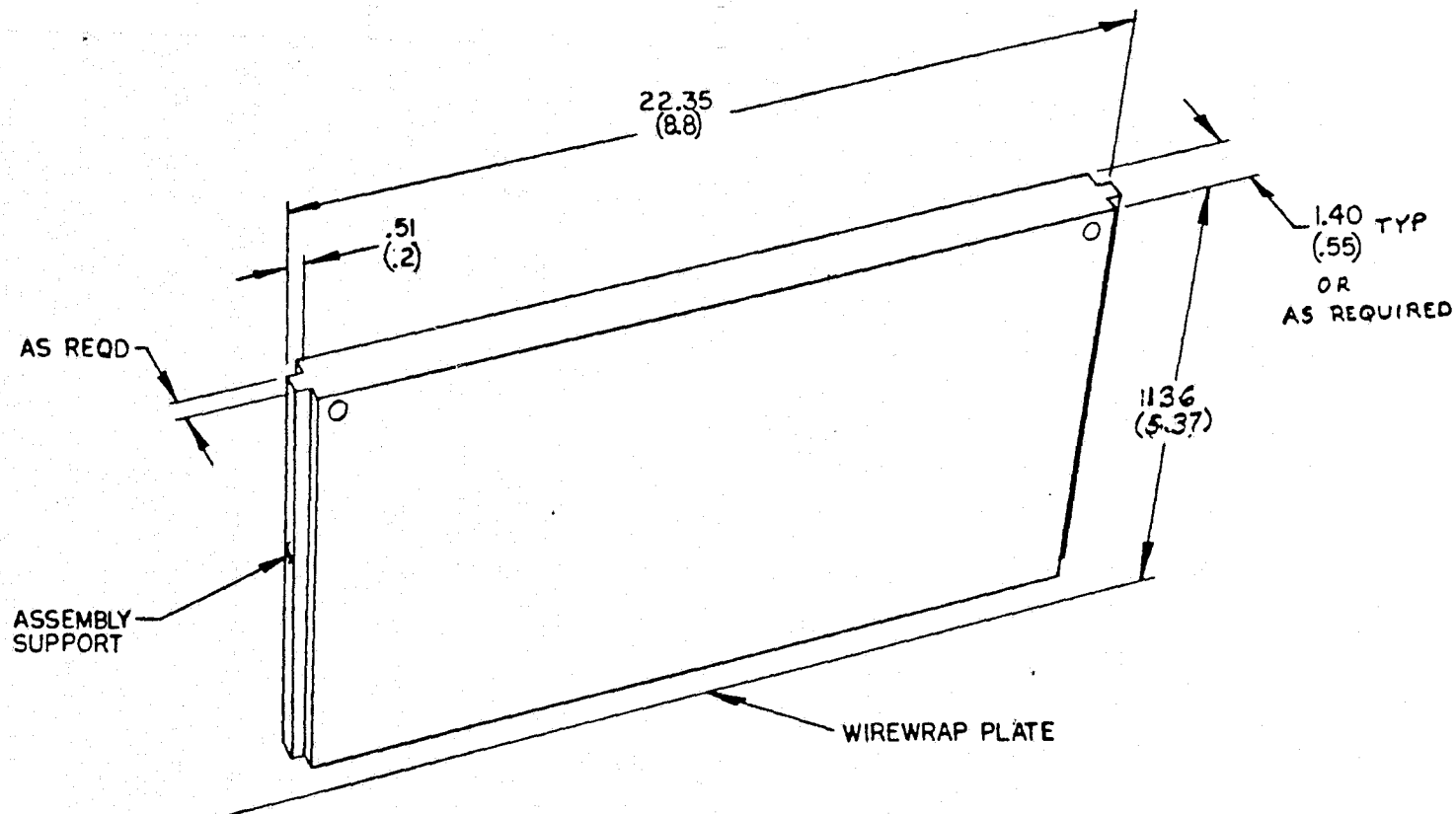


FIGURE 1.

STANDARD ELECTRONIC ENVELOPE
FOR 1.52 (.60) CENTERLINE PITCH.

FORCED AIR COOLED SUBASSEMBLY

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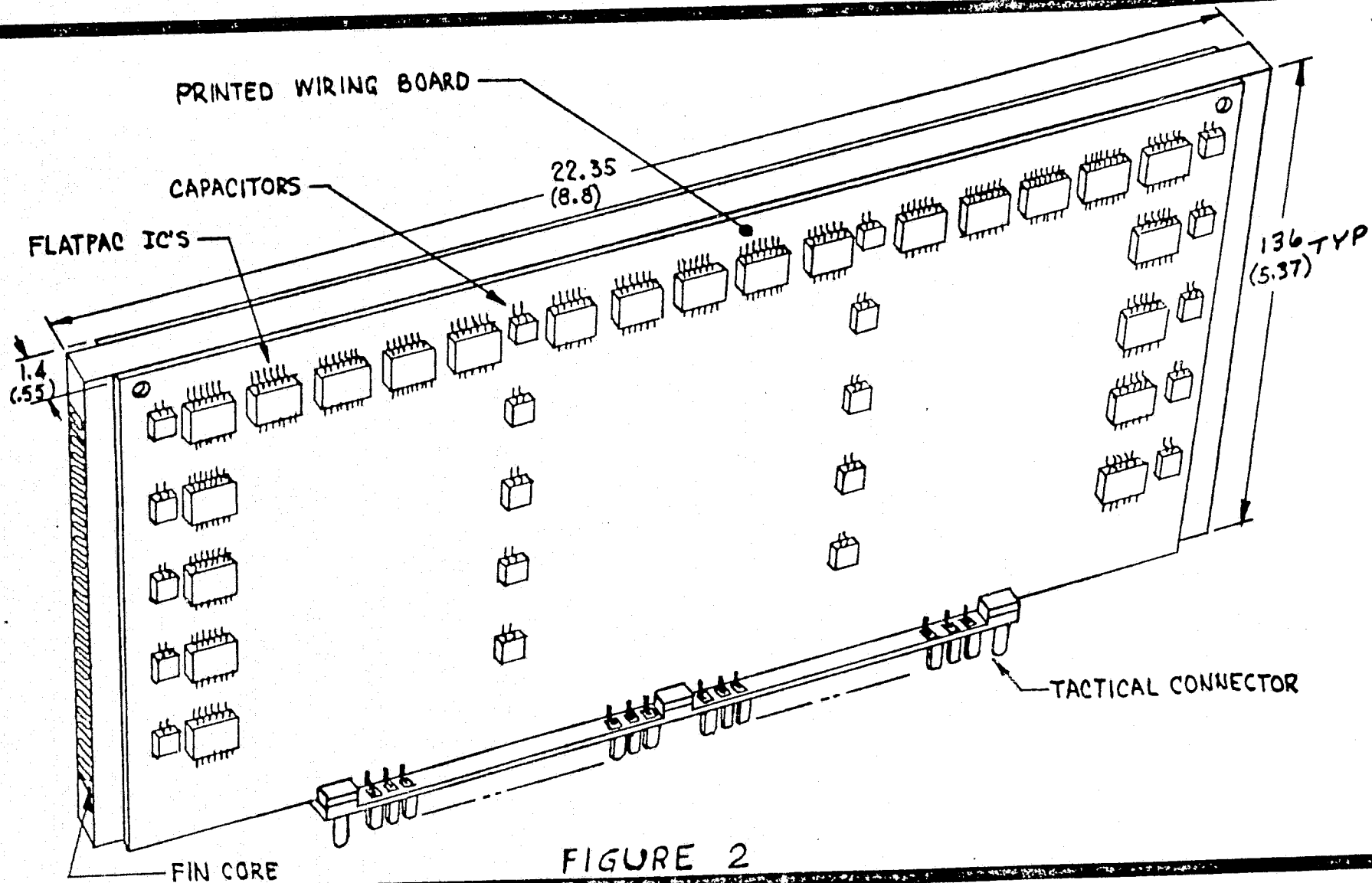


FIGURE 2

HEAT TRANSFER CHARACTERISTICS OF PARALLEL PLATES

TABLE 1

Equipment	Surface Size (IN)	Number of Screws (Peripheral)	Condition of Surface	Transfer Coefficient ($h = \frac{\text{Watts}}{\text{IN}^2 \text{ } ^\circ\text{C}}$)
Subassy	.55 x 8.2	5	DRY	.46
			RTV-11	4.6,
Preprocessor	10 x 27	38	DRY	.02
			RTV-11	.11
Transmitter HVPS	17 x 22	42	DRY	.02
			RTV-11	.09
LVPS	10 x 12	22	DRY	.035
			RTV-11	.20
Exciter	10 x 20	30	DRY	.03
			RTV-11	.15
Transfer Plate	33 x 34	64	DRY	.015
			RTV-11	.07

HEAT TRANSFER CHARACTERISTICS OF CLAMPED PLATES

TABLE 2

Equipment	Contact Dims. (IN)	Area (IN ²)	Q (watts)	Peripheral Clamping		6 in x 6 in Area Clamping	
				"h" with RTV11 $\left(\frac{W}{IN^2 \text{ } ^\circ C}\right)$	*Δ T (°C)	"h" with RTV11 $\left(\frac{W}{IN^2 \text{ } ^\circ C}\right)$	*Δ T °C
Standard Subassy.	.55 x 8.2	4.5	35	4.6	≈ 2	4.6	≈ 2
Preprocessor	10 x 27	270	700	.11	24	.33	≈ 8
Transmitter HVPS	17 x 22	374	950	.09	28	.33	≈ 7
LVPS	10 x 12	120	380	.2	16	.33	≈ 10
Exciter	10 x 20	200	200	.15	7	.33	≈ 3
Transfer Plate	33 x 34	1172	800	.07	10	.33	≈ 2

$$*\Delta T = \frac{Q}{Ah}$$